

Lecture#2

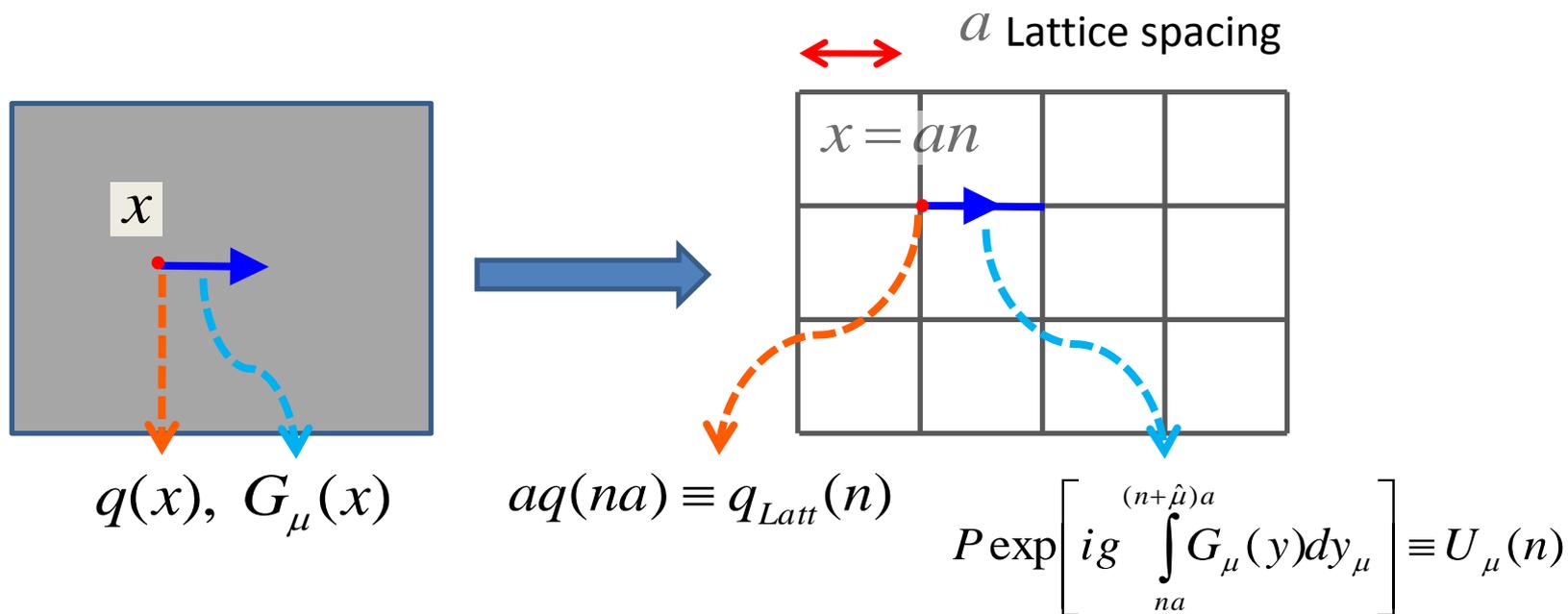
Hybrid Monte Carlo (HMC) algorithm

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1. HMC in Lattice QCD

1-1 LQCD

- Gluon and quark fields are defined on a lattice.
- Quarks are described with fermionic spinor fields with color d.o.f.
- Gluons are described with bosonic color matrix fields.

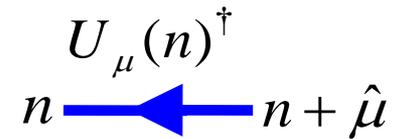


- Euclidean path-integral partition function

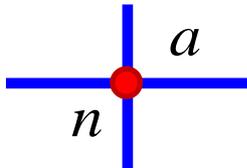
$$U_\mu(n) = \left(U_\mu(n)^{ab} \right)$$



Link field. SU(3) 3x3 unitary matrix.
Lattice vector field. Connects site n and $n + \hat{\mu}$.



$$q(n) = \left(q(n)_a \right)$$



Quark field. SU(3) fundamental rep.
lattice spinor field. Resides on site n .
This may have flavor index f by introducing several quarks. (u,d,c,s,t,b)

$$Z[V, \bar{\eta}, \eta] = \int \prod_n d\bar{q}(n) dq(n) \prod_{n,\mu} dU_\mu(n) \exp[-S_{LQCD}[U, \bar{q}, q] + V \cdot U + \bar{q} \cdot \eta + \bar{\eta} \cdot q]$$

Local Gauge transformation.

$$q'(n) = \Omega(n)q(n)$$

$$U'_\mu(n) = \Omega(n)U_\mu(n)\Omega(n + \hat{\mu})$$

Local gauge transformation
SU(3) group matrix.

$$\Omega(n)$$

Integration Measure and the action are defined to be gauge invariant.
SU(3) group invariant Haar measure for dU .

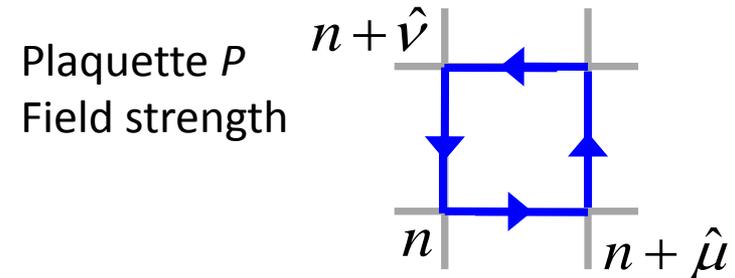
- Typical LQCD action. (K.G.Wilson 1974)

$$S_{LQCD}[U, \bar{q}, q] = S_G[U] + S_Q[U, \bar{q}, q]$$

$$S_G[U] = \beta \sum_n \sum_{\mu > \nu} \left(1 - \frac{1}{2N_c} \text{Tr} [P_{\mu\nu}(n) + P_{\mu\nu}(n)^\dagger] \right) \quad \text{Wilson Gauge action. (Gluon)}$$

$$P_{\mu\nu}(n) \equiv U_\mu(n) U_\nu(n + \hat{\mu}) U_\mu(n + \hat{\nu})^\dagger U_\nu^\dagger(n)$$

$$\beta = \frac{2N_c}{g^2} = \frac{6}{g^2} \quad \text{Inverse bare gauge coupling.}$$



$$S_Q[U, \bar{q}, q] = \sum_{f=u,d,s} \sum_{n,m} \bar{q}_f(n) D_f[U](n,m) q_f(m) \quad \text{Wilson Fermion action. (quarks)}$$

$$D_f[U](n,m) = \delta_{n,m} - \kappa_f \sum_{\mu=1}^4 \left[(1 - \gamma_\mu) U_\mu(n) \delta_{n+\hat{\mu},m} + (1 + \gamma_\mu) U_\mu(n - \hat{\mu})^\dagger \delta_{n-\hat{\mu},m} \right]$$

Wilson-Dirac operator D .
Contains gauge covariant
difference op.

$$\kappa_f = \frac{1}{2(am_f + 4)} \quad \text{Hopping parameter } \kappa$$

No chiral symmetry.

• Observables in LQCD

- Weighted averaging for Hadronic operators $O[U, \bar{q}, q]$

$$\langle O[U, \bar{q}, q] \rangle = \frac{1}{Z[0]} \int \prod_n d\bar{q}(n) dq(n) \prod_{n,\mu} dU_\mu(n) O[U, \bar{q}, q] \exp[-S_{LQCD}[U, \bar{q}, q]]$$

- This integral contains Grassmann variables q . This cannot be treated numerically on computers.
- Analytic integration on Grassmann variables q is possible when the action is bilinear of q . This is OK for LQCD.

$$S_Q[U, \bar{q}, q] = \bar{q} \cdot D[U] \cdot q$$

$$\langle O[U, D[U]^{-1}] \rangle = \frac{1}{Z[0]} \int \prod_{n,\mu} dU_\mu(n) O[U, D[U]^{-1}] \prod_{f=u,d,s} \det[D_f[U]] \exp[-S_G[U]]$$

- $q\bar{q}$ operators in the observables are all replaced to corresponding quark propagators $(D[U])^{-1}$ [= inverse of Dirac operators].

$$\langle O[U, D[U]^{-1}] \rangle = \frac{1}{Z[0]} \int \prod_{n,\mu} dU_\mu(n) O[U, D[U]^{-1}] \prod_{f=u,d,s} \det[D_f[U]] \exp[-S_G[U]]$$

- Thus the average is obtained by integration on $\{U_\mu(n)\}$ with the weight

$$W[U] = \text{Const} \prod_{f=u,d,s} \det[D_f[U]] \exp[-S_G[U]]$$

- This weight is constructed to be real and non-negative. With the Wilson gauge action the exp weight is real and non-negative.
- The determinant of the Lattice Dirac operator appears in the weight. The determinant is also real in the standard setup. However it causes difficulty with negative/complex values in some cases (finite density simulation).
- For Wilson Dirac fermions the determinant is not protected from negative value. However sufficiently large quark masses it is positive real.
- **What we have to do is MCMC simulation with the weight $W[U]$.**

1-2 MCMC for the continuous state/probability case.

- As seen before we need to generate ensemble for $\{U\}$ with the weight

$$W[U] = \text{Const} \prod_{f=u,d,s} \det[D_f[U]] \exp[-S_G[U]]$$

- More precisely the probability density

$$W[U] \prod_{n,\mu} dU_\mu(n) = \text{Const} \times \left(\prod_{f=u,d,s} \det[D_f[U]] \exp[-S_G[U]] \right) \prod_{n,\mu} dU_\mu(n)$$

- Hybrid Monte Carlo (HMC) algorithm is used for this purpose.

$$\{U^{(1)}, U^{(2)}, U^{(3)}, \dots, U^{(N)}\} \quad \langle O[U, D[U]^{-1}] \rangle \approx \frac{1}{N} \sum_{j=1}^N O[U^{(j)}, D[U^{(j)}]^{-1}]$$

- To explain the basics on the HMC algorithm, we simplify the notation by introducing corrective real scalar coordinates $\vec{\phi} \leftarrow \{U\}$.

$$\{\vec{\phi}^{(1)}, \vec{\phi}^{(2)}, \vec{\phi}^{(3)}, \dots, \vec{\phi}^{(N)}\} \quad \langle O(\vec{\phi}) \rangle = \frac{1}{Z(\vec{0})} \int d\vec{\phi} O(\vec{\phi}) \exp[-S(\vec{\phi})] \approx \frac{1}{N} \sum_{j=1}^N O(\vec{\phi}^{(j)})$$

- The basic idea of HMC comes from statistical mechanics.

$$Z(\vec{0}) = \int d\vec{\phi} \exp[-S(\vec{\phi})]$$

$$\langle O(\vec{\phi}) \rangle = \frac{1}{Z(\vec{0})} \int d\vec{\phi} O(\vec{\phi}) \exp[-S(\vec{\phi})]$$

- Constant expressed by Gaussian integral $C = \int d\vec{\pi} \exp\left[-\frac{\vec{\pi}^2}{2}\right]$

$\vec{\pi}$: real scalar coordinate having same d.o.f to $\vec{\phi}$

- Multiply this constant to the partition function

$$Z_{HMC} = Z(\vec{0})C = \int d\vec{\pi}d\vec{\phi} \exp\left[-\left(\frac{\vec{\pi}^2}{2} + S(\vec{\phi})\right)\right] = \int d\vec{\pi}d\vec{\phi} \exp[-H(\vec{\pi}, \vec{\phi})]$$

$$\langle O(\vec{\phi}) \rangle = \frac{1}{Z_{HMC}} \int d\vec{\pi}d\vec{\phi} O(\vec{\phi}) \exp[-H(\vec{\pi}, \vec{\phi})]$$

- This is identical to the Canonical ensemble estimator mathematically.

2. Hybrid Monte Carlo (HMC)

$$Z_{HMC}(\vec{\eta}) = \int d\vec{\pi} d\vec{\phi} \exp[-H(\vec{\pi}, \vec{\phi}) + \vec{\eta} \cdot \vec{\phi}] \quad H(\vec{\pi}, \vec{\phi}) = \frac{\vec{\pi}^2}{2} + S(\vec{\phi})$$

$$\langle O(\vec{\phi}) \rangle = \frac{1}{Z_{HMC}(\vec{0})} \int d\vec{\pi} d\vec{\phi} O(\vec{\phi}) \exp[-H(\vec{\pi}, \vec{\phi})]$$

- We can use Metropolis algorithm to generate ensemble for random variables $(\vec{\pi}, \vec{\phi})$.

$$\{(\vec{\pi}^{(1)}, \vec{\phi}^{(1)}), (\vec{\pi}^{(2)}, \vec{\phi}^{(2)}), (\vec{\pi}^{(3)}, \vec{\phi}^{(3)}), \dots, (\vec{\pi}^{(N)}, \vec{\phi}^{(N)})\} \quad w((\vec{\pi}, \vec{\phi})) \propto \exp[-H(\vec{\pi}, \vec{\phi})]$$

$$\rho((\vec{\pi}, \vec{\phi}), (\vec{\pi}', \vec{\phi}')) = \min\left(1, \exp[-H(\vec{\pi}, \vec{\phi}) + H(\vec{\pi}', \vec{\phi}')]\right)$$

$$q((\vec{\pi}, \vec{\phi}) | (\vec{\pi}', \vec{\phi}')) = ? \quad [\text{Candidate generation prob.}]$$

- For good Metropolis test acceptance rate, generating candidate state $(\vec{\pi}, \vec{\phi})$ requires small energy change

$$\Delta H \equiv H(\vec{\pi}, \vec{\phi}) - H(\vec{\pi}', \vec{\phi}') \approx 0$$

- We know that the canonical ensemble reproduces the identical prediction to the Micro canonical ensemble in the thermodynamic limit.
- The average with the Micro canonical ensemble can be expressed as

$$\langle O(\vec{\phi}) \rangle = \lim_{T \rightarrow \infty} \int_0^T d\tau O(\vec{\phi}^{(\tau)})$$

- Where τ is a fictitious time for micro canonical ensemble and $\vec{\pi}^{(\tau)}$ is treated as the canonical momentum to the $\vec{\phi}^{(\tau)}$.
- The dynamics of $(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)})$ is governed by the Hamiltonian

$$H(\vec{\pi}, \vec{\phi}) = \frac{\vec{\pi}^2}{2} + S(\vec{\phi})$$

- And equation of motion:

$$\frac{d}{d\tau} \vec{\phi}^{(\tau)} = \vec{\pi}^{(\tau)} = \frac{d}{d\vec{\pi}} H(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)})$$

$$\frac{d}{d\tau} \vec{\pi}^{(\tau)} = -\frac{d}{d\vec{\phi}} S(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)}) = -\frac{d}{d\vec{\phi}} H(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)})$$

- **We can use this property to generate candidate state $(\vec{\pi}, \vec{\phi})$ from $(\vec{\pi}', \vec{\phi}')$.**

- Initial condition : $(\vec{\pi}^{(0)}, \vec{\phi}^{(0)}) = (\vec{\pi}', \vec{\phi}')$
- Fictitious time evolution via Hamiltonian eq. of motion : $(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)}) \xleftarrow{\text{time evolve}} (\vec{\pi}^{(0)}, \vec{\phi}^{(0)})$
- Candidate for Metropolis test : $(\vec{\pi}, \vec{\phi}) = (\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)})$

- **HMC algorithm**

(step 0) Given initial state $\vec{\phi}$.

(step 1) Generate initial momentum $\vec{\pi}$ with the probability/Gaussian dist. $\exp\left(-\frac{\vec{\pi}^2}{2}\right)$

(step 2) Set initial state $(\vec{\pi}^{(0)}, \vec{\phi}^{(0)}) = (\vec{\pi}, \vec{\phi})$, where $\vec{\phi}$ is from latest ensemble.

(step 3) Generate candidate state $(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)})$ via integrating Hamilton eq. of m.

for a fixed time τ .
$$\dot{\vec{\phi}} = \vec{\pi}, \dot{\vec{\pi}} = -\vec{\nabla}S(\vec{\phi}), \Leftarrow H(\vec{\pi}, \vec{\phi}) = \frac{\vec{\pi}^2}{2} + S(\vec{\phi}).$$

(step 4) Do Metropolis test. If it is accepted $(\vec{\phi}^{(\tau)})$ is added to the ensemble.

If rejected $(\vec{\phi}^{(0)})$ is added to the ensemble.

(step 5) Goto step 1.

- In step 2, we can directly generate the fictitious momentum from Gaussian distribution as it should be.
- Step 3 requires the numerical integration on Hamilton eq. of m. This is called as the **Molecular dynamics (MD) integration/evolution**. This violates the energy conservation. Thus the Metropolis test is required.
- Step 3 corresponds to the candidate generation. The transition prob. for this candidate generation should be **symmetric** $q_{ij} = q_{ji}$ to satisfy the **detailed balance** (Lect#1). Thus the **MD integrator should be revertible** and at the end of time evolution the momentum should be reversed.
- In step 4, the momentum is not stored to the ensemble since it is not required for observables.

- The efficiency of the HMC algorithm depends on the numerical MD integrator performance.
 - Time reversible (and area preserving) integrator.
 - Smaller energy conservation violation with larger time step.
 - The most time consuming part of the MD integrator is the computation of force.

HMC = MD integrator + Metropolis algorithm

- We need better MD integration scheme.

3. MD integrators

- We need to integrate the following Hamiltonian equation of motion.

$$\frac{d}{d\tau} \vec{\phi}^{(\tau)} = \vec{\pi}^{(\tau)} = \frac{d}{d\vec{\pi}} H(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)})$$

$$\frac{d}{d\tau} \vec{\pi}^{(\tau)} = -\frac{d}{d\vec{\phi}} S(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)}) = -\frac{d}{d\vec{\phi}} H(\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)})$$

$$H(\vec{\pi}, \vec{\phi}) = \frac{\vec{\pi}^2}{2} + S(\vec{\phi})$$

- Simple Runge-Kutta method is not time reversible. This cannot be used for HMC.

$$\begin{aligned} (\vec{\pi}^{(0)}, \vec{\phi}^{(0)}) &\xrightarrow{\text{Runge-Kutta}} (\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)}) \\ (-\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)}) &\xrightarrow{\text{Runge-Kutta}} (\vec{\pi}^{(2\tau)}, \vec{\phi}^{(2\tau)}) \end{aligned} \quad (\vec{\pi}^{(0)}, \vec{\phi}^{(0)}) \neq (-\vec{\pi}^{(2\tau)}, \vec{\phi}^{(2\tau)})$$

$$q((-\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)}) | (\vec{\pi}^{(0)}, \vec{\phi}^{(0)})) \neq q((\vec{\pi}^{(0)}, \vec{\phi}^{(0)}) | (-\vec{\pi}^{(\tau)}, \vec{\phi}^{(\tau)}))$$

- Properties of Hamiltonian dynamics.

- Poisson brackets.

$$\{X, Y\} \equiv \frac{\partial X}{\partial \vec{\phi}} \cdot \frac{\partial Y}{\partial \vec{\pi}} - \frac{\partial X}{\partial \vec{\pi}} \cdot \frac{\partial Y}{\partial \vec{\phi}}, \quad X, Y : \text{functions of } (\vec{\pi}, \vec{\phi})$$

$$\{X, Y\} = -\{Y, X\}$$

$$\{X, aY + bZ\} = a\{X, Y\} + b\{X, Z\}$$

Defines Lie algebra

$$\{X, \{Y, Z\}\} + \{Z, \{X, Y\}\} + \{Y, \{Z, X\}\} = 0$$

- Define Liouville operator L : $iL_Y X \equiv \{X, Y\}$

- Hamiltonian eq. of m.

$$\begin{aligned} \frac{d\vec{\phi}}{d\tau} &= \{\vec{\phi}, H\} = + \frac{dH}{d\vec{\pi}} = \vec{\pi} \\ \frac{d\vec{\pi}}{d\tau} &= \{\vec{\pi}, H\} = - \frac{dH}{d\vec{\phi}} = - \frac{dS}{d\vec{\phi}} \end{aligned} \quad \longrightarrow \quad \begin{aligned} \frac{d\vec{\phi}}{d\tau} &= iL_H \vec{\phi} \\ \frac{d\vec{\pi}}{d\tau} &= iL_H \vec{\pi} \end{aligned} \quad \longrightarrow \quad \frac{d}{d\tau} \begin{pmatrix} \vec{\phi} \\ \vec{\pi} \end{pmatrix} = iL_H \begin{pmatrix} \vec{\phi} \\ \vec{\pi} \end{pmatrix}$$

- Properties of Hamiltonian dynamics.

- Formal solution of Hamilton equation.

$$\frac{d}{d\tau} \begin{pmatrix} \vec{\phi} \\ \vec{\pi} \end{pmatrix} = iL_H \begin{pmatrix} \vec{\phi} \\ \vec{\pi} \end{pmatrix} \quad \longrightarrow \quad \begin{pmatrix} \vec{\phi} \\ \vec{\pi} \end{pmatrix}(\tau) = \exp[\tau \times iL_H] \begin{pmatrix} \vec{\phi} \\ \vec{\pi} \end{pmatrix}(0)$$

- Where $\exp(\tau \times iL_Y)X \equiv X + \tau \times iL_Y X + \frac{\tau^2}{2!} (iL_Y)^2 X + \frac{\tau^3}{3!} (iL_Y)^3 X + \dots$

$$= X + \tau \{X, Y\} + \frac{\tau^2}{2!} \{ \{X, Y\}, Y \} + \frac{\tau^3}{3!} \{ \{ \{X, Y\}, Y \}, Y \} + \dots$$

Similar formula for commutation bracket in Quantum mechanics. Algebra is same.

- Finding a time reversible and area conserving MD integration integrator == finding simple approximation for time evolution operator $\exp[\tau \times iL_H]$.

- Approximation for the time evolution op.

- Our Hamiltonian is composed of Kinetic term T and potential term S.

$$H(\vec{\pi}, \vec{\phi}) = \frac{\vec{\pi}^2}{2} + S(\vec{\phi}) = T(\vec{\pi}) + V(\vec{\phi})$$

- The Hamiltonian Liouville operator can be decomposed to two parts.

$$iL_H X = \{X, H\} = \{X, T + V\} = \{X, T\} + \{X, V\} \quad [iL_T, iL_V]X \neq 0$$

$$= iL_T X + iL_V X$$

Note: L_V and L_T are not commutable.

- Time evolution operator

$$\exp[\tau \times iL_H] = \exp[\tau \times (iL_T + iL_V)]$$

- We can approximate this operator as

$$\exp[\tau \times iL_H] = \exp[\tau \times (iL_T + iL_V)]$$

$$\approx \left[\exp\left[\frac{\tau}{2N_{MD}} \times iL_T\right] \exp\left[\frac{\tau}{N_{MD}} \times iL_V\right] \exp\left[\frac{\tau}{2N_{MD}} \times iL_T\right] \right]^{N_{MD}}$$

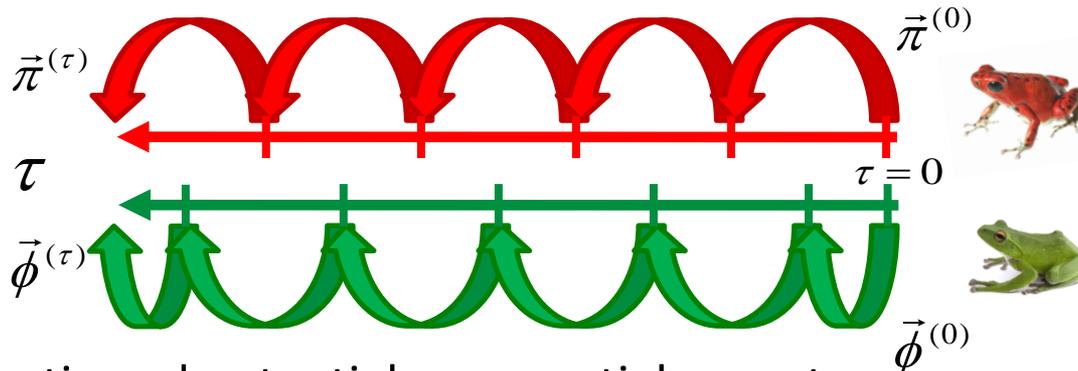
$e^{(A+B)\delta} \approx e^{A\delta/2} e^{B\delta} e^{A\delta/2}$ A symmetric decomposition of Matrix Exponential.

Leapfrog Scheme

• Properties of the Leapfrog Scheme

- Leapfrog time evolution operator U_{LF} :

$$\exp[\tau \times iL_H] \approx U_{LF}(\tau) \equiv \left[Q\left(\frac{\Delta\tau}{2}\right) P(\Delta\tau) Q\left(\frac{\Delta\tau}{2}\right) \right]^{N_{MD}}$$



- The Kinetic and potential exponential operators are exactly computable and invertible.

$$\exp[\Delta\tau \times iL_T] \begin{pmatrix} \vec{\phi}^{(0)} \\ \vec{\pi}^{(t)} \end{pmatrix} \equiv Q(\Delta\tau) \begin{pmatrix} \vec{\phi}^{(0)} \\ \vec{\pi}^{(t)} \end{pmatrix} = \exp \left[\Delta\tau \times \vec{\pi}^{(t)} \cdot \frac{\partial}{\partial \vec{\phi}} \right] \begin{pmatrix} \vec{\phi}^{(0)} \\ \vec{\pi}^{(t)} \end{pmatrix} = \begin{pmatrix} \vec{\phi}^{(0)} + \Delta\tau \times \vec{\pi}^{(t)} \\ \vec{\pi}^{(t)} \end{pmatrix}$$

$$\exp[\Delta\tau \times iL_V] \begin{pmatrix} \vec{\phi}^{(t)} \\ \vec{\pi}^{(0)} \end{pmatrix} \equiv P(\Delta\tau) \begin{pmatrix} \vec{\phi}^{(t)} \\ \vec{\pi}^{(0)} \end{pmatrix} = \exp \left[\Delta\tau \times \vec{F}(\vec{\phi}^{(t)}) \cdot \frac{\partial}{\partial \vec{\pi}} \right] \begin{pmatrix} \vec{\phi}^{(t)} \\ \vec{\pi}^{(0)} \end{pmatrix} = \begin{pmatrix} \vec{\phi}^{(t)} \\ \vec{\pi}^{(0)} + \Delta\tau \times \vec{F}(\vec{\phi}^{(t)}) \end{pmatrix}$$

$$Q(\tau)Q(-\tau) = 1 \rightarrow Q(-\tau) = Q(\tau)^{-1}, \quad P(\tau)P(-\tau) = 1 \rightarrow P(-\tau) = P(\tau)^{-1}$$

• Properties of the Leapfrog Scheme

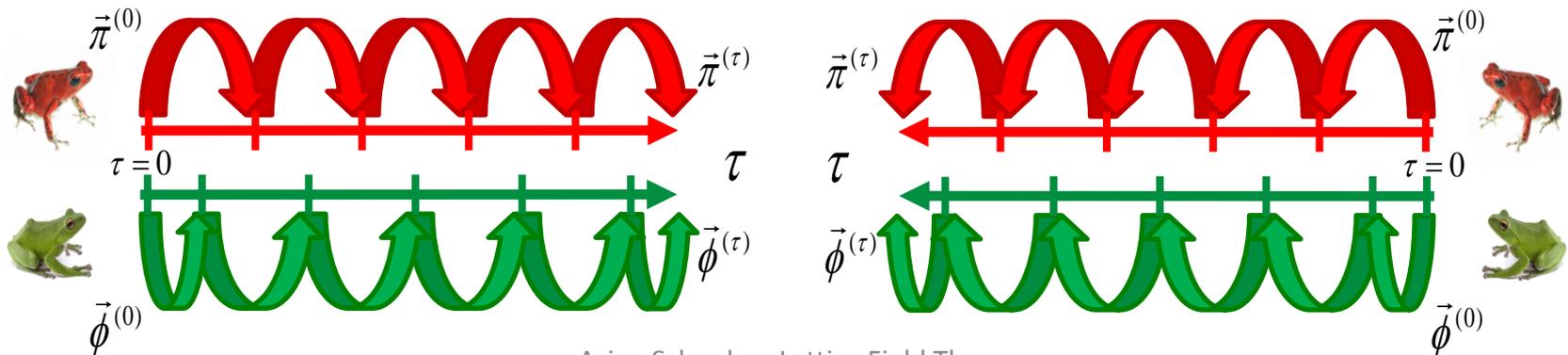
- Thus the Leapfrog operator U_{LF} is invertible.

$$U_{LF}(\tau) \equiv \left[Q\left(\frac{\Delta\tau}{2}\right) P(\Delta\tau) Q\left(\frac{\Delta\tau}{2}\right) \right]^{N_{MD}}$$

$$Q(\tau)Q(-\tau) = 1 \rightarrow Q(-\tau) = Q(\tau)^{-1}, \quad P(\tau)P(-\tau) = 1 \rightarrow P(-\tau) = P(\tau)^{-1}$$

$$\begin{aligned} U_{LF}(\tau)U_{LF}(-\tau) &= \left[Q\left(\frac{\Delta\tau}{2}\right) P(\Delta\tau) Q\left(\frac{\Delta\tau}{2}\right) \right]^{N_{MD}} \left[Q\left(-\frac{\Delta\tau}{2}\right) P(-\Delta\tau) Q\left(-\frac{\Delta\tau}{2}\right) \right]^{N_{MD}} \\ &= \left[Q\left(\frac{\Delta\tau}{2}\right) P(\Delta\tau) Q\left(\frac{\Delta\tau}{2}\right) \right]^{N_{MD}} \left[Q\left(\frac{\Delta\tau}{2}\right)^{-1} P(\Delta\tau)^{-1} Q\left(\frac{\Delta\tau}{2}\right)^{-1} \right]^{N_{MD}} \\ &= 1 \end{aligned}$$

Half time step evolution at first and last on ϕ is important to ensure the reversibility.



• Properties of the Leapfrog Scheme

- The leapfrog time evolution operator is one of the approximation for true time evolution op.
- This operator violates energy conservation law.
- We can analyze the accuracy of the approximation using the Baker-Campbell-Hausdorff formula for matrix exponential.

$$e^A e^B \approx e^{A+B + \frac{1}{2}[A,B] + \frac{1}{12}([A,[A,B]] + [B,[B,A]])} \dots \quad \text{: B.C.H. formula}$$

$$\exp[\tau \times iL_H] \approx U_{\text{LF}}(\tau) = \left[e^{\frac{\Delta\tau}{2} \times iL_T} e^{\Delta\tau \times iL_V} e^{\frac{\Delta\tau}{2} \times iL_T} \right]^{N_{MD}} = \exp[\tau \times iL_{H(\text{Shadow})}]$$

- Here we defined a **Shadow Hamiltonian** $H^{(\text{Shadow})}$. The discrepancy from the true Hamiltonian is

$$H^{(\text{Shadow})} = H - \frac{1}{24} (\{T, \{T, V\}\} + 2\{V, \{T, V\}\}) \Delta\tau^2 + O(\Delta\tau^4)$$

Problem 1

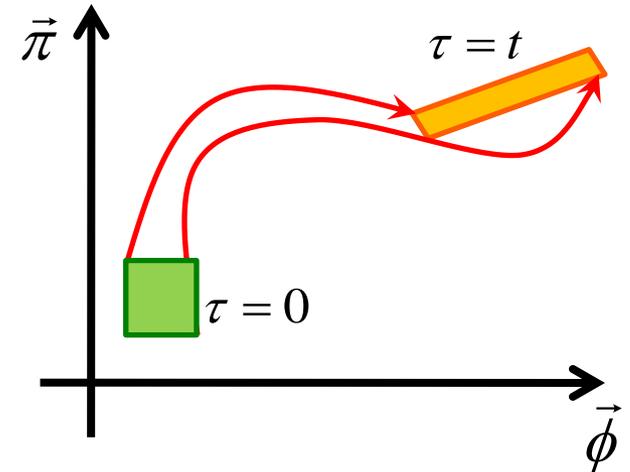
- We expect $O(\Delta\tau^2)$ violation on the energy conservation law. This affects the Metropolis test acceptance rate directly.

• Area preservation of the Leapfrog Scheme

- The candidate generation should preserve integration measure in the continuous case to preserve the transition probability. This means

Known as Liouville's theorem in analytical mechanics

$$d\vec{\pi}d\vec{\phi}\Big|_{\tau=0} = d\vec{\pi}d\vec{\phi}\Big|_{\tau=t}$$



- The area preservation holds for the leapfrog scheme. To prove this property, it is sufficient to consider the time evolution for a single time step.

$$\begin{pmatrix} \vec{\phi}^{(\Delta\tau)} \\ \vec{\pi}^{(\Delta\tau)} \end{pmatrix} = e^{\frac{\Delta\tau}{2} \times iL_T} e^{\Delta\tau \times iL_V} e^{\frac{\Delta\tau}{2} \times iL_T} \begin{pmatrix} \vec{\phi}^{(0)} \\ \vec{\pi}^{(0)} \end{pmatrix}$$

- The Jacobian of this transformation is proved to be 1.

Problem 2

• Time reversal and momentum flip in the MD integrators

- The MD integrators should be constructed to be time reversible and area preserving.
- We can integrate back on the same trajectory by flipping the Momentum.
- This means

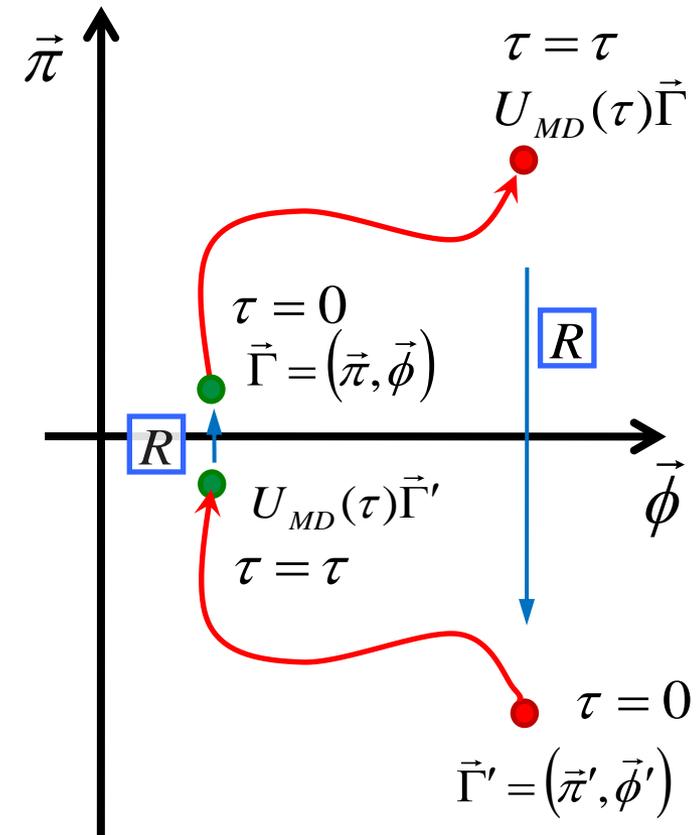
$$\vec{\Gamma} = (\vec{\pi}, \vec{\phi}) \quad \vec{\Gamma}' = (\vec{\pi}', \vec{\phi}')$$

$$\vec{\Gamma}' = RU_{MD}(\tau)\vec{\Gamma} \quad \Leftrightarrow \quad RU_{MD}(\tau)\vec{\Gamma}' = \vec{\Gamma}$$

$$R: \text{momentum flip op.} \quad R(\vec{\pi}, \vec{\phi}) = (-\vec{\pi}, \vec{\phi})$$

- In the phase space.

Note: The operation of R is usually irrelevant for H value.
The R operations are often omitted in the HMC algorithm.



4. Properties of the HMC algorithm

- Acceptance rate

- The leapfrog scheme has a $O(\Delta\tau^2)$ error.

- Rejection occurs in the Metropolis test. How large/small is it?

$$\vec{\Gamma} = (\vec{\pi}, \vec{\phi})$$

- Consider the partition function: $Z_{HMC}(\vec{0}) = \int d\vec{\Gamma} \exp[-H(\vec{\Gamma})]$

- A MD integrator+momentum flip moves/maps $\vec{\Gamma} = (\vec{\pi}, \vec{\phi})$ to $\vec{\Gamma}' = (\vec{\pi}', \vec{\phi}')$ as

$$\vec{\Gamma}' = RU_{MD}(\tau)\vec{\Gamma}$$

- Considering this MD evolution as a variable change for the partition function, we have

$$\langle e^{-\Delta H} \rangle = 1$$

Expectation value of the exponential of the Energy conservation violation should be 1 for area preserving MD integrator.

$$\begin{aligned} \int d\vec{\Gamma} \exp[-H(\vec{\Gamma})] &= \int d\vec{\Gamma}' \exp[-H(\vec{\Gamma}')] = \int d(RU_{MD}\vec{\Gamma}) \exp[-H(RU_{MD}\vec{\Gamma})] \\ &= \int d\vec{\Gamma} \exp[-H(RU_{MD}\vec{\Gamma})] = \int d\vec{\Gamma} \exp[-H(RU_{MD}\vec{\Gamma}) + H(\vec{\Gamma})] \exp[-H(\vec{\Gamma})] \\ &= \int d\vec{\Gamma} \exp[-\Delta H] \exp[-H(\vec{\Gamma})] \end{aligned}$$

- Acceptance rate of the HMC Metropolis test

- From $\langle e^{-\Delta H} \rangle = 1$, we can estimate the acceptance rate by assuming a Gaussian distribution for $\Delta H = x$ (as a random variable).

$$1 = \langle e^{-x} \rangle = \int_{-\infty}^{\infty} e^{-x} \frac{e^{-\frac{(x-\mu)^2}{2\sigma^2}}}{\sqrt{2\pi\sigma^2}} dx = e^{-\mu + \frac{\sigma^2}{2}} \Rightarrow \mu = \frac{\sigma^2}{2}$$

- From the problem #5) of Lecture 1 we can estimate the averaged acceptance rate as

$$\langle P_{acc} \rangle = \int_{-\infty}^{\infty} \min(1, e^{-\Delta H}) \frac{1}{\sqrt{4\pi\mu}} e^{-\frac{(\Delta H - \mu)^2}{4\mu}} d\Delta H = \text{erfc}\left(\frac{\sqrt{\Delta H}}{2}\right)$$

- For the Leapfrog MD integrator we have $\Delta H \propto \Delta\tau^2$ and

$$\langle \Delta H \rangle = \frac{\text{Var}(\Delta H)}{2} = \frac{1}{2} (\langle \Delta H^2 \rangle - \langle \Delta H \rangle^2) \propto \Delta\tau^4$$

- Thus

$$\langle P_{acc} \rangle = \text{erfc}\left(\frac{\text{Const} \times (\Delta\tau)^2}{2}\right)$$

- HMC transition probability for $\vec{\phi} \leftarrow \vec{\phi}'$

$$P_{\text{HMC}}(\vec{\phi} | \vec{\phi}') = u(\vec{\phi} | \vec{\phi}') + (1 - r(\vec{\phi}'))\delta(\vec{\phi} | \vec{\phi}')$$

$$u(\vec{\phi} | \vec{\phi}') = \int d\vec{\pi} \left(\int \left[\rho((\vec{\pi}, \vec{\phi}) | (\vec{\pi}', \vec{\phi}')) q((\vec{\pi}, \vec{\phi}) | (\vec{\pi}', \vec{\phi}')) e^{-\frac{\vec{\pi}'}{2}} \right] d\vec{\pi}' \right)$$

$$r(\vec{\phi}') = \int d\vec{\phi} u(\vec{\phi} | \vec{\phi}')$$

π' is generated with Gaussian.
 π and π' are integrated out
since they are not measured.

$$\rho((\vec{\pi}, \vec{\phi}), (\vec{\pi}', \vec{\phi}')) = \min\left(1, e^{-H(\vec{\pi}, \vec{\phi}) + H(\vec{\pi}', \vec{\phi}')} \right)$$

$$q((\vec{\pi}, \vec{\phi}) | (\vec{\pi}', \vec{\phi}')) = \delta((\vec{\pi}, \vec{\phi}) - RU_{MD}^{(\tau)}(\vec{\pi}', \vec{\phi}'))$$

Metropolis test probability

Candidate generation probability

This is deterministic via MD
integration.

$$P_{\text{HMC}}(\vec{\phi}' | \vec{\phi}) e^{-S(\vec{\phi})} = P_{\text{HMC}}(\vec{\phi} | \vec{\phi}') e^{-S(\vec{\phi}')}$$

Satisfies the detailed balance condition

Problem 3

5. Examples

(1) Gaussian distribution with HMC

$$Z(\eta) = \int d\phi \exp[-S(\phi) + \eta\phi], \quad S(\phi) = \omega^2 \frac{\phi^2}{2}$$

$$\langle O(\phi) \rangle = \frac{1}{Z(0)} \int d\phi O(\phi) \exp[-S(\phi)]$$

– transformation to the HMC weight.

$$Z_{\text{HMC}}(\eta) = \int d\pi d\phi \exp[-H(\pi, \phi) + \eta\phi]$$

$$H(\pi, \phi) = \frac{\pi^2}{2} + S(\phi) = \frac{\pi^2}{2} + \omega^2 \frac{\phi^2}{2}$$

$$\langle O(\phi) \rangle = \frac{1}{Z_{\text{HMC}}(0)} \int d\pi d\phi O(\phi) \exp[-H(\pi, \phi)]$$

– MD system becomes a Harmonic oscillator $H(\pi, \phi) = \frac{\pi^2}{2} + \omega^2 \frac{\phi^2}{2}$

(1) Gaussian distribution with HMC

– MD system becomes a Harmonic oscillator

$$H(\pi, \phi) = \frac{\pi^2}{2} + \omega^2 \frac{\phi^2}{2}$$

– Equation of Motion

$$\dot{\pi} = -\omega^2 \phi, \quad \dot{\phi} = \pi$$

– Leapfrog integrator

$$\exp[\Delta\tau \times iL_T] \begin{pmatrix} \pi \\ \phi \end{pmatrix} = \exp\left[\Delta\tau \times \pi \frac{\partial}{\partial \phi}\right] \begin{pmatrix} \pi \\ \phi \end{pmatrix} = \begin{pmatrix} \pi \\ \phi + \Delta\tau \times \pi \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ \Delta\tau & 1 \end{pmatrix} \begin{pmatrix} \pi \\ \phi \end{pmatrix}$$

$$\exp[\Delta\tau \times iL_V] \begin{pmatrix} \pi \\ \phi \end{pmatrix} = \exp\left[-\Delta\tau \times \frac{\partial S}{\partial \phi} \frac{\partial}{\partial \pi}\right] \begin{pmatrix} \pi \\ \phi \end{pmatrix} = \begin{pmatrix} \pi - \Delta\tau \times \omega^2 \phi \\ \phi \end{pmatrix} = \begin{pmatrix} 1 & -\omega^2 \Delta\tau \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \pi \\ \phi \end{pmatrix}$$

$$\begin{pmatrix} \pi' \\ \phi' \end{pmatrix} = U_{LF}(\tau, N_{MD}) \begin{pmatrix} \pi \\ \phi \end{pmatrix} = \left[\begin{pmatrix} 1 & 0 \\ \Delta\tau & 1 \end{pmatrix} \begin{pmatrix} 1 & -\omega^2 \Delta\tau \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \Delta\tau & 1 \end{pmatrix} \right]^{N_{MD}} \begin{pmatrix} \pi \\ \phi \end{pmatrix}$$

The Jacobian of this LF transformation is 1.

$$\Delta\tau \equiv \tau / N_{MD}$$

When $|\Delta\tau| > 2/\omega$, the MD evolution becomes unstable.

Problem 4

(1) Gaussian distribution with HMC

– Algorithm

(Step 0) Generate initial state ϕ

(Step 1) Generate initial momentum π from Gaussian dist.

(Step 2) MD evolution to get (π', ϕ') from (π, ϕ)

(Step 3) (flip momentum $\pi' = -\pi'$)

(Step 4) Do Metropolis test with prob. $P = \min(1, e^{-H'+H})$

If accepted ($\phi = \phi'$) and add (ϕ) to the ensemble.

If rejected add (ϕ) to the ensemble.

(Step 5) Goto Step 1

- For a Harmonic oscillator HMC algorithm is rather trivial. The Gaussian distribution of π is transmitted to ϕ distribution.

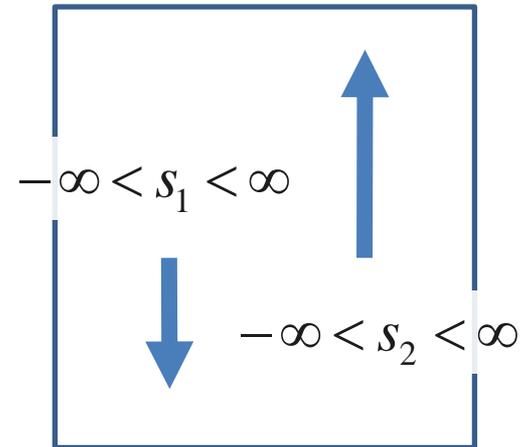
5. examples

(2) 2-site scalar model

– Partition function

$$\beta < 1$$

$$Z(\vec{\eta}) = \int_{-\infty}^{\infty} d\vec{s} \exp \left[- \left(\beta s_1 s_2 + \frac{s_1^2 + s_2^2}{2} \right) + \vec{\eta} \cdot \vec{s} \right]$$



– Observables

$$\left\langle \frac{s_1 + s_2}{2} \right\rangle = \frac{1}{Z(\vec{0})} \int_{-\infty}^{\infty} d\vec{s} \frac{s_1 + s_2}{2} \exp \left[- \left(\beta s_1 s_2 + \frac{s_1^2 + s_2^2}{2} \right) \right] = 0$$

$$\langle s_1 s_2 \rangle = \frac{1}{Z(\vec{0})} \int_{-\infty}^{\infty} d\vec{s} (s_1 s_2) \exp \left[- \left(\beta s_1 s_2 + \frac{s_1^2 + s_2^2}{2} \right) \right] = - \frac{\beta}{1 - \beta^2}$$

(2) 2-site scalar model

– In HMC, this corresponds to the coupled two Harmonic oscillators.

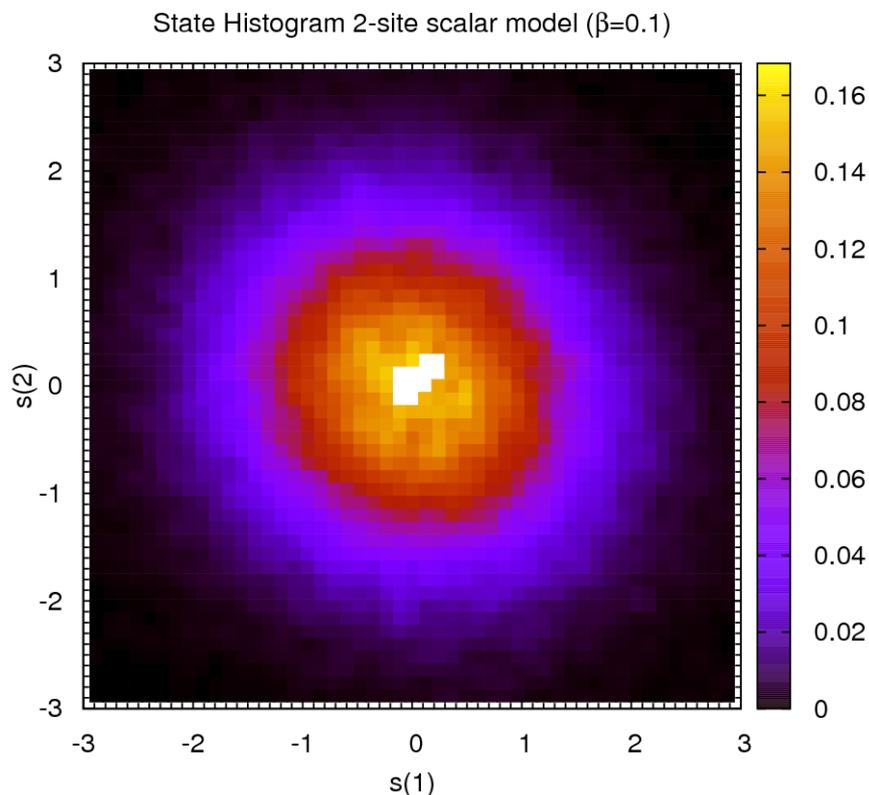
– Fortran Program

[\[http://theo.phys.sci.hiroshima-u.ac.jp/~ishikawa/ASLFT2010/2SiteScalarHMC.tar.gz\]](http://theo.phys.sci.hiroshima-u.ac.jp/~ishikawa/ASLFT2010/2SiteScalarHMC.tar.gz)

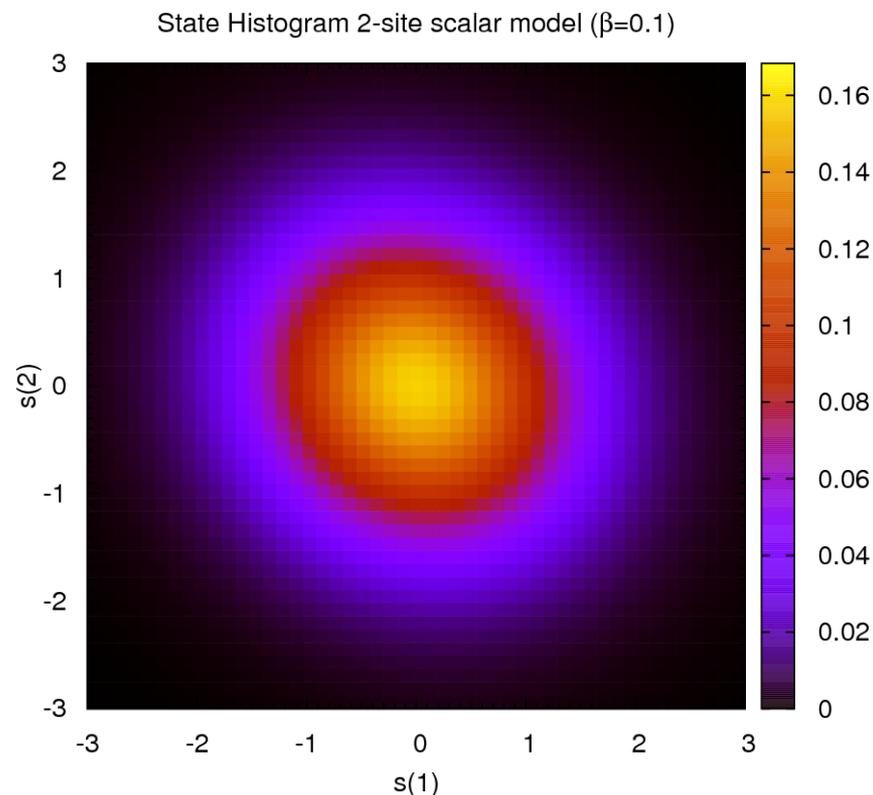
– 10,000,000 samples are generated. But we save 10,000 samples with interval 100. We use $\tau=2$, $N_{MD}=4$ for candidate generation.

- State weight/histogram generated via Metropolis algorithm

HMC measured

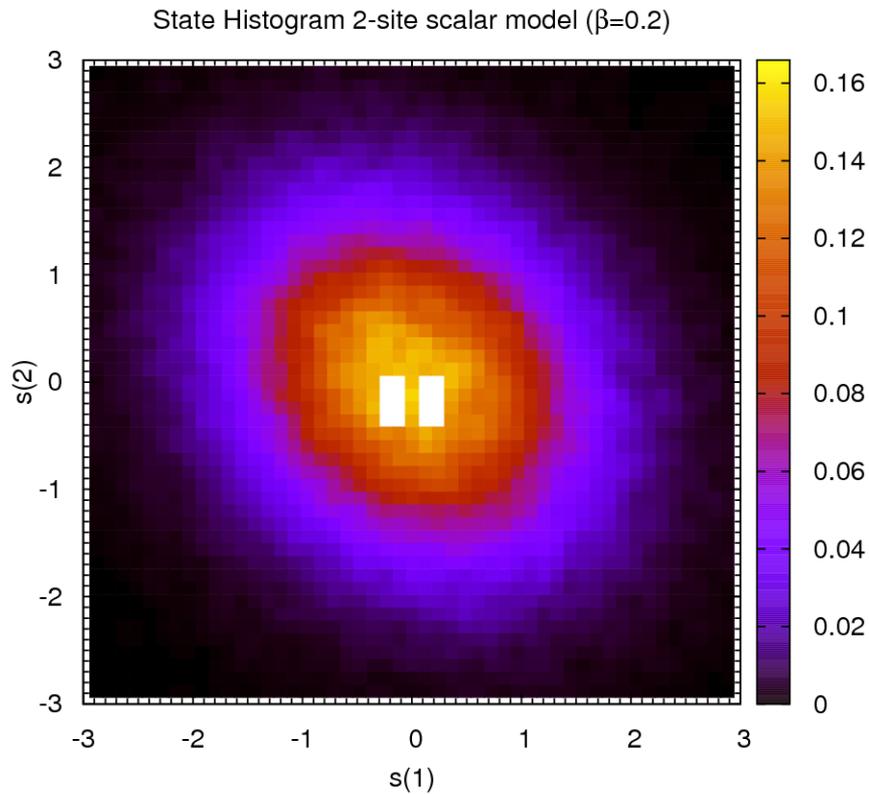


Theoretical

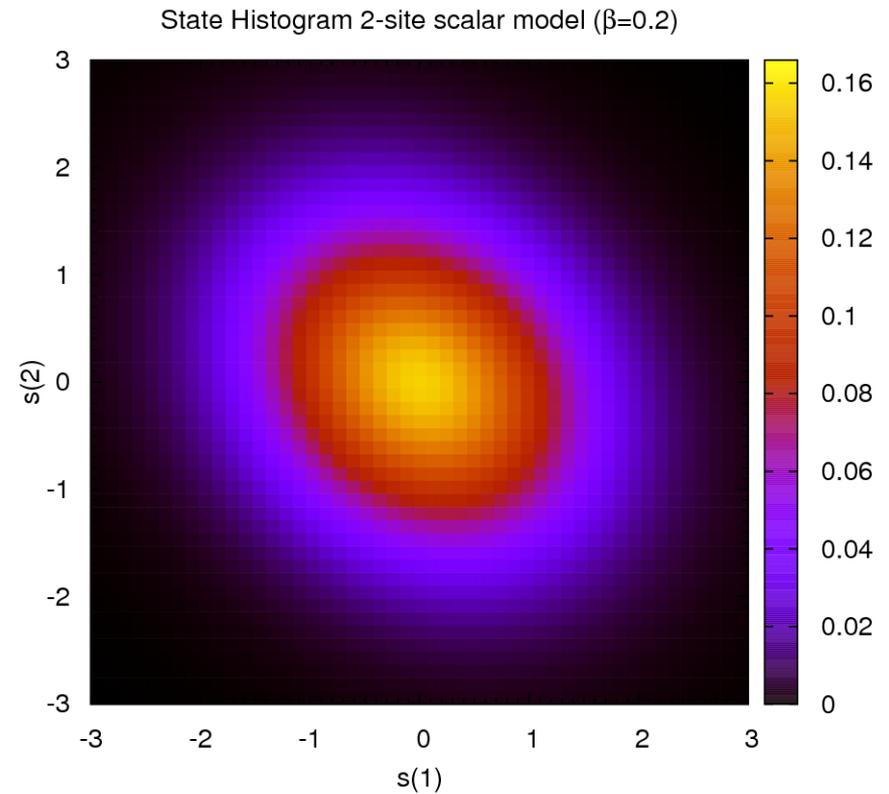


- State weight/histogram generated via Metropolis algorithm

HMC measured

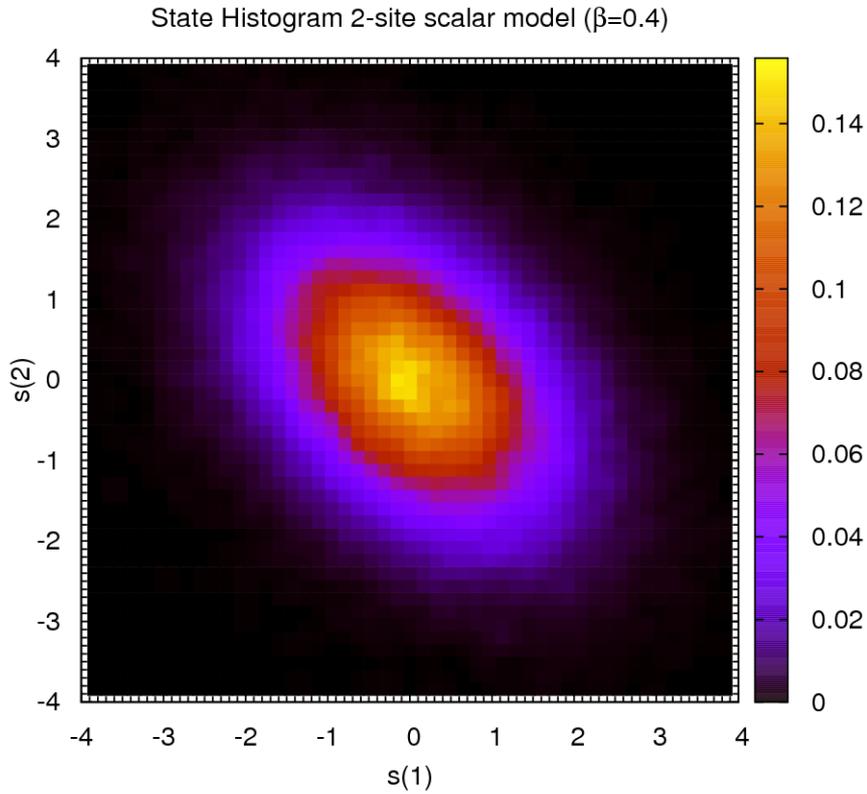


Theoretical

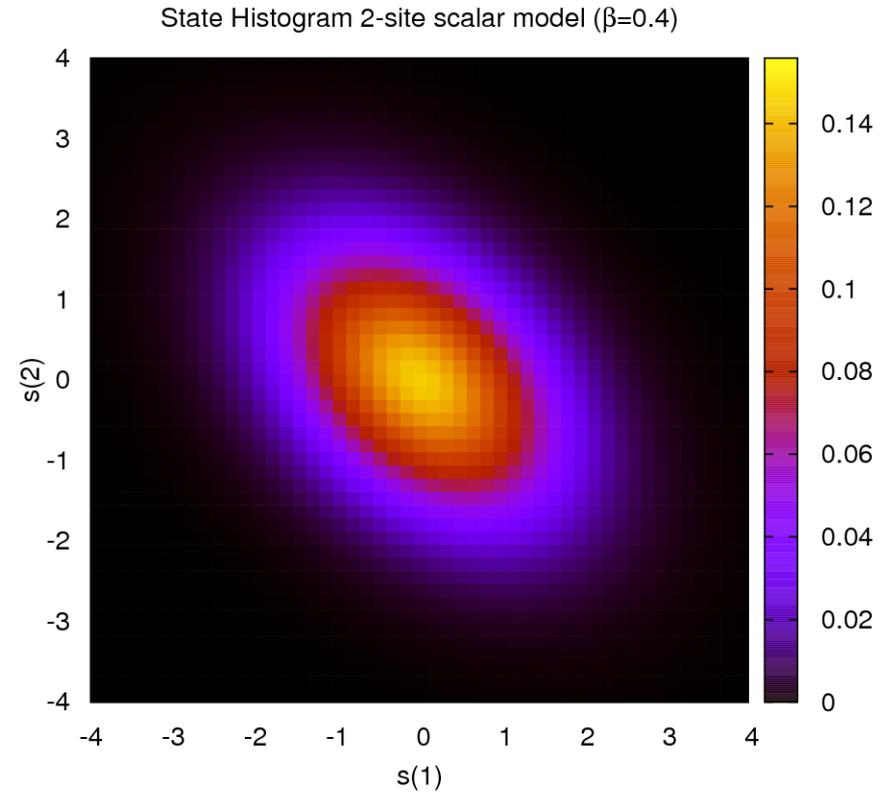


- State weight/histogram generated via Metropolis algorithm

HMC measured



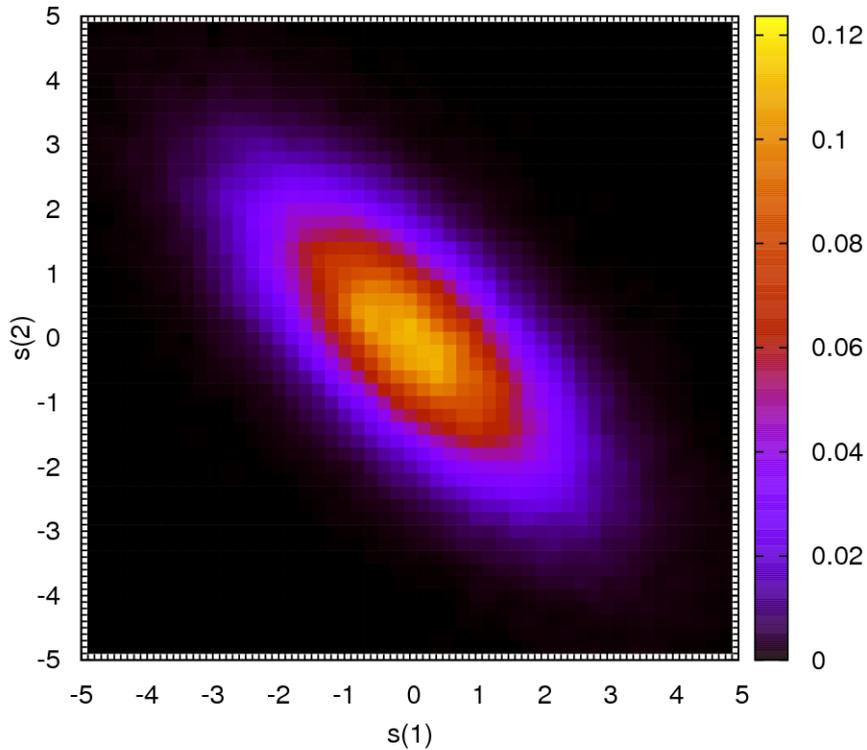
Theoretical



- State weight/histogram generated via Metropolis algorithm

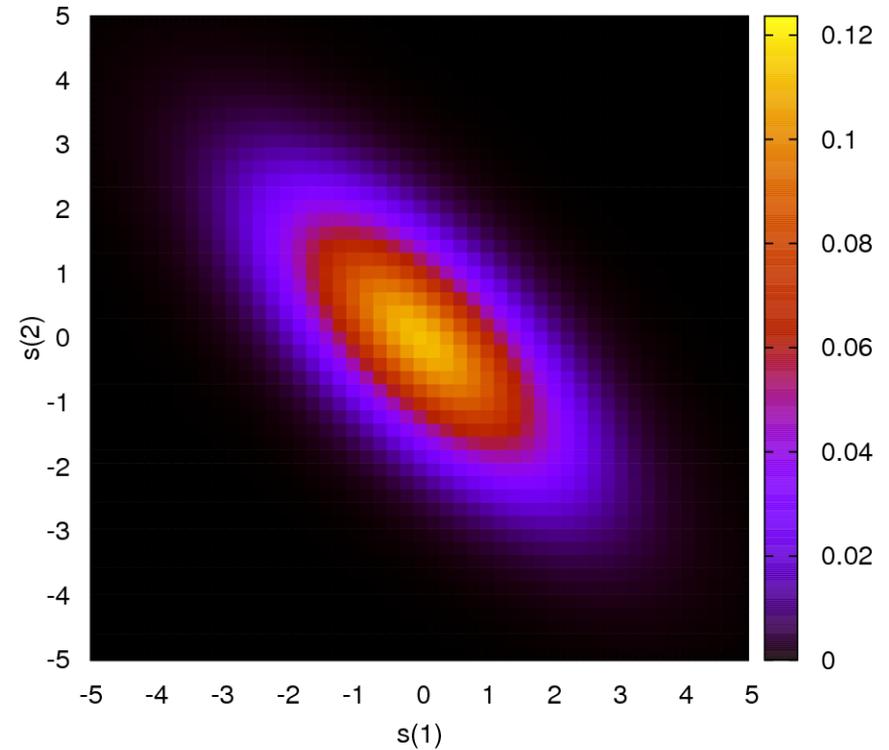
HMC measured

State Histogram 2-site scalar model ($\beta=0.7$)



Theoretical

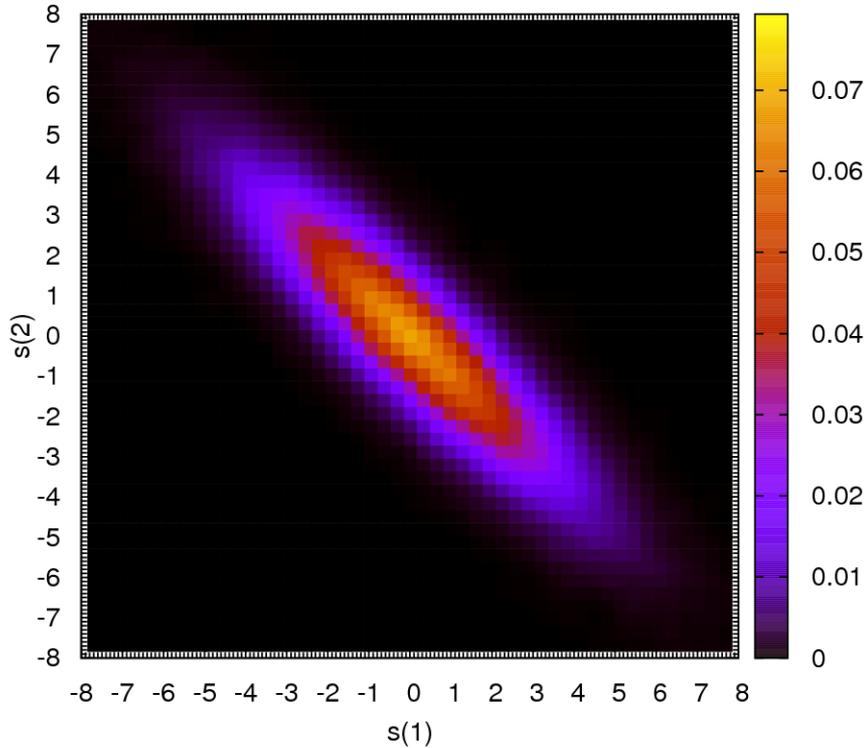
State Histogram 2-site scalar model ($\beta=0.7$)



- State weight/histogram generated via Metropolis algorithm

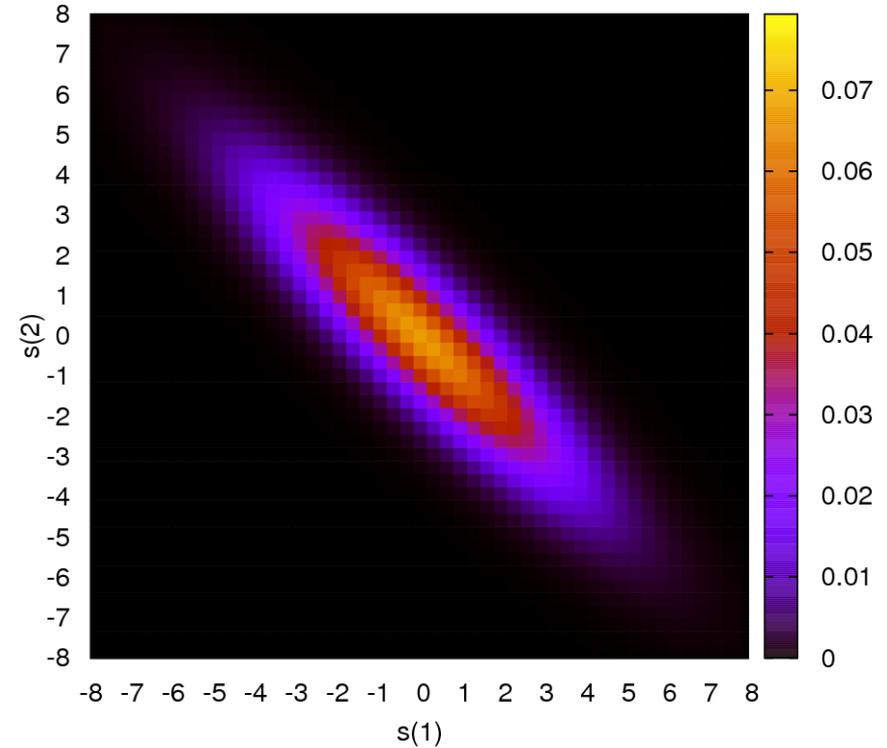
HMC measured

State Histogram 2-site scalar model ($\beta=0.9$)



Theoretical

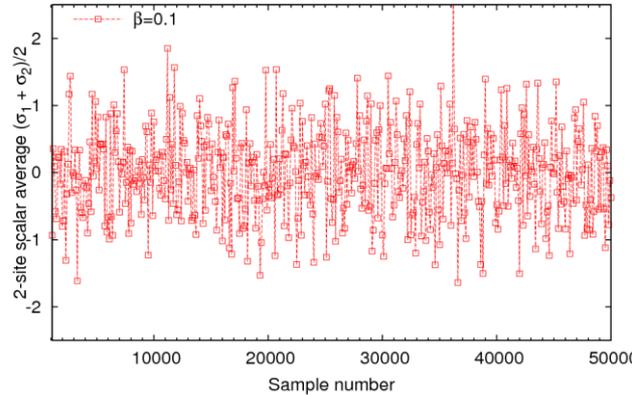
State Histogram 2-site scalar model ($\beta=0.9$)



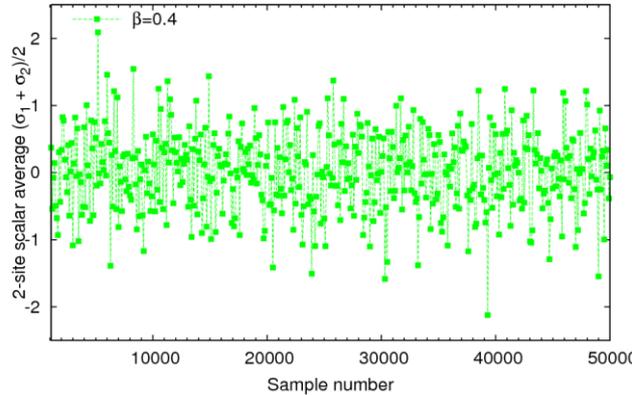
- Spin average/Spin correlation history

Spin average

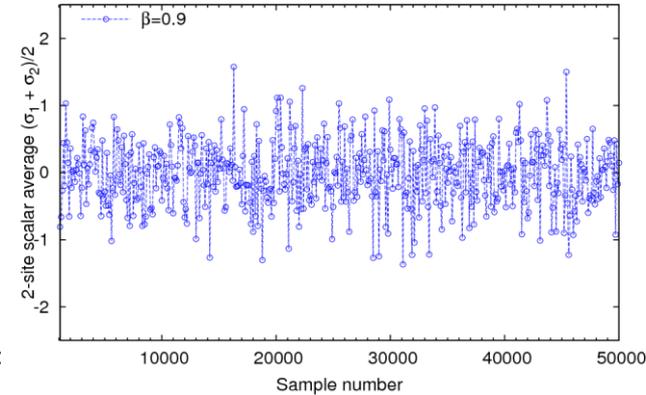
2-site scalar average sample history (2-site scalar model)



2-site scalar average sample history (2-site scalar model)

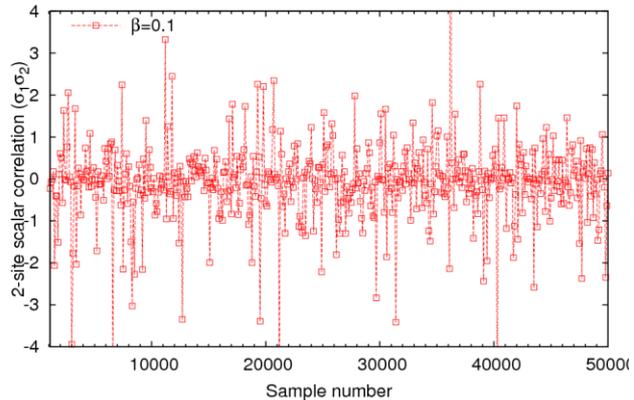


2-site scalar average sample history (2-site scalar model)

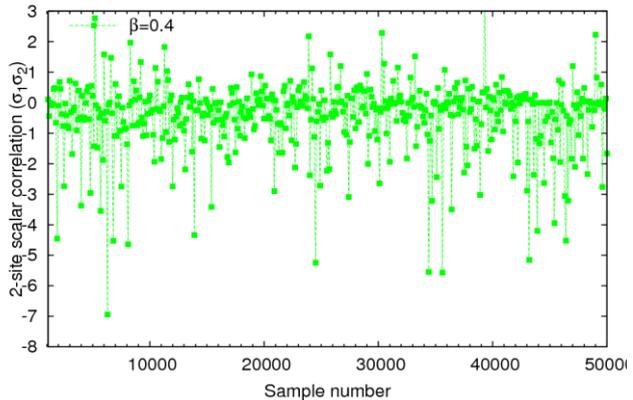


Spin correlation

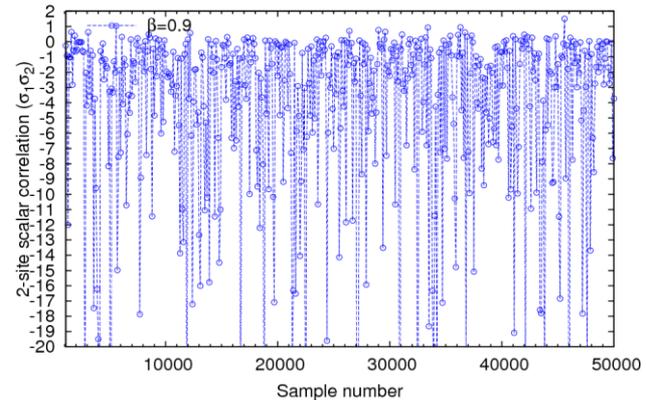
2-site scalar correlation sample history (2-site scalar model)



2-site scalar correlation sample history (2-site scalar model)



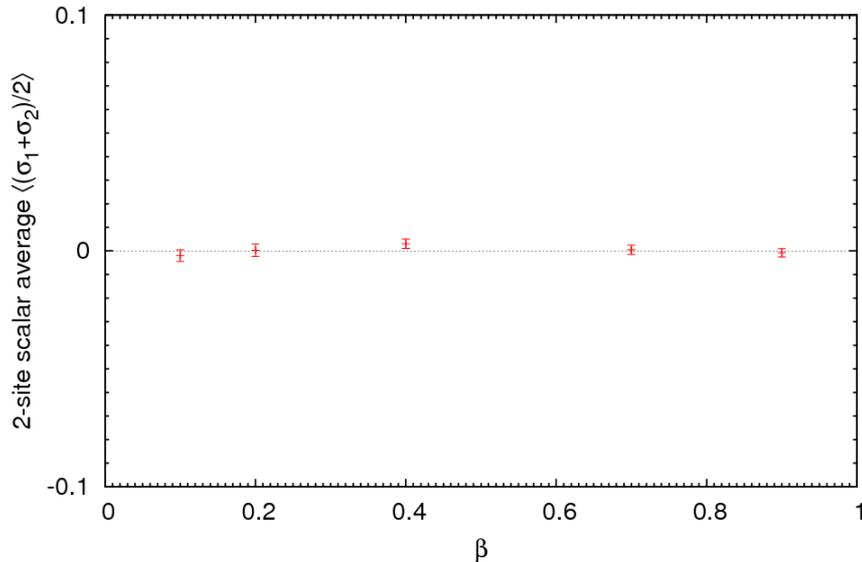
2-site scalar correlation sample history (2-site scalar model)



- β dependence of expectation values

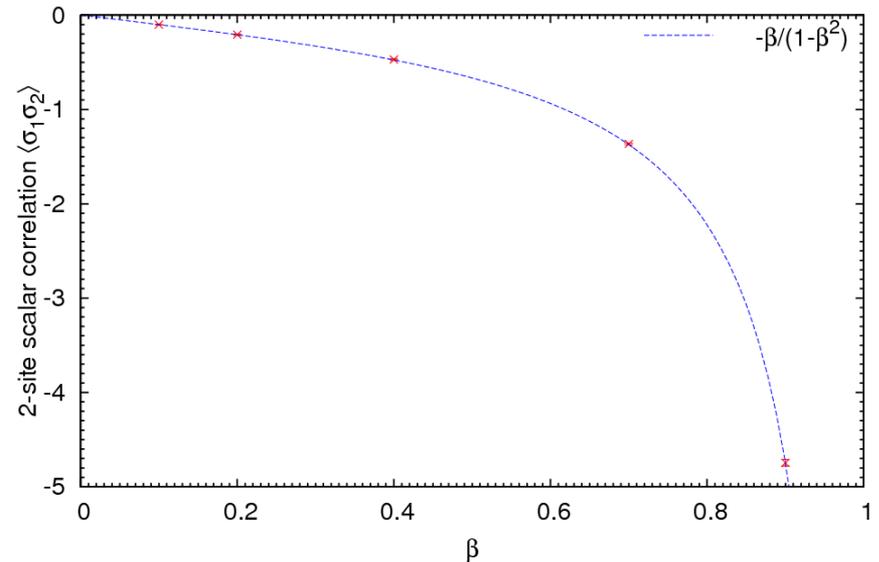
Spin average

β dependence of 2-site scalar average (2-site scalar model)



Spin correlation

β dependence of 2-site scalar correlation (2-site scalar model)



- Statistical averaging reproduces theoretical results.
- Acceptance rate is about 90% for this simple model.

6. HMC for LQCD

- For LQCD we can employ HMC algorithm to generate link variable ensemble. However several non-trivial issues still remain.
 - (1) We have to introduce fictitious momentum for link variables for MD evolution. This is not trivial as scalar variables because link variables U take $SU(3)$ values. **How can we introduce the fictitious momentum?**

$$Z(0) = \int_{-\infty}^{\infty} DU \prod_{f=u,d,s} \det[D_f[U]] \exp[-S_G[U]] \quad \Pi \text{ for } U ?$$

- The Gauge action is expressed in local form. However the quark determinant term has non-local form/non-trivial dependence on link variables. **How can we incorporate the determinant in the MD evolution?**
- I simply give the answers for these questions.

6-1 MD momentum for U (SU(3) matrix)

– Consider single U for example.

– In order to move in the SU(3) compact phase space, we have to introduce group manifold.

– U can be expressed as

$$U = \exp[iA] \quad A \in su(3), \quad \text{Tr} A = 0, \quad A^\dagger = -A$$

– We define the time derivative of U as

$$\frac{\partial}{\partial \tau} U = i\Pi U$$

– This corresponds to

$$U(\tau) = T \exp \left[i \int_0^\tau ds \Pi(s) \right] U(0)$$

– Where Π is the momentum for A .

$$\Pi \in su(3), \quad \text{Tr} \Pi = 0, \quad \Pi^\dagger = -\Pi$$

– We use (Π, U) for the MD evolution instead of (Π, A) although we have introduced Π for A .

- How to derive the equation of motion?

- The kinetic term is introduced as

$$H(\Pi, U) = \frac{1}{2} \text{Tr}[\Pi\Pi\Pi] + S(U) = \frac{1}{4} \sum_{a=1}^8 (\Pi^a)^2 + S(U)$$

- Where we used the following generator.

$$\Pi = \sum_{a=1}^8 \Pi^a T^a \quad \text{Tr}[T^a T^b] = \frac{1}{2}$$

Kinetic term normalization is irrelevant for the MD evolution. This simply changes the scale of fictitious time.

- The force expression is non-trivial since we use (Π, U) as variables to be evolved. (we need derivatives w.r.t. SU(3) matrix U .)
- To avoid derivatives w.r.t. U , we may force Energy conservation low to the Hamiltonian with the definition of momentum.

$$\frac{\partial}{\partial \tau} H(\Pi, U) = 0 \quad \text{and} \quad \frac{\partial}{\partial \tau} U = i\Pi U$$

- From this we can extract the equation of motion for Π .

- **HMC for Single SU(3) matrix model**

Analytic integration and expressions are known.

- Partition function:

$$Z(\beta) = \int dU \exp[-S(U, \beta)]$$

$$S(U, \beta) = -\beta \text{Tr}[U + U^\dagger] = -2\beta \text{ReTr}[U]$$

- Observables:

$$\langle (2\text{ReTr}[U])^k \rangle = \frac{1}{Z(\beta)} \int dU (2\text{ReTr}[U])^k \exp(-S(U)) = \frac{1}{Z(\beta)} \frac{\partial^k Z(\beta)}{\partial \beta^k}$$

- HMC

$$Z_{HMC}(\beta) = \int d\Pi dU \exp[-H(\Pi, U, \beta)]$$

$$H(\Pi, U) = \frac{1}{2} \text{Tr}[\Pi\Pi] + S(U) = \frac{1}{4} \sum_{a=1}^8 (\Pi^a)^2 + S(U)$$

- Hamiltonian eq. of. M.

$$\frac{\partial}{\partial \tau} H(\Pi, U) = 0 \quad \text{and} \quad \frac{\partial}{\partial \tau} U = i\Pi U$$

$$0 = \frac{\partial}{\partial \tau} H(\Pi, U) = \text{Tr}[\Pi\dot{\Pi} - \beta(i\Pi U - U^\dagger \Pi^\dagger i)] = \text{Tr}[\Pi(\dot{\Pi} - i\beta(U - U^\dagger))]$$

$$\dot{\Pi} = i\beta \left[V - \frac{\text{Tr}[V]}{3} \right] \quad \text{and} \quad \dot{U} = i\Pi U$$

$$V \equiv U - U^\dagger$$

Traceless and Hermitian property of su(3) is imposed to the force computation.

- HMC for Single SU(3) matrix model

- HMC Molecular dynamics

$$\dot{\Pi} = i\beta \left[V - \frac{\text{Tr}[V]}{3} \right] \quad \text{and} \quad \dot{U} = i\Pi U$$

$$V \equiv U - U^\dagger$$

- Coordinate (U) update:

- Solve $\dot{U} = i\Pi U$ for $\Delta\tau$ with constant Π approx.

$$Q(\Delta\tau) \begin{pmatrix} \Pi \\ U \end{pmatrix} \equiv \begin{pmatrix} \Pi \\ \exp[i\Delta\tau \times \Pi] U \end{pmatrix},$$

Numerical evaluation of Matrix exponential is required.

- Taylor expansion method.
- Diagonalization method.

- Momentum (Π) update:

$$P(\Delta\tau) \begin{pmatrix} \Pi \\ U \end{pmatrix} \equiv \begin{pmatrix} \Pi + \Delta\tau \times F \\ U \end{pmatrix}, \quad F = i\beta \left[V - \frac{\text{Tr}[V]}{3} \right], \quad V \equiv U - U^\dagger$$

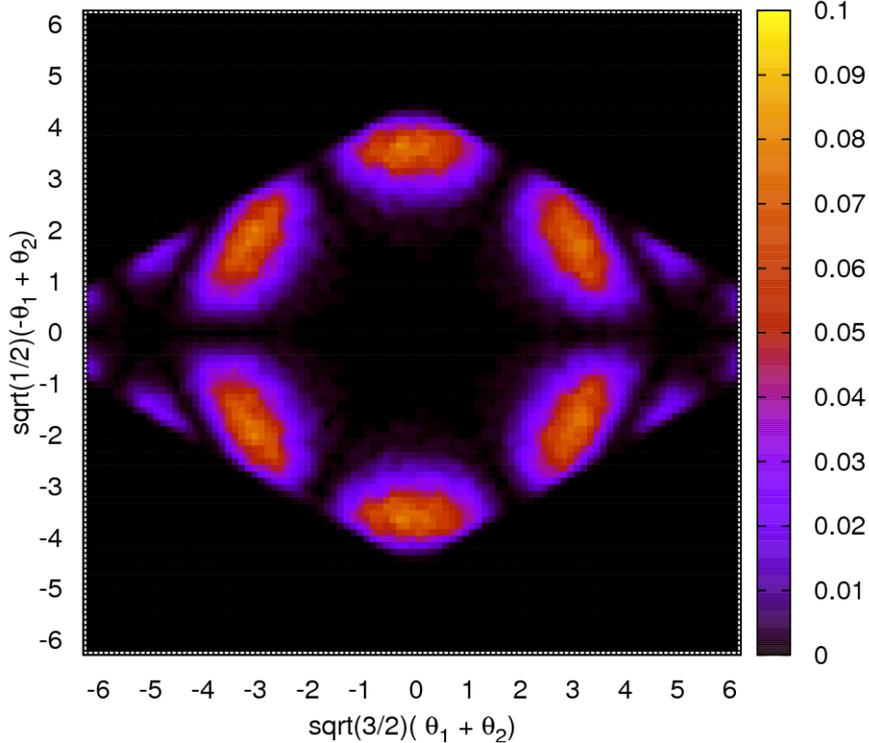
Note: In order to be U in SU(3) matrix.
Re-orthonormalization and $\det[U]=1$
condition is forced in the MD evolution.

Simply add the force to the momentum as usual.

- HMC for Single SU(3) matrix model
 - Fortran program: [<http://theo.phys.sci.hiroshima-u.ac.jp/~ishikawa/ASLFT2010/SingleSU3MatrixHMC.tar.gz>]
 - SU(3) matrix eigenvalues phase distribution: (100000 trajs, 10000 samples, 10-intervals, $N_{MD}=4$, $\tau=1$)

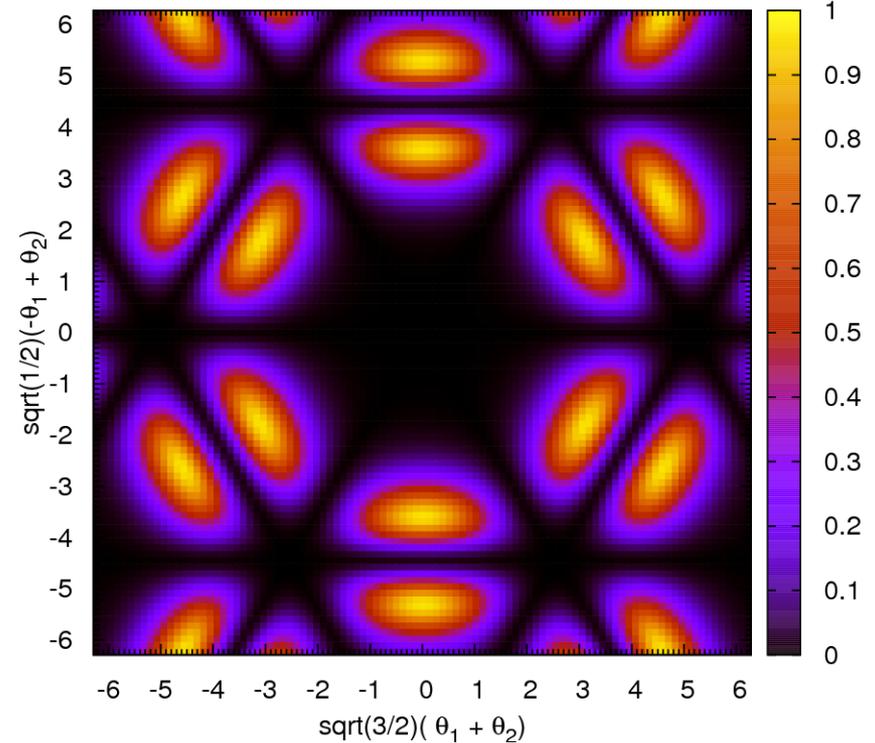
HMC measured

Eigenvalue angle Histogram single SU(3) matrix model ($\beta=-1.0$)



Theoretical

Eigenvalue angle Histogram single SU(3) matrix model ($\beta=-1.0$)



$$(\theta_1, \theta_2, \theta_3), \theta_1 + \theta_2 + \theta_3 = 0$$

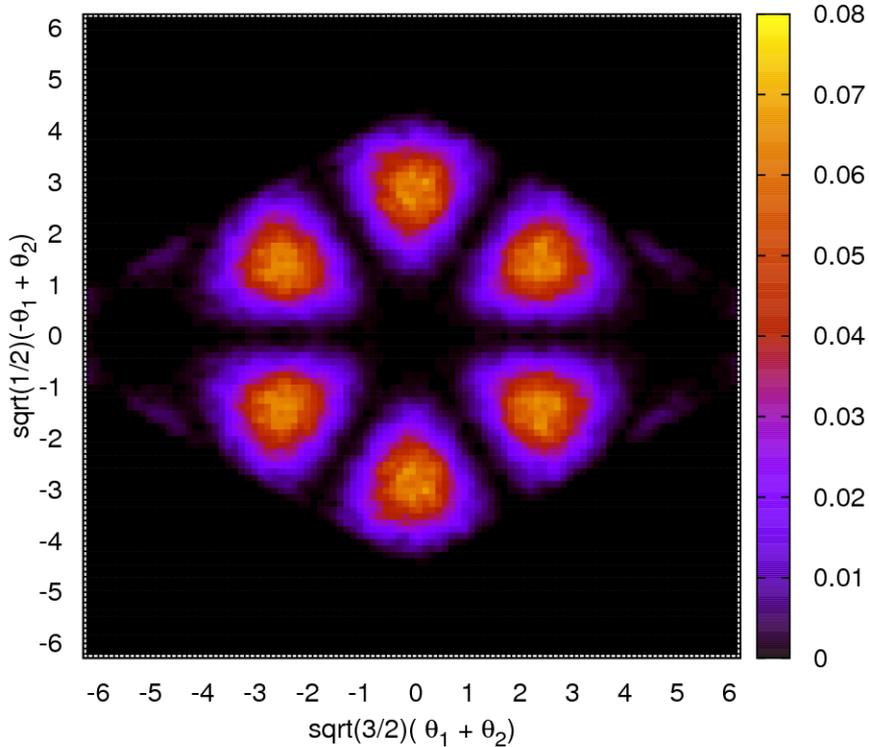
- HMC for Single SU(3) matrix model

– SU(3) matrix eigenvalues phase distribution:

$$(\theta_1, \theta_2, \theta_3), \theta_1 + \theta_2 + \theta_3 = 0$$

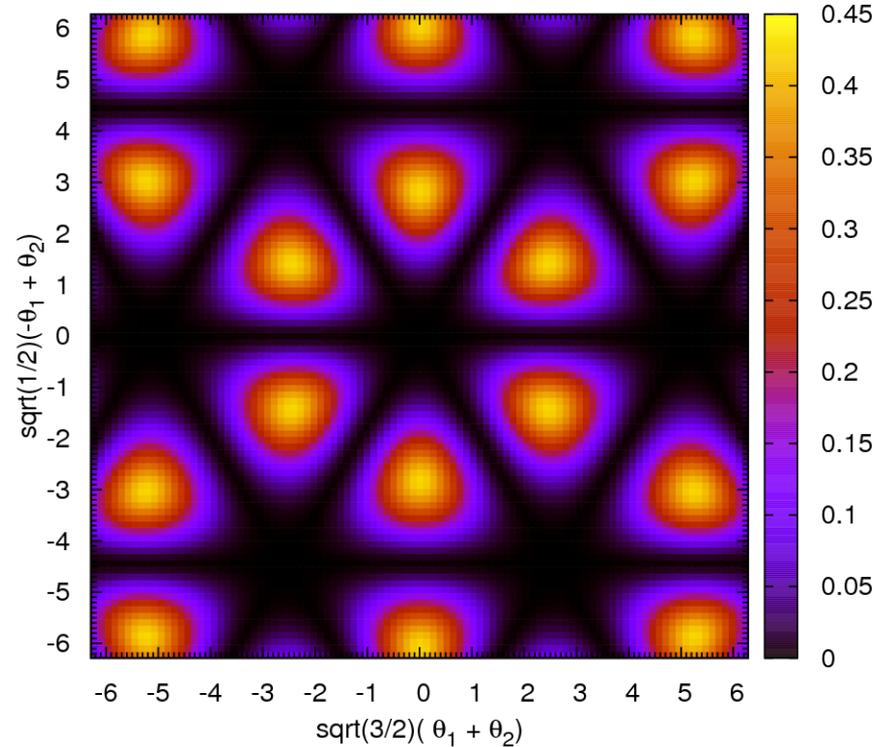
HMC measured

Eigenvalue angle Histogram single SU(3) matrix model ($\beta=0.1$)



Theoretical

Eigenvalue angle Histogram single SU(3) matrix model ($\beta=0.1$)



Theoretical distribution via
Weyl parameterization.

$$p(\theta_1, \theta_2) \propto \sin^2\left(\frac{\theta_1 - \theta_2}{2}\right) \sin^2\left(\frac{2\theta_1 + \theta_2}{2}\right) \sin^2\left(\frac{\theta_1 + 2\theta_2}{2}\right) \exp[2\beta(\cos \theta_1 + \cos \theta_2 + \cos(\theta_1 + \theta_2))]$$

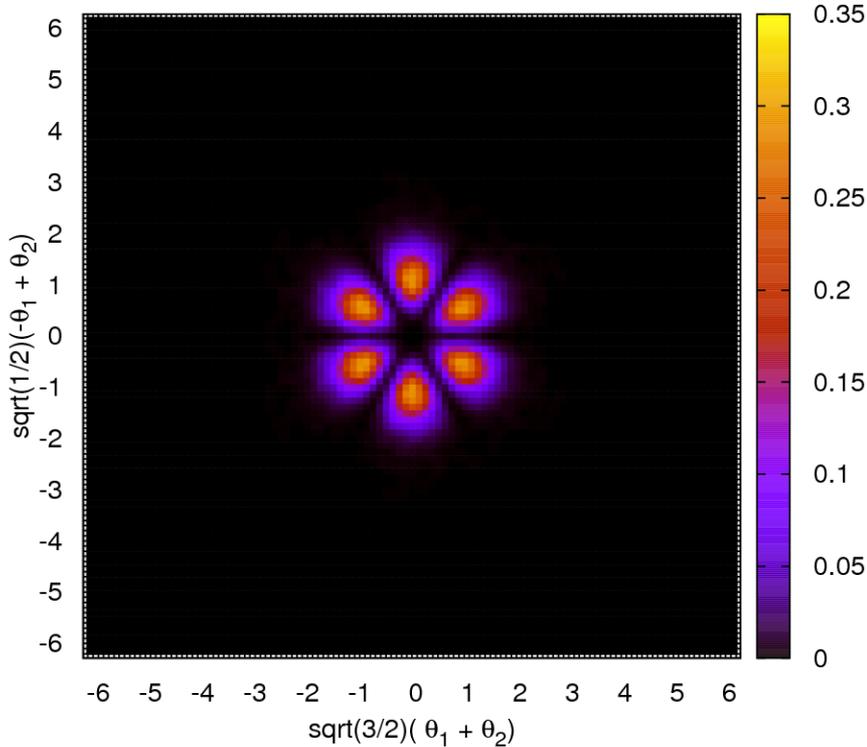
- HMC for Single SU(3) matrix model

– SU(3) matrix eigenvalues phase distribution:

$$(\theta_1, \theta_2, \theta_3), \theta_1 + \theta_2 + \theta_3 = 0$$

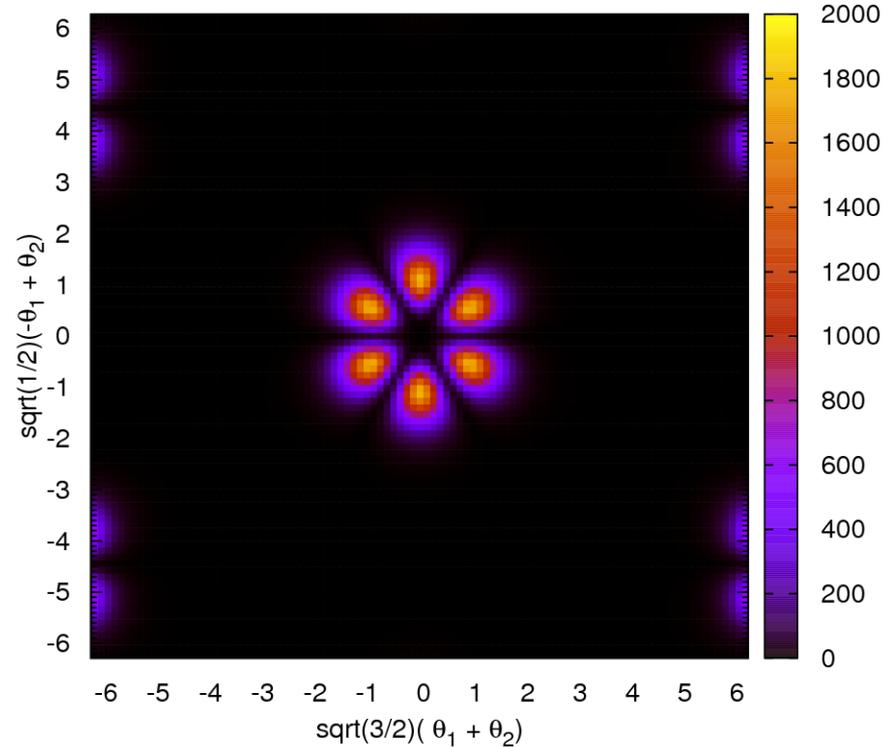
HMC measured

Eigenvalue angle Histogram single SU(3) matrix model ($\beta=2.5$)



Theoretical

Eigenvalue angle Histogram single SU(3) matrix model ($\beta=2.5$)



Theoretical distribution via
Weyl parameterization.

$$p(\theta_1, \theta_2) \propto \sin^2\left(\frac{\theta_1 - \theta_2}{2}\right) \sin^2\left(\frac{2\theta_1 + \theta_2}{2}\right) \sin^2\left(\frac{\theta_1 + 2\theta_2}{2}\right) \exp[2\beta(\cos \theta_1 + \cos \theta_2 + \cos(\theta_1 + \theta_2))]$$

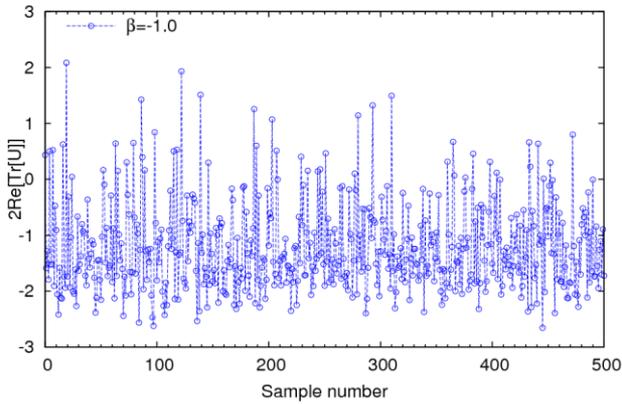
- HMC for Single SU(3) matrix model

– Oberevables:

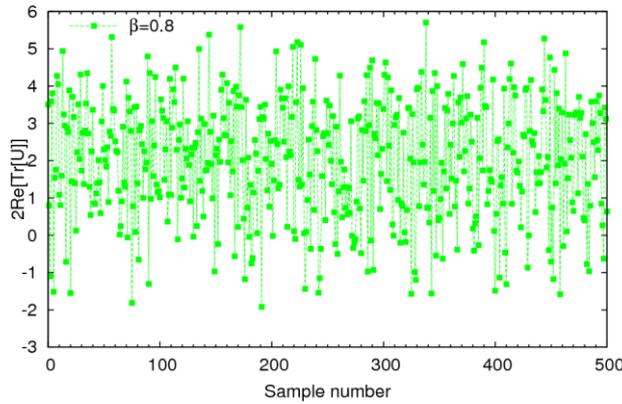
$$2\text{ReTr}[U], \text{ and } (2\text{ReTr}[U])^2$$

$2\text{ReTr}[U]$ HMC history

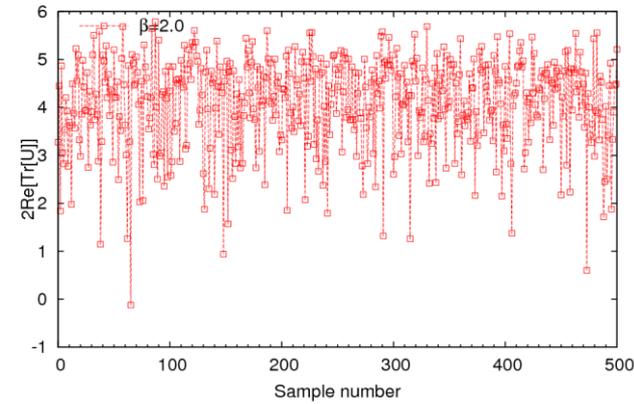
Single SU(3) matrix model $2\text{ReTr}[U]$ sample history



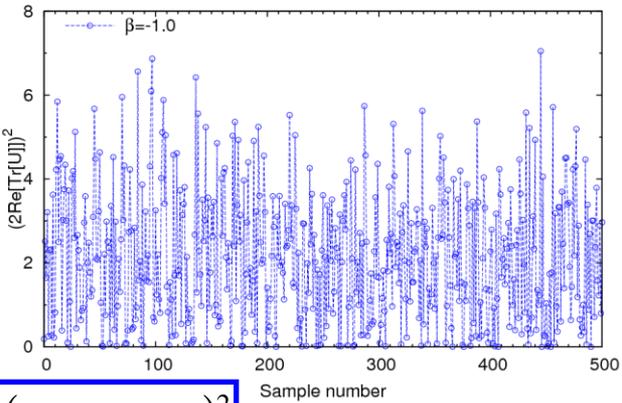
Single SU(3) matrix model $2\text{ReTr}[U]$ sample history



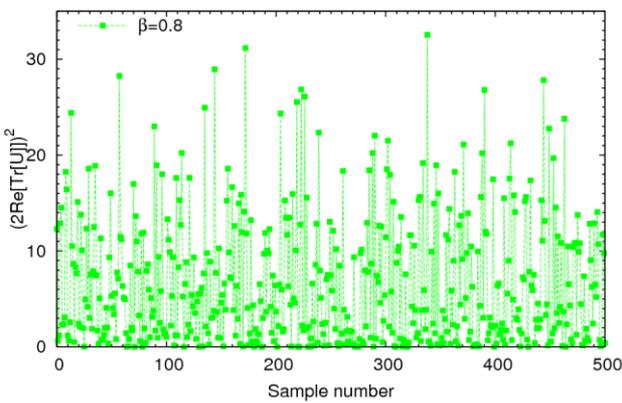
Single SU(3) matrix model $2\text{ReTr}[U]$ sample history



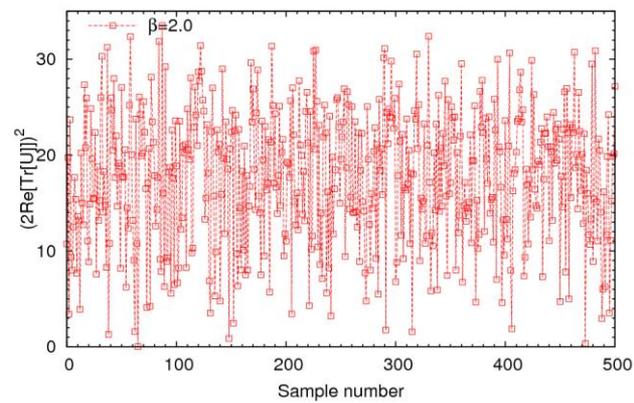
Single SU(3) matrix model $(2\text{ReTr}[U])^2$ sample history



Single SU(3) matrix model $(2\text{ReTr}[U])^2$ sample history



Single SU(3) matrix model $(2\text{ReTr}[U])^2$ sample history



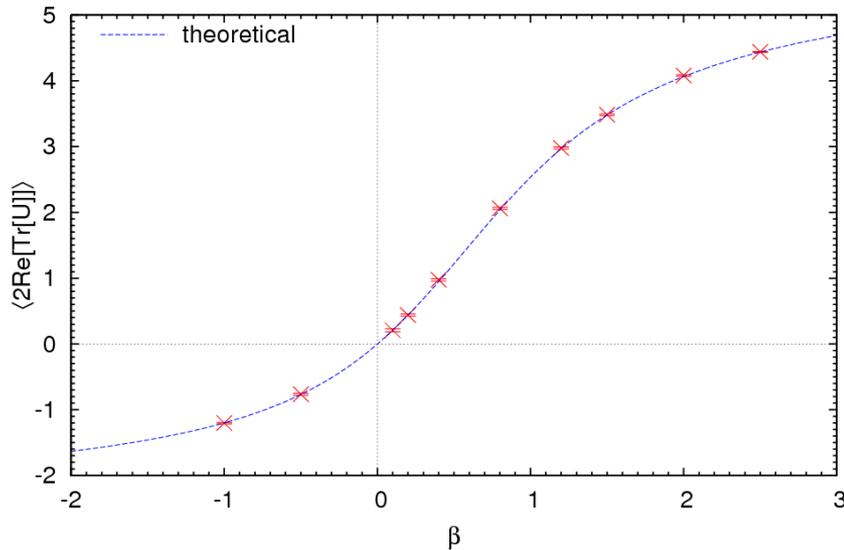
$(2\text{ReTr}[U])^2$

- HMC for Single SU(3) matrix model

- Observables: $\langle 2 \text{ReTr}[U] \rangle$, and $\langle (2 \text{ReTr}[U])^2 \rangle$
- Beta dependence of the expectation values.

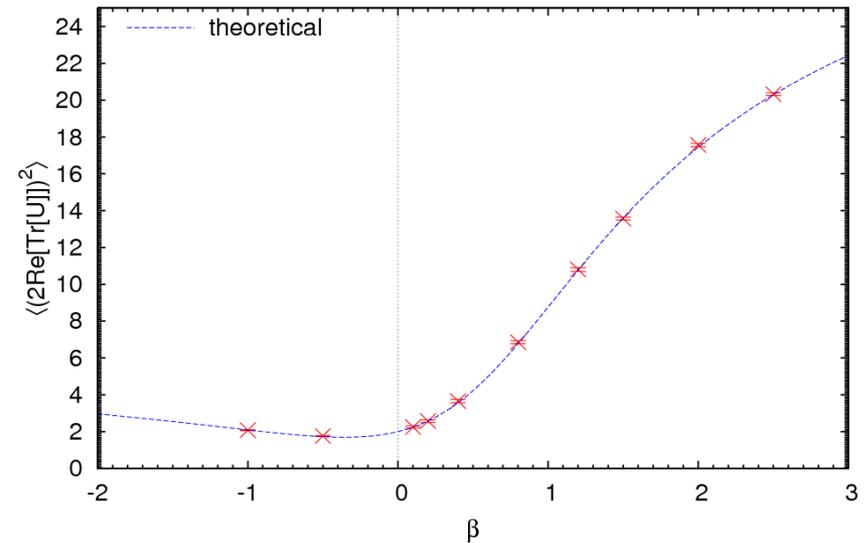
$$\langle 2 \text{ReTr}[U] \rangle$$

β dependence of $\langle 2 \text{ReTr}[U] \rangle$ (single SU(3) matrix model)



$$\langle (2 \text{ReTr}[U])^2 \rangle$$

β dependence of $\langle (2 \text{ReTr}[U])^2 \rangle$ (single SU(3) matrix model)



Check the SU(3) matrix related computations in the program

- Projection to Traceless-Hermitian,
- MatrixExp,
- Orthonormalization & $\det[U]=1$ condition, ...

Note that the HMC algorithm flow is identical to that of 2-site scalar model.

How about for LQCD?

- How to derive the equation of motion for LQCD?

– For Wilson gauge action: $H[\Pi, U] = \frac{1}{2} \sum_{n, \mu} \text{Tr}[\Pi_\mu(n) \Pi_\mu(n)] + S_G[U]$

$$S_G[U] = \beta \sum_n \sum_{\mu > \nu} \left(1 - \frac{1}{2N_c} \text{Tr} [P_{\mu\nu}(n) + P_{\mu\nu}(n)^\dagger] \right)$$

$$P_{\mu\nu}(n) \equiv U_\mu(n) U_\nu(n + \hat{\mu}) U_\mu(n + \hat{\nu})^\dagger U_\nu(n)^\dagger$$

$$0 = \frac{\partial}{\partial \tau} H(\Pi, U) = \sum_{n, \mu} \text{Tr} [\Pi_\mu(n) \dot{\Pi}_\mu(n)] + \frac{\partial}{\partial \tau} S_G(U) \quad \leftarrow \dot{U}_\mu(n) = i\Pi_\mu(n)U_\mu(n)$$

$$= \sum_{n, \mu} \text{Tr} [\Pi_\mu(n) \dot{\Pi}_\mu(n) - \Pi_\mu(n) F_\mu(n)] = \sum_{n, \mu} \text{Tr} [\Pi_\mu(n) (\dot{\Pi}_\mu(n) - F_\mu(n))]$$

– We obtain $\dot{\Pi}_\mu(n) = F_\mu(n)$

$$F_\mu(n) = \frac{i\beta}{6} \left([V_\mu(n) - V_\mu(n)^\dagger] - \frac{1}{3} \text{Tr} [V_\mu(n) - V_\mu(n)^\dagger] \right) \quad \leftarrow \text{Traceless condition is forced explicitly for numerical stability}$$

$$V_\mu(n) = \sum_{\nu \neq \mu} [U_\mu(n) U_\nu(n + \hat{\mu}) U_\mu(n + \hat{\nu})^\dagger U_\nu(n)^\dagger + U_\mu(n) U_\nu(n + \hat{\mu} - \hat{\nu})^\dagger U_\mu(n - \hat{\nu})^\dagger U_\nu(n - \hat{\nu})]$$

Problem 7

6-2 Quark Determinant incorporation in the HMC

- The matrix size of quark operator is extremely large. Thus the exact/analytic computation of the Determinant is impossible.

$D[U]$: A Lattice Dirac operator is a complex matrix with dimension : $(3 \times 4 \times N_T \times N_Z \times N_Y \times N_X)$

Typical DIM = $3 \times 2^{18} \sim 800000$ = for 16^4 lattice

- Stochastic estimate of the determinant have been used in the HMC for LQCD.
- The most common stochastic method is the “Pseudo-Fermion method”.
- Here I Briefly explain the pseudo-fermion method.

- Pseudo-Fermion method.

- The determinant of a matrix can be expressed by a integral of scalar field.

$$\frac{1}{\det[A]} = C \int d\vec{\phi}^\dagger d\vec{\phi} \exp\left[-\vec{\phi}^\dagger A \vec{\phi}\right]$$

$\vec{\phi}$ Complex scalar field(=Complex vecotr)
 A Complex Matrix (Non-singular)

- If A is Hermitian and positive $\exp\left[-\vec{\phi}^\dagger A \vec{\phi}\right]$ can be treated as a probability distribution for $(\vec{\phi}^\dagger, \vec{\phi})$.
- For Quark determinant with 2-flavor (up,down) with degenerate masses. We can transform the determinant to the integration of complex scalar variables.

- Pseudo-Fermion method.

$$\begin{aligned}
 \det[D_u] \det[D_d] &= \det[D] \det[D] = \det[D] (\det[D]^*) \\
 &= |\det[D]|^2 = \det[(DD^\dagger)] \\
 &= C \int d\vec{\phi}^\dagger d\vec{\phi} \exp\left[-\vec{\phi}^\dagger (DD^\dagger)^{-1} \vec{\phi}\right] \\
 &= C \int d\vec{\phi}^\dagger d\vec{\phi} \exp\left[-\left|(D)^{-1} \vec{\phi}\right|^2\right]
 \end{aligned}$$

- Where $D^\dagger = \gamma_5 D \gamma_5$, $(\gamma_5)^2 = 1$, $\det[AB] = \det[BA]$ are used.
- $(\vec{\phi}^\dagger, \vec{\phi})$ are called as the Pseudo-fermion field.
- The pseudo-fermion field is incorporated in the random variables. Thus we have to generate the ensemble for $(U, \vec{\phi}^\dagger, \vec{\phi})$..
- In order for $\exp\left[-\left|D^{-1} \vec{\phi}\right|^2\right]$ to be a probability, we have used the positivity and realness of $(\det[D] \det[D])$ using two quarks with the identical masses. For odd-number flavor simulations tricks are required to introduce the pseudo-fermion. (I will skip this issue. See Polynomial-HMC, Rational-HMC)

- HMC algorithm for Two-flavor LQCD

$$\langle O[U, D[U]^{-1}] \rangle = \frac{1}{Z[0]} \int \prod_n d\phi^\dagger(n) d\phi(n) \prod_{n,\mu} dU_\mu(n) O[U, D[U]^{-1}] \exp[-S_G[U] - S_{PF}[U, \phi^\dagger, \phi,]]$$

$$S_{PF}[U, \phi^\dagger, \phi] \equiv \sum_n \left| \sum_m (D[U])^{-1}_{(n,m)} \phi(m) \right|^2 = |(D[U])^{-1} \vec{\phi}|^2$$

– HMC algorithm is applied to $S_G[U] + S_{PF}[U, \phi^\dagger, \phi]$.

- The momentum Π is introduced only for U .
- $(\vec{\phi}^\dagger, \vec{\phi})$ are treated as a auxiliary field and not evolved during the MD. $(\vec{\phi}^\dagger, \vec{\phi})$ are generated directly by the distribution

$$\phi = D[U]\eta, \quad \text{with Gaussian random number } \eta. \quad \exp\left[-|D^{-1}\vec{\phi}|^2\right]$$

$$\text{Prob}(\eta^\dagger, \eta) \propto \exp\left[-|\eta|^2\right]$$

- HMC algorithm for Two-flavor LQCD

$$S_{PF}[U, \phi^\dagger, \phi] \equiv \left| (D[U])^{-1} \vec{\phi} \right|^2$$

$$H[\Pi, U, \phi^\dagger, \phi] = \frac{1}{2} \sum_{n, \mu} \text{Tr}[\Pi_\mu(n) \Pi_\mu(n)] + S_G[U] + S_{PF}[U, \phi^\dagger, \phi]$$

(Step 0) Generate initial state U

(Step 1) Generate initial momentum Π from Gaussian dist.

Generate pseudo-fermion field ϕ from $\phi = D[U]\eta$ with Gaussian dist' d η .

(Step 2) MD evolution to get (Π', U') from (Π, U)

(Step 3) (flip momentum $\Pi' = -\Pi'$)

(Step 4) Do Metropolis test with prob. $P = \min(1, e^{-H'+H})$

If accepted ($U = U'$) and add (U) to the ensemble.

If rejected add (U) to the ensemble.

(Step 5) Goto Step 1

- Note 1: We have new contribution from S_{PF} term in the MD evolution. The force computation is required.
- Note 2: We need inversion computation $(D[U])^{-1} \vec{\phi}$ to evaluate S_{PF} value.

- Pseudo-Fermion Contribution to the MD.

- We can derive the MD force expression via $0 = \frac{\partial}{\partial \tau} H[\Pi, U, \phi^\dagger, \phi]$
- as before.

- Evaluating
$$\frac{\partial}{\partial \tau} S_{PF}[U, \phi^\dagger, \phi] \equiv \frac{\partial}{\partial \tau} |(D[U])^{-1} \vec{\phi}|^2$$

- We have
$$\begin{aligned} \frac{\partial}{\partial \tau} |(D[U])^{-1} \vec{\phi}|^2 &= - \left[X^\dagger (D[U])^{-1} \frac{\partial D[U]}{\partial \tau} X \right] - [h.c.] = - \left[\text{Tr} \left[\frac{\partial D[U]}{\partial \tau} X X^\dagger (D[U])^{-1} \right] \right] - [h.c.] \\ &= - \left[\text{Tr} \left[i \Pi_\mu U_\mu \left(\frac{\partial D[U]}{\partial U_\mu} \right) X Y^\dagger \right] \right] - [h.c.] = \text{Tr} [-i \Pi_\mu F_{PF\mu}] \end{aligned}$$

- where

$$X \equiv (D[U])^{-1} \vec{\phi}, \quad Y \equiv (D[U]^\dagger)^{-1} (D[U])^{-1} \vec{\phi} = \gamma_5 (D[U])^{-1} \gamma_5 (D[U])^{-1} \vec{\phi}$$

- Thus we need **two-inversion** computation to evaluate the MD force from the pseudo-fermion at **every time step**.

$$F_{PF\mu} = F_{PF\mu}[U, X, Y]$$

Problem 8

This is the most time consuming part of LQCD simulations

- In the last lecture I will explain the methods to invert the lattice Dirac operator $D[U]$.
- However the explanation using the explicit form of $D[U]$ is rather tedious. I will explain the common part of the algorithm to invert more simple lattice discretised differential operators.
- I will employ the Poisson equation on discretized space(=3D/2D/1D lattices).

$$D[U]\phi = \eta \Leftrightarrow -\Delta\phi = \rho$$

Lattice Dirac equation with source term

Lattice Poisson equation with source term

$$\phi = D[U]^{-1}\eta \Leftrightarrow \phi = -\Delta^{-1}\rho$$

Problems

- (1) Check that the Leapfrog scheme has the error term explained in [page 19].
- (2) Check that the Leapfrog scheme satisfies the area conservation law [page 20].
- (3) Check the detailed balance condition for the HMC transition probability described in [page 23].
- (4) Evaluate the eigenvalues of the MD transition matrix for a Harmonic Oscillator [page 26]. When does the evolution become unstable?
- (5) Get and compile the 2-Site Scalar model. Check the result numerically. [page 28-35]
- (6) Get and compile the Single SU(3) matrix model. Check the result numerically. [page 39-45]
- (7) Derive the MD force expression for the Wilson gauge action (quenched LQCD) [page 46].
- (8) [Advanced] Derive the MD force from the pseudo-fermion part with the Wilson-Dirac action [page 52][page 4 for the explicit form of $D[U]$].

Backups

- SU(3) matrix from su(3) matrix.
 - We need to compute SU(3) matrix from su(3) Hermitian traceless matrix via matrix exponential form.

$$V = \exp[iaH] \quad \begin{array}{l} H : H^\dagger = H \text{ and } \text{Tr}[H] = 0 \\ a : \text{real parameter} \end{array}$$

- There are Two categories to compute this
 - (1) method based on Eigen decomposition.
 - (2) method based on Taylor expansion.

Backups

- (1) method based on Eigen decomposition.

- H can be diagonalized and has real eigen values.
- The characteristic polynomial is

$$\det[H - \lambda] = -\lambda^3 + x\lambda + y \quad x = \frac{\text{Tr}[H^2]}{2}, \quad y = \frac{\text{Tr}[H^3]}{3} \in \mathbb{R}$$

- We can diagonalize as $H = Q^\dagger \Lambda Q$

- We can compute the matrix exponential as

$$V = Q^\dagger \exp[ia\Lambda]Q = Q^\dagger \begin{pmatrix} e^{ia\lambda_1} & & \\ & e^{ia\lambda_2} & \\ & & e^{-ia(\lambda_1+\lambda_2)} \end{pmatrix} Q^\dagger$$

- This method needs some care when a pair of the eigenvalues nearly degenerates. To avoid loss of significant digit in the computation some special formula should be used.

Backups

- (2) method based on Taylor expansion.

- Any matrix exponential are defined as

$$V = \exp[iaH] = \sum_{j=0}^{\infty} \frac{(iaH)^j}{j!}$$

- We can truncate the series at

$$V = \exp[iaH] \approx \sum_{j=0}^{N_{\text{exp}}} \frac{(iaH)^j}{j!} \quad \frac{|aH|^{N_{\text{exp}}}}{N_{\text{exp}}!} < \varepsilon$$

- However $|aH| > 1$ case the loss of significant digit occurs when computing the series even if we use Horner's method.

- We make use of the identity:

$$\exp[iaH] = \left(\exp\left[\frac{iaH}{2^m}\right] \right)^{2^m}$$

$V = 1$

do $j = N_{\text{exp}}, 1, -1$

$$V = 1 + \frac{ia}{j} HV$$

enddo

Backups

- (2) method based on Taylor expansion.
 - We make use of the identity:

$$\exp[iaH] = \left(\exp\left[\frac{iaH}{2^m}\right] \right)^{2^m}$$

- Divide and Squared method.

$$\text{determin } m \text{ s.t. } \left| \frac{iaH}{2^m} \right| < \frac{1}{2}$$

- 12th-14th order expansion is sufficient for the approx.

However this part can be further economized as follows.

$$V = \text{Approx} \left(\exp\left[\frac{iaH}{2^m}\right], N_{\text{exp}} = 12 \sim 14 \right)$$

do $j = 1, m$

$$V = V^2$$

enddo

Backups

- (2) method based on Taylor expansion.

- From the characteristic polynomial, we have

$$\det[H - \lambda] = -\lambda^3 + x\lambda + y \quad x = \frac{\text{Tr}[H^2]}{2}, \quad y = \frac{\text{Tr}[H^3]}{3} \in R$$

- Cayley-Hamilton theorem leads

$$-H^3 + xH + y = 0$$

- Thus any analytic function of H ($f(H)$) should have the following form.

$$f(H) = c_2 H^2 + c_1 H + c_0$$

- These coefficients $\{c_i\}$ are computed via a kind of modulo computation for polynomial.

$$f(H) = \sum_{j=-\infty}^{\infty} f_j H^j = c_2 H^2 + c_1 H + c_0 \pmod{H^3 - xH - y}$$

Backups

- (2) method based on Taylor expansion.
 - Instead of doing modulo computation for infinite series we compute

$$H^j = d_2^{(j)} H^2 + d_1^{(j)} H + d_0^{(j)} \pmod{H^3 - xH - y}$$

- {d's} are computed as follows,
- Define the 2nd order polynomial of H as a vector expressed by the coefficients.

$$\{d_0^{(j)}, d_1^{(j)}, d_2^{(j)}\} = \begin{pmatrix} d_0^{(j)} \\ d_1^{(j)} \\ d_2^{(j)} \end{pmatrix} \Leftrightarrow d_0^{(j)} + d_1^{(j)} H + d_2^{(j)} H^2 = H^j$$

This is a coefficient domain representation of a su(3) matrix function.

- We can evaluate next $H^{(j+1)}$ from using the Cayley-Hamilton theorem.

Backups

- (2) method based on Taylor expansion.
 - Instead of doing modulo computation for infinite series we compute

$$H^j = d_2^{(j)} H^2 + d_1^{(j)} H + d_0^{(j)} \pmod{H^3 - xH - y}$$

$$\begin{aligned} H^{j+1} &= d_0^{(j+1)} + d_1^{(j+1)} H + d_2^{(j+1)} H^2 = H \times (d_0^{(j)} + d_1^{(j)} H + d_2^{(j)} H^2) \\ &= d_0^{(j)} H + d_1^{(j)} H^2 + d_2^{(j)} H^3 \underset{\lambda}{=} y d_2^{(j)} + (d_0^{(j)} + x d_2^{(j)}) H + d_1^{(j)} H^2 \end{aligned}$$

$$\vec{d}^{(j+1)} = \begin{pmatrix} d_0^{(j+1)} \\ d_1^{(j+1)} \\ d_2^{(j+1)} \end{pmatrix} = \begin{pmatrix} y d_2^{(j)} \\ d_0^{(j)} + x d_2^{(j)} \\ d_1^{(j)} \end{pmatrix} = \begin{pmatrix} & y \\ 1 & x \\ & 1 \end{pmatrix} \begin{pmatrix} d_0^{(j)} \\ d_1^{(j)} \\ d_2^{(j)} \end{pmatrix} = \check{H} \vec{d}^{(j)}$$

- Thus we have

$$\vec{d}^{(j)} = \check{H}^j \vec{d}^{(0)}, \quad \vec{d}^{(0)} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Backups

- (2) method based on Taylor expansion.
 - The matrix exponential is now expressed as

$$\begin{aligned}
 \exp[iaH] &= \sum_{j=0}^{\infty} \frac{(iaH)^j}{j!} = \sum_{j=0}^{\infty} \frac{(ia)^j}{j!} (d_2^{(j)} H^2 + d_1^{(j)} H + d_0^{(j)}) \\
 &= \left(\sum_{j=0}^{\infty} \frac{(ia)^j d_2^{(j)}}{j!} \right) H^2 + \left(\sum_{j=0}^{\infty} \frac{(ia)^j d_1^{(j)}}{j!} \right) H + \left(\sum_{j=0}^{\infty} \frac{(ia)^j d_0^{(j)}}{j!} \right) \\
 &= (1, H, H^2) \begin{pmatrix} \sum_{j=0}^{\infty} \frac{(ia)^j d_0^{(j)}}{j!} \\ \sum_{j=0}^{\infty} \frac{(ia)^j d_1^{(j)}}{j!} \\ \sum_{j=0}^{\infty} \frac{(ia)^j d_2^{(j)}}{j!} \end{pmatrix} = (1, H, H^2) \sum_{j=0}^{\infty} \frac{(ia)^j}{j!} \vec{d}^{(j)} \\
 &= (1, H, H^2) \sum_{j=0}^{\infty} \frac{(ia)^j}{j!} \tilde{H}^j \vec{d}^{(0)} = (1, H, H^2) \exp[ia\tilde{H}] \vec{d}^{(0)}
 \end{aligned}$$

Backups

- (2) method based on Taylor expansion.

– The computation of $\exp[ia\check{H}^j]\vec{d}^{(0)}$ is much easier and economical than $V = \exp[iaH]$ using Taylor series,

because \check{H} is real and sparse. And we need a vector multiplied form of $\check{H}\vec{v}$ in this representation. Finally we have

$$V = \exp[iaH] = e_2 H^2 + e_1 H + e_0 = (1, H, H^2) \vec{e}$$

$$\vec{e} = \exp[ia\check{H}^j]\vec{d}^{(0)} \approx \sum_{j=0}^{N_{\text{exp}}} \frac{(ia\check{H})^j \vec{d}^{(0)}}{j!}$$

$$\check{H} \equiv \begin{pmatrix} & y \\ 1 & x \\ & 1 \end{pmatrix} \quad x = \frac{\text{Tr}[H^2]}{2}, \quad y = \frac{\text{Tr}[H^3]}{3} \in R$$

$$\vec{d}^{(0)} = (1, 0, 0)^T$$

$$\vec{e} = \vec{d}^{(0)}$$

$$\text{do } j = N_{\text{exp}}, 1, -1$$

$$\vec{e} = \vec{d}^{(0)} + \frac{ia}{j} \check{H} \vec{e}$$

enddo