

Lecture#1

Path integral and Monte Carlo simulations

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1. Lattice Field Theory?

- For example:
- Standard Model
 - QCD: Strong interaction, Hadrons \Leftarrow quarks, gluons
 - Glashow-Weinberg-Salam: Electroweak
 - QED: electromagnetic interaction: charged particles, photon
 - Weak interaction: Z,W bosons, leptons,...
 - Higgs mechanism
- These are based on Quantum field theory (QFT).
 - Perturbative analysis using the coupling constant expansion.
 - Rely on the smallness of the coupling.
- QCD: at low-energy, coupling expansion fails.
 - Non-perturbative analysis is required.

- To understand the nature of the strong interaction among Hadrons from the dynamics of quarks and gluons, Quantum Chromodynamics (QCD) has been introduced and investigated.
- QCD is well understood in the high-energy experiments where the asymptotic-free nature of the coupling constant of QCD enables us the perturbative expansion analysis.
- However, at low-energy, the perturbative analysis fails due to the large coupling constant.

- The lattice field theory is one of the non-perturbative analysis method.
- Lattice QCD has been used and developed to understand the low-energy nature of Hadrons.
- The various technique for lattice field theory is common and also has been used in LQCD.
- In this lecture I would like to give some lattice technique and numerical algorithms for LQCD as an example of lattice field theories.

2. Path integral and lattice field theory

- Feynman's path integral quantization is a fundamental basis for lattice field theory.
- Euclidean field is also required to introduce well defined (numerically calculable) path integral formulation.
- Lattice QCD is based on $SU(3)$ gauge theory defined on a Euclidean 4Dim lattice universe.

2-1 Feynman's path integral quantization

- A quantum field theory :
 - $S[\phi]$: Action.
 - $\phi(x)$: Field to be quantized (real scalar for simplicity).
 - x : space-time coordinate.

- Feynman's path integral quantization.

- Generating functional for Green's functions (correlation func.)

$$Z[\eta] = \int D\phi \exp \left[\frac{i}{\hbar} (S[\phi] + \eta \cdot \phi) \right]$$

- N-point Green's function of the theory.

$$\begin{aligned} \langle T[\hat{\phi}(x_1)\hat{\phi}(x_2)\cdots\hat{\phi}(x_n)] \rangle &= \frac{\hbar^n}{i^n Z[0]} \frac{\delta^n Z[\eta]}{\delta\eta(x_1)\delta\eta(x_2)\cdots\delta\eta(x_n)} \Big|_{\eta=0} \\ &= \frac{1}{Z[0]} \int D\phi (\phi(x_1)\phi(x_2)\cdots\phi(x_n)) \exp \left[\frac{i}{\hbar} S[\phi] \right] \end{aligned}$$

- We can extract various information from Green's functions basically....

- However, the analytic integration of the path-integral is not always available except for free field theories.
- The integral also has a difficulty in Minkowski metric. The integral is a kind of Fresnel integrals and the integrand oscillates. This may prevent us from evaluating it numerically....
- In order to evaluate this integral:
 - Introduce Euclidean path integral
 - Needs validation : Minkowski \leftrightarrow Euclid relation. Experimentally or constructive field theory, Osterwalder-Schrader axioms...
 - Discretize Space-Time \Rightarrow Lattice space-time
 - Needs validation: lattice spacing error
- Here we assume:
 - there is a Euclidean field theory for a target Minkowski field theory.

2-2 Euclidean path integral

- $S_E[\phi_E]$: Euclidean action.
- $\phi_E(x_E)$: Euclidean field. Real valued.
- $x_E = (x, y, z, \tau)$: Euclidean 4D coordinate.
 - They are usually obtained from Minkowski versions after Wick's rotation. $t = i\tau$

- Generating functional for Euclidean Green's functions.

$$Z_E[\eta] = \int D\phi_E \exp\left[-\frac{1}{\hbar} (S_E[\phi_E] - \eta \cdot \phi_E)\right]$$

- If the Euclidean action is real valued, the integral has a better property than the Minkowski version. A chance to evaluate them by numerical integration?
- The physics information can be obtained from Euclidean Green's functions by inverse Wick's rotation or investigating the tau dependence.

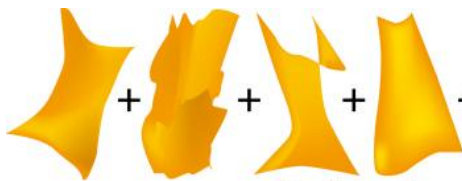
$$\langle \phi_E(\vec{x}, \tau) \phi_E(\vec{0}, 0) \rangle = \frac{1}{Z_E[0]} \frac{\delta^2 Z_E[\eta]}{\delta \eta(\vec{x}, \tau) \delta \eta(\vec{0}, 0)} \Big|_{\eta=0} = \frac{1}{Z_E[0]} \int D\phi_E (\phi_E(\vec{x}, \tau) \phi_E(\vec{0}, 0)) \exp[-S_E[\phi_E]/\hbar]$$

$$\int d\vec{x} \langle \phi_E(\vec{x}, \tau) \phi_E(\vec{0}, 0) \rangle e^{-i\vec{p} \cdot \vec{x}} \xrightarrow{\tau \rightarrow +\infty} C e^{-E(\vec{p})\tau}$$

$E(\vec{p})$: lowest energy in this channel (intermediate state).

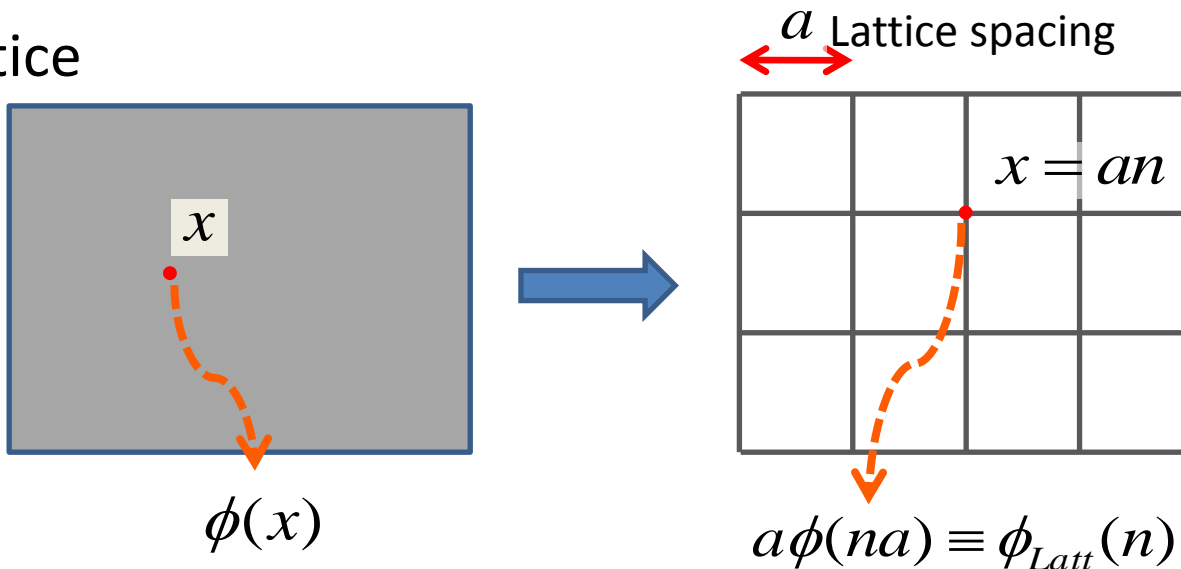
2-3 Euclidean path integral and lattice

- Path integral measure $\int D\phi_E$
 - Integration by field shape (configuration)

$$\int D\phi_E \approx \text{sum over field shape}$$


- Euclidean space time, $x_E = (x, y, z, \tau)$ is continuous. Difficult to maintain $\int D\phi_E$ for numerical evaluation. This will cause UV divergences. The renormalization and regularization is required.
- Introduce the lattice discretization:
 - As a regularization.
 - As a well defined integration measure.
 - Degree of Freedom (DoF) is still finite. IR regulator by limiting system size (finite volume).

- Lattice



- Lattice regularized path integral

$$n = (n_x, n_y, n_z, n_\tau) \in \mathbb{Z}^4$$


$$Z_E[\eta] = \int D\phi_E \exp\left[-\frac{1}{\hbar}(S_E[\phi_E] - \eta \cdot \phi_E)\right] \rightarrow Z_{Latt}[\eta] = \int D\phi_{Latt} \exp\left[-\frac{1}{\hbar}(S_{Latt}[\phi_{Latt}] - \eta \cdot \phi_{Latt})\right]$$

$$\int D\phi_{Latt} \equiv \prod_n \int d\phi_{Latt}(n) = \text{sum over lattice field shape}$$

Multiple integration on the vector $\vec{\phi} = (\dots \phi_{Latt}(n_1), \phi_{Latt}(n_2), \phi_{Latt}(n_3), \dots)^T$

- Lattice regularized path integral

$$Z_{Latt}[\eta] = \int D\phi_{Latt} \exp\left[-\frac{1}{\hbar}(S_{Latt}[\phi_{Latt}] - \eta \cdot \phi_{Latt})\right] \quad n = (n_x, n_y, n_z, n_\tau) \in \mathbb{Z}^4$$



$$Z(\vec{\eta}) = \int d\vec{\phi} \exp\left[-(S(\vec{\phi}) - \vec{\eta} \cdot \vec{\phi})\right]$$

Multiple integration on the vector $\vec{\phi} = (\dots \phi_{Latt}(n_1), \phi_{Latt}(n_2), \phi_{Latt}(n_3), \dots)^T$

- How to evaluate this integral?

- Similar to Canonical partition function in statistical mechanics.
- Dimension of $\vec{\phi}$ is very large. For real scalar on a 4D lattice with the size (16x16x16x16), $\dim(\vec{\phi}) = 16^4 = 65,536$
- If the weight $\exp(\dots)$ is real and non-negative, we can evaluate it using Monte Carlo Methods.
- Note: Lattice action should be designed appropriately. (based on Symmetry, spectrum, relation Minkowski \leftrightarrow Euclid,
- When no real and non-negative weight is derived, we encounter the sign problem in the Monte Carlo method. Ex. System in finite density.

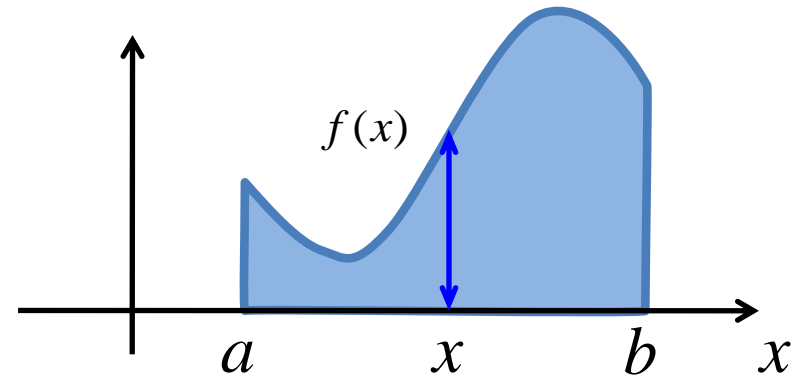
2-4 Integration using Monte Carlo Methods.

- Monte Carlo

- Ex. Integration with a single variable.

$$I = \int_a^b f(x) dx$$

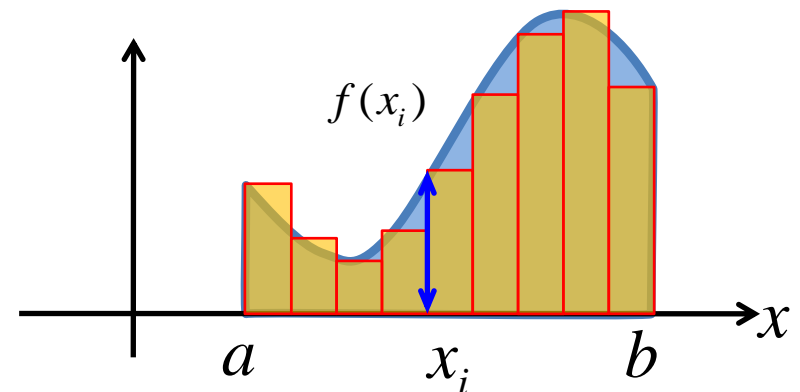
$f(x) \geq 0$, and real valued.



- Rectangular integration

$$I = \lim_{N \rightarrow \infty} f(x_i) \Delta x,$$

$$\Delta x = (b - a) / N$$



• Random sampling

(1) Pick up a number $x_i = x$ from the interval $[a, b]$ **randomly**.

(2) Evaluate function as $f_i = f(x_i)$.

(3) Repeat (1)-(2) N times, then we get samples $\{f_1, f_2, \dots, f_N\}$.

We can estimate the integral as

$$I \approx \frac{b-a}{N} \sum_{i=1}^N f_i$$

The random number sequence $\{x_1, x_2, \dots, x_N\}$ has a uniform distribution in $[a, b]$. This means that the random variable x has the following probability density:

$$P(x) = \begin{cases} \text{Const} & x \in [a, b] \\ 0 & x \notin [a, b] \end{cases}$$

Thus the statistical averaging for $f_i = f(x_i)$ means

$$\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N f_i = \int_{-\infty}^{\infty} f(x) P(x) dx / \int_{-\infty}^{\infty} P(x) dx$$

Denominator is for the probability normalization.

- A defect and inefficient property of the simple rectangular and random sampling integration.
 - If the target function $f(x)$ has a keen peak with narrow width W ,
The integration may fail until

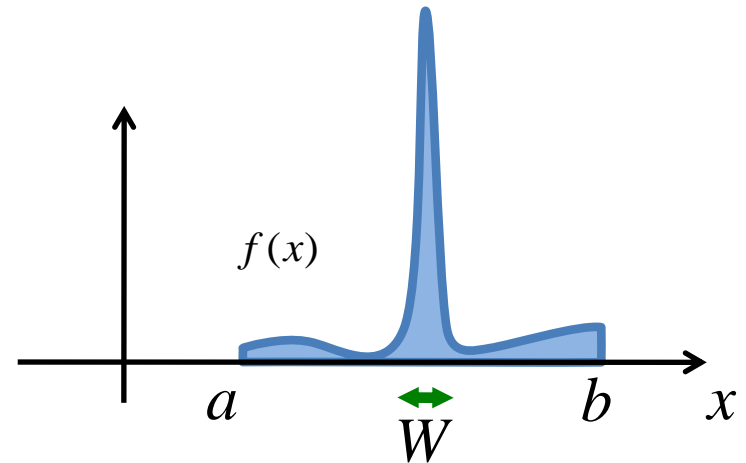
$$(a-b) / N \ll W$$

is satisfied.

One sample in the peak.

Most of samples are unimportant.

sample ratio = $1/N$.



- In multi dimensional integrations, the situation becomes more worse.

- D-dimension
$$I = \iiint \dots \iint f(\vec{x}) d^D \vec{x}$$

$$(a-b)_i / N_i \ll W_i \quad \text{for } i\text{-th direction}$$

$$\text{Total Sample Number} = \prod_{i=1}^D N_i \approx N^D$$

Only one sample is in the peak.

Ratio = $1/N^D \ll 1$.

• Importance Sampling (Monte Carlo)

- As seen before uniform sampling is not effective if the integrand has keen peaks.
- Euclidean Path-integral is a kind of huge-multi dimensional integration.
- The integral has narrow peaks in general, and the highest peak corresponds to the classical solution of the system.

$$\langle \phi_{Latt}(x)\phi_{Latt}(y) \rangle = \frac{1}{Z_{Latt}[0]} \int D\phi_{Latt}(\phi_{Latt}(x)\phi_{Latt}(y)) \exp\left[-\frac{S_{Latt}[\phi_{Latt}]}{\hbar}\right]$$

- In the classical limit ($\hbar \rightarrow 0$), the dominant contribution to the integral comes from:

$$\text{A solution } \phi_{Latt}^* \text{ which gives the highest peak of } \exp\left[-\frac{S_{Latt}[\phi_{Latt}^*]}{\hbar}\right].$$

- This corresponds to the stationary (or minimum) solution of action:

$$S_{Latt}[\phi_{Latt}^* + \Delta] \approx 0 \text{ for any variation } \Delta. \quad \phi_{Latt}^* : \text{classical solution.}$$

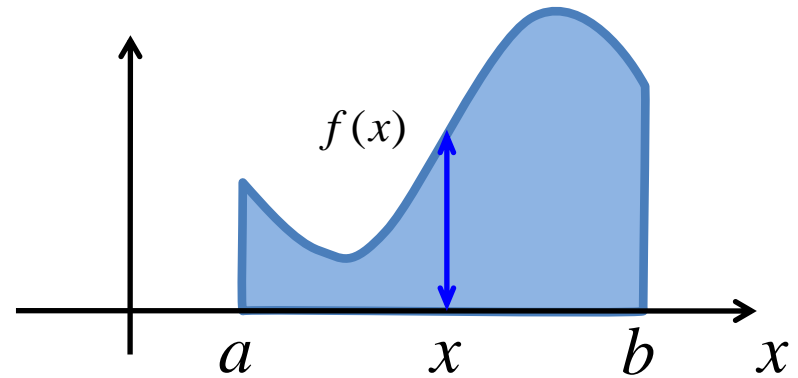
- We know that the classical solution gives a narrow peak for $\exp(-S)$

Uniform sampling for ϕ is not effective to evaluate path integrals.

- Importance Sampling (Monte Carlo) cont'd

$$I = \int_a^b f(x) dx$$

$f(x) \geq 0$, and real valued.



- To integrate this function $f(x)$:

- If we can generate a sequence / ensemble $\{x\}$ so that the statistical histogram/distribution of $\{x\}$ is $w(x)$.

- We have $\{x^{(1)}, x^{(2)}, x^{(3)}, \dots, x^{(N)}\}$

Distribution of $\{x\}$: $w(x)$

$$I = \int_a^b f(x) dx = \int_a^b \frac{f(x)}{w(x)} w(x) dx = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{j=1}^N \frac{f(x^{(j)})}{w(x^{(j)})} = \left\langle \frac{f(x)}{w(x)} \right\rangle : \text{statistical averaging.}$$

- The error behaves as $1/\text{Sqrt}(N)$

$$I = \int_a^b f(x) dx \approx \left\langle \frac{f(x)}{w(x)} \right\rangle \pm \sqrt{\frac{\langle f^2 / w^2 \rangle - \langle f / w \rangle^2}{N}} = \left\langle \frac{f(x)}{w(x)} \right\rangle \pm O(1/\sqrt{N})$$

- The error is minimized when $f(x)=w(x)$.

- The error behaves as $1/\text{Sqrt}(N)$ even for the multi-dimensional integrations.

- Importance sampling for Euclidean path-integrals.

- For the two-point correlation function:

$$\langle \phi_i \phi_j \rangle = \frac{1}{Z(\vec{0})} \int d\vec{\phi}(\phi_i \phi_j) \exp[-S(\vec{\phi})]$$

- Generate a sequence/ensemble: $\{\vec{\phi}^{(1)}, \vec{\phi}^{(2)}, \vec{\phi}^{(3)}, \dots, \vec{\phi}^{(N)}\}$

- So that the sample has the distribution : $w(\vec{\phi}) = C \exp[-S(\vec{\phi})]$

- The two-point correlation function can be estimated as:

$$\langle \phi_i \phi_j \rangle \approx \frac{1}{N} \sum_{k=1}^N \phi_i^{(k)} \phi_j^{(k)}$$

- The error behaves as $1/\text{Sqrt}(N)$.

- Note: the dimension of the integral/ $\vec{\phi}$ is \propto (Lattice sites = 16^4 for ex.)

How to generate such an ensemble ?

• Markov Chain Monte Carlo (MCMC)

(general description)

- A simple random sampling generation is not effective as seen before.
- A non-random generation is required.

– MCMC Set up. There exist

$\vec{\phi}$: random variable

$\{\vec{\phi}^{(1)}, \vec{\phi}^{(2)}, \vec{\phi}^{(3)}, \dots, \vec{\phi}^{(t-1)}\}$: $t-1$ step sequence generated.

– MCMC adds a new sample to the sequence as

Generate $\vec{\phi}^{(t)}$ with a probability distribution $P(\vec{\phi}^{(t)} | \vec{\phi}^{(t-1)})$.

Then add the new sample to the sequence.

$\{\vec{\phi}^{(1)}, \vec{\phi}^{(2)}, \vec{\phi}^{(3)}, \dots, \vec{\phi}^{(t-1)}, \vec{\phi}^{(t)}\}$: t step sequence generated.

Where

$P(\vec{\phi}^{(t)} | \vec{\phi}^{(t-1)})$: Transition probability $\vec{\phi}^{(t-1)} \rightarrow \vec{\phi}^{(t)}$ in MCMC.

- Markov Chain Monte Carlo (MCMC) cont'd
- How to generate the desired distribution from the transition P ?

– **Perron-Frobenius theorem.**

- $P(\phi | \phi')$ transition probability can be treated as a matrix element which index takes a value of state number.

$$\vec{\phi} : \text{state} \rightarrow i : i\text{-th state}, \quad P(\vec{\phi} | \vec{\phi}') \rightarrow P_{ij}$$

: transition probability from j -th state to i -th state.

- The matrix P satisfies

$P_{ij} > 0,$	Real positive Probability.
$\sum_i P_{ij} = 1,$	Probability conservation.
- P is called a positive matrix.

– **Perron-Frobenius theorem:**

- Any positive real matrix has a unique and largest eigenvalue (with =1), and associated eigenvector with positive components.

$$Pw = w, \quad w_i > 0$$

- Markov Chain Monte Carlo (MCMC) cont'd
- Using Perron-Frobenius theorem, we have

- For a given initial state:

$v^{(0)}$: initial distribution.

if the system is in i -th state, $v^{(0)}_i = 1$, and other components are zero.

- k -step MCMC corresponds to

$$v^{(0)} = P v^{(1)}, v^{(1)} = P v^{(2)}, \dots, v^{(k)} = P v^{(k-1)}$$

$$v^{(k)} = P^k v^{(0)}$$

- The Perron-Frobenius theorem says that

$$\lim_{k \rightarrow \infty} v^{(k)} = \lim_{k \rightarrow \infty} P^k v^{(0)} = w, \quad \text{where } \underline{Pw = w}.$$

- The convergence to the fixed distribution is usually exponential. After many MCMC step the distribution is almost identical to the maximum eigen vector w .
- If s has the desired distribution we can generate the desired sequence.

- Markov Chain Monte Carlo (MCMC) cont'd
 - (1) Generate initial state.
 - (2) If the system is in the j -th state, generate i -th state with the probability P_{ij}
 - (3) Add the new state to the ensemble.
 - (4) Goto (2)
- Where we assumed that the state is discrete and countable, P is a positive matrix.
- Extension to Non-negative matrixes, and continuum state is also possible.
- The property that the existence of a unique real maximum eigenvalue and positive eigenvector of the theorem still holds, but some special properties are required on P . Here I omit the details of the extension. (irreducible,...)
- **Now the problem to the path-integral is**

– How to construct $P(\vec{\phi} | \vec{\phi}')$ so that the maximum eigen vector is $w(\vec{\phi}) = C \exp(-S(\vec{\phi}))$?

2-5 Detailed Balance Condition

- How to construct Transition probability $P(\vec{\phi} | \vec{\phi}')$ to make a desired distribution $w(\vec{\phi}) = C \exp(-S(\vec{\phi}))$?
- One sufficient condition is the so called **detailed balance condition**.
 - Recalling that the fixed point distribution is a eigenvector of the transition probability with real unit eigenvalue.

Eigen equation for transition probability matrix P

$$Pw = w \Leftrightarrow \sum_j P_{ij} w_j = w_i \quad \text{for discrete statespace}$$

$$\text{or } \int d\vec{\phi}' P(\vec{\phi} | \vec{\phi}') w(\vec{\phi}') = w(\vec{\phi}) \quad \text{for continuous statespace}$$

- **The detailed balance condition requires**

$$P_{ij} w_j = P_{ji} w_i \quad \text{or} \quad P(\vec{\phi} | \vec{\phi}') w(\vec{\phi}') = P(\vec{\phi}' | \vec{\phi}) w(\vec{\phi})$$

(Problem-1)

This is a sufficient condition for eigenvector w with unit eigenvalue.
In this case, P is a reversible Markov chain (w is a simultaneous left and right evec).

- Some MCMC examples that satisfies the detailed balance condition.
- (1) Metropolis-Hastings algorithm
(Metropolis et al. 1953, Hasitings 1970)

(step 0) Given initial state $j^{(0)}, t = 0$

(setp1) Generate a canditate state i with probability $q_{ij^{(t)}}$.

(step 2) Take next state $j^{(t+1)}$ as

$$j^{(t+1)} = \begin{cases} i & \text{with probablity } \rho_{ij^{(t)}} \\ j^{(t)} & \text{with probablity } 1 - \rho_{ij^{(t)}} \end{cases}$$

(step 3) $t \leftarrow t + 1$, goto step 1.

- Where $\rho_{ij} = \min\left(1, \frac{w_i}{w_j}\right)$ and $q_{ij} = q_{ji}$

- This algorithm is equivalent to the following transition probability

(Problem-2)

$$P_{ij} = \rho_{ij} q_{ij} + (1 - r_j) \delta_{ij},$$

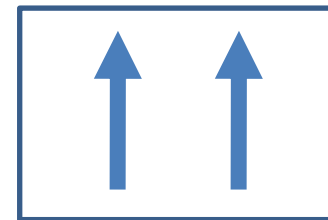
$$\rho_{ij} = \min\left(1, \frac{w_i}{w_j}\right), \quad r_j = \sum_k \rho_{kj} q_{kj}$$

- This transition probability matrix satisfies the detailed balance condition.
- A More concrete example for Metropolis algorithm.
 - Ising model with 2 spins.

$$S(\vec{\sigma}) = \beta \sigma_1 \sigma_2$$

$$Z(\vec{\eta}) = \sum_{\sigma_1=\pm 1, \sigma_2=\pm 1} \exp[-S(\vec{\sigma}) + \vec{\eta} \cdot \vec{\sigma}]$$

$$\sigma_1 = \begin{cases} +1 \\ -1 \end{cases} \quad \sigma_2 = \begin{cases} +1 \\ -1 \end{cases}$$



- Ising model with 2 spins.

$$S(\vec{\sigma}) = \beta\sigma_1\sigma_2 \quad Z(\vec{\eta}) = \sum_{\sigma_1=\pm 1, \sigma_2=\pm 1} \exp[-S(\vec{\sigma}) + \vec{\eta} \cdot \vec{\sigma}]$$

- To compute the spin average and spin correlation

$$\langle \bar{\sigma} \rangle = \frac{1}{Z(\vec{0})} \sum_{\sigma_1=\pm 1, \sigma_2=\pm 1} \frac{\sigma_1 + \sigma_2}{2} \exp[-S(\vec{\sigma})] = 0$$

$$\langle \sigma_1\sigma_2 \rangle = \frac{1}{Z(\vec{0})} \sum_{\sigma_1=\pm 1, \sigma_2=\pm 1} \sigma_1\sigma_2 \exp[-S(\vec{\sigma})] = -\tanh(\beta)$$

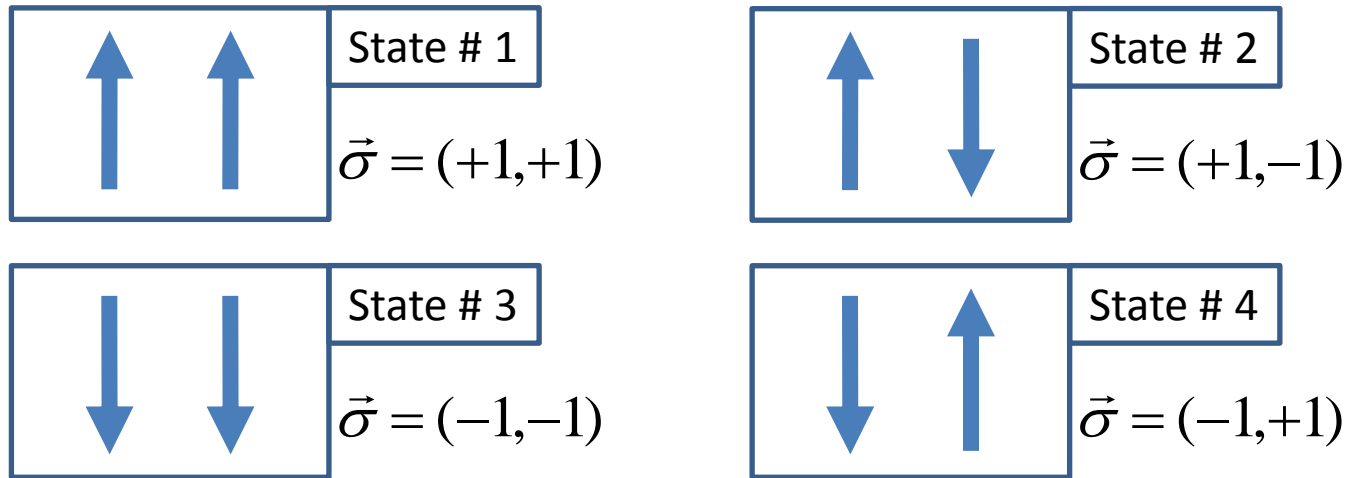
- We generate the ensemble $\{\vec{\sigma}^{(0)}, \vec{\sigma}^{(1)}, \vec{\sigma}^{(2)}, \dots, \vec{\sigma}^{(N)}\}$ with the distribution

$$w(\vec{\sigma}) = \frac{1}{Z(\vec{0})} \exp[-S(\vec{\sigma})]$$

- Then we can estimate the squared spin average by

$$\langle \bar{\sigma} \rangle \approx \frac{1}{N} \sum_{j=1}^N \frac{\sigma_1^{(j)} + \sigma_2^{(j)}}{2}, \quad \langle \sigma_1\sigma_2 \rangle \approx \frac{1}{N} \sum_{j=1}^N \sigma_1^{(j)} \sigma_2^{(j)}$$

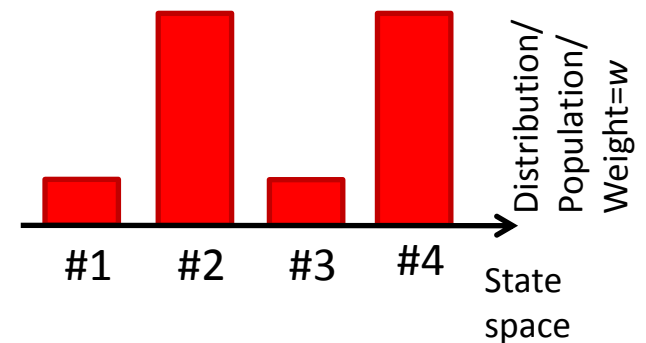
- We have only 4 states.



- The weight(probability) is calculable (C is the normalization const = $Z(0)$)

$$w(\#1) = C \exp[-\beta], \quad w(\#2) = C \exp[+\beta]$$

$$w(\#3) = C \exp[-\beta], \quad w(\#4) = C \exp[+\beta]$$



- We can generate this distribution with the Metropolis Algorithm

- Metropolis algorithm for the Ising model with 2-spins.

(step 0) Randomly choose initial state $\vec{\sigma}^{(t)}, t = 0$

(step 1) Generate a candidate state \vec{s} with probability $q_{ij^{(t)}} = 1/4$

(step 2) Compute the weight $\rho = \min(1, \exp[-S(\vec{s}) + S(\vec{\sigma}^{(t)})])$

(Step 3) Generate a random real number U from $[0,1)$.

(step 4) Take next state $\vec{\sigma}^{(t+1)}$ as

$$\vec{\sigma}^{(t+1)} = \begin{cases} \vec{s} & \text{when } U \leq \rho \text{ (Accept)} \\ \vec{\sigma}^{(t)} & \text{otherwise (Reject)} \end{cases}$$

(step 5) $t \leftarrow t + 1$, goto step 1 for desired sample numbers.

- Then we obtain ensemble:

$$\{\vec{\sigma}^{(0)}, \vec{\sigma}^{(1)}, \vec{\sigma}^{(2)}, \dots, \vec{\sigma}^{(N)}\}$$

Metropolis test
Metropolis accept/reject step

- Corresponding Fortran Program:

– <http://theo.phys.sci.hiroshima-u.ac.jp/~ishikawa/ASLFT2010/2SiteIsingMetropolis.tar.gz>

```

use ising_module
implicit none
integer :: N THERM      ! first N THERM samples are dropped
integer :: NSAMPLE      ! measured sample number
integer, allocatable :: seed(:)
integer :: iseed,rand_size

integer :: s0(2) ! previous state (2-spins)
integer :: s1(2) ! current state (2-spins)
integer :: j0    ! previous state index
integer :: j1    ! current state index
integer :: istep
real(DP) :: rand_num
real(DP) :: beta
real(DP) :: rho,w0,w1,h0,h1
real(DP) :: spinave,spincorr
integer :: iout

iout=99
open(iout,file="ISING_PARAM",status='old',form='formatted')
read(iout,*)beta
read(iout,*)iseed
read(iout,*)N THERM,NSAMPLE
close(iout)

!
! Set up pseudo-random number generator
!
call RANDOM_SEED(size=rand_size)
allocate(seed(rand_size))
seed(:) = iseed
call RANDOM_SEED(put=seed)

write(*,'("# BETA=",ES24.15)') beta

write(*,'("# ISEED=",I10," N THERM=",I10," NSAMPLE=",I10)') &
&      iseed,N THERM,NSAMPLE

write(*,'("# sample#  state index  spin state",&
&      10X,"spin ave",14X,"spin corr"')

!
! Generate initial state at random
!
call RANDOM_NUMBER(rand_num)
j0 = get_state_index(rand_num)
call set_state(s0,j0)

do istep=1,N THERM+NSAMPLE

```

Candidate generation

```

!
! Generate candidate state at random
!
call RANDOM_NUMBER(rand_num)

```

```

j1 = get_state_index(rand_num)
call set_state(s1,j1)

```

```

!
! Compute Metropolis test weight
!
h0 = hamil(beta,s0)
h1 = hamil(beta,s1)
w0 = exp(-h0)
w1 = exp(-h1)
rho = MIN(1.0_DP,w1/w0)

!
! Metropolis test Accept Reject step
!
call RANDOM_NUMBER(rand_num)
if (rand_num <= rho) then

! accept s1 as the new state

continue

else

! reject s1. s0 is the new state

s1(:) = s0(:)
j1    = j0

endif

```

Metropolis test

```

if (istep > N THERM) then
!
! store current state in the ensemble
! and measure observables
!

spinave = (s1(1) + s1(2))*0.5_DP
spincorr = s1(1)*s1(2)

write(*,'(I10,I10,SP,6X,"(",I2,",",I2,")",2ES24.15)') &
&      istep,j1,s1(1),s1(2), spinave, spincorr

endif

!
! shift history
!
s0(:) = s1(:)
j0    = j1

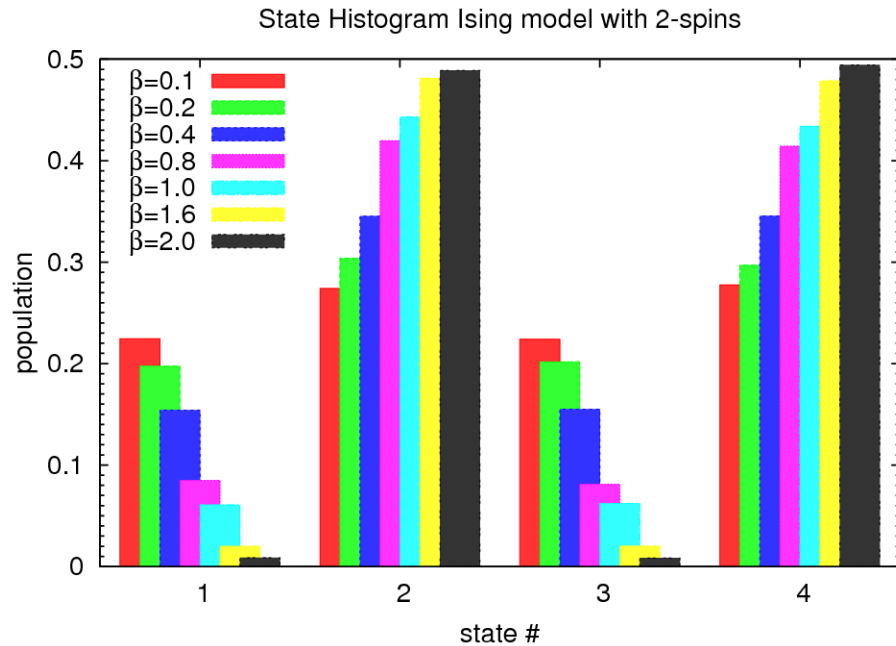
enddo

deallocate(seed)
stop
end program

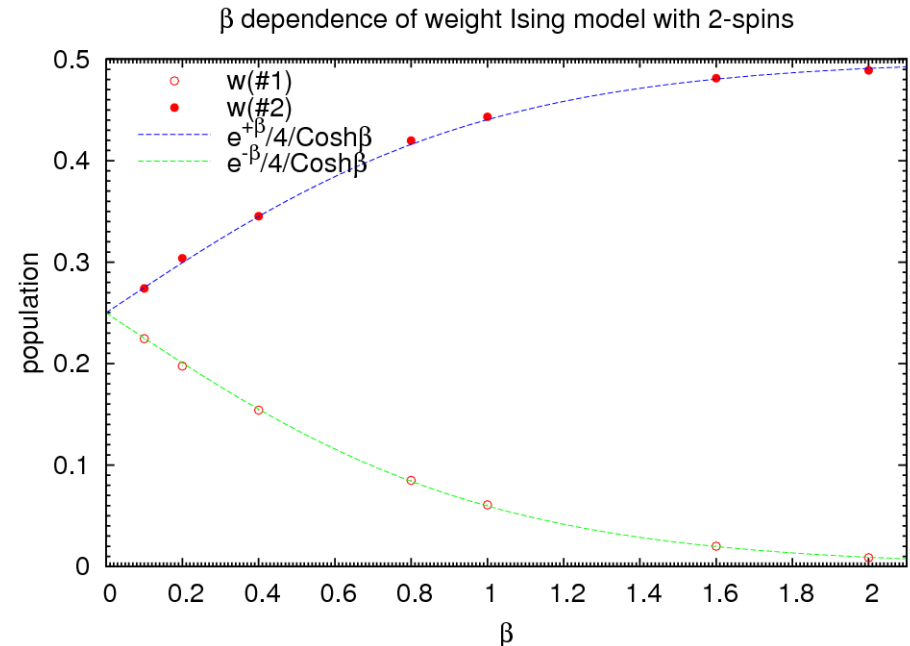
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• Results

– Weight histogram



– Beta dependence of Weight



$$Z = \exp[-\beta] + \exp[+\beta] + \exp[-\beta] + \exp[+\beta] = 4\text{Cosh}(\beta)$$

$$w(\#1) = \exp[-\beta] / 4 / \text{Cosh}(\beta)$$

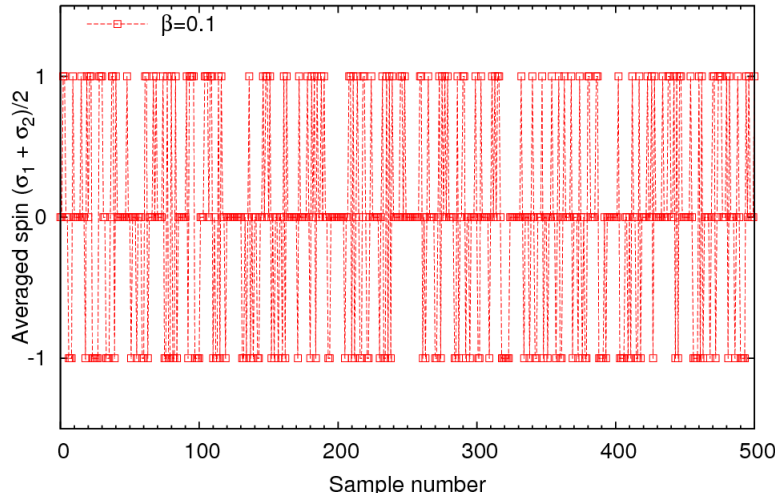
$$w(\#2) = \exp[+\beta] / 4 / \text{Cosh}(\beta)$$

• Results

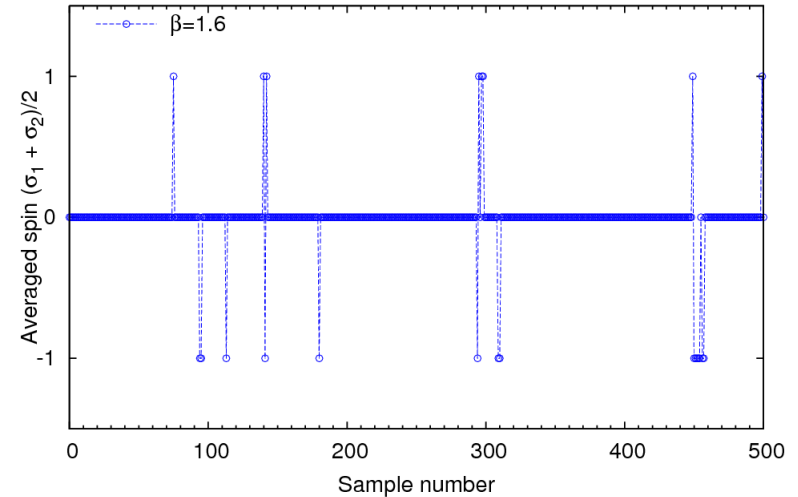
– Spin average ensemble history

$$\frac{\sigma_1^{(j)} + \sigma_2^{(j)}}{2}$$

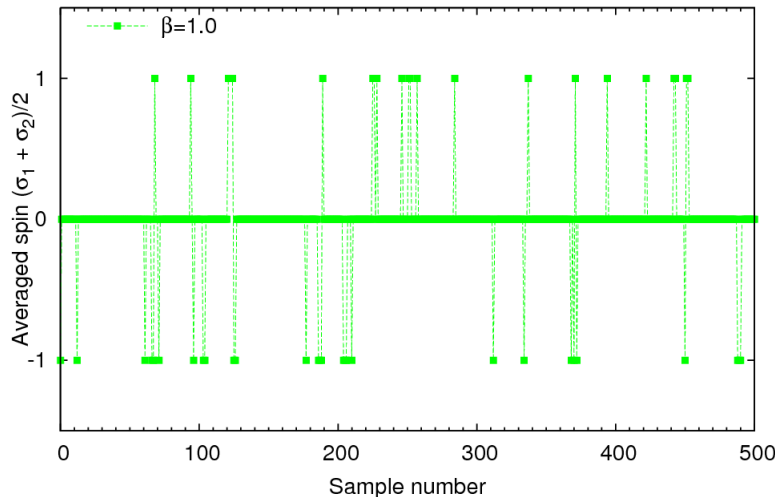
Spin average sample history (Ising model with 2-spins)



Spin average sample history (Ising model with 2-spins)



Spin average sample history (Ising model with 2-spins)

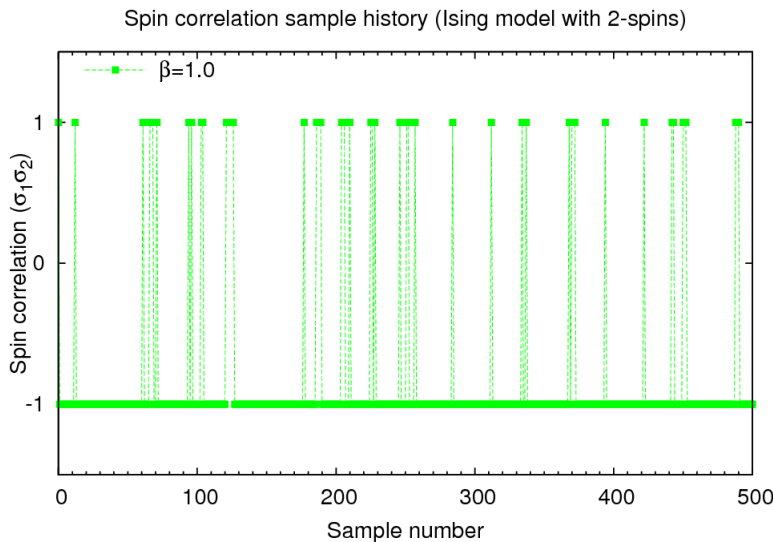
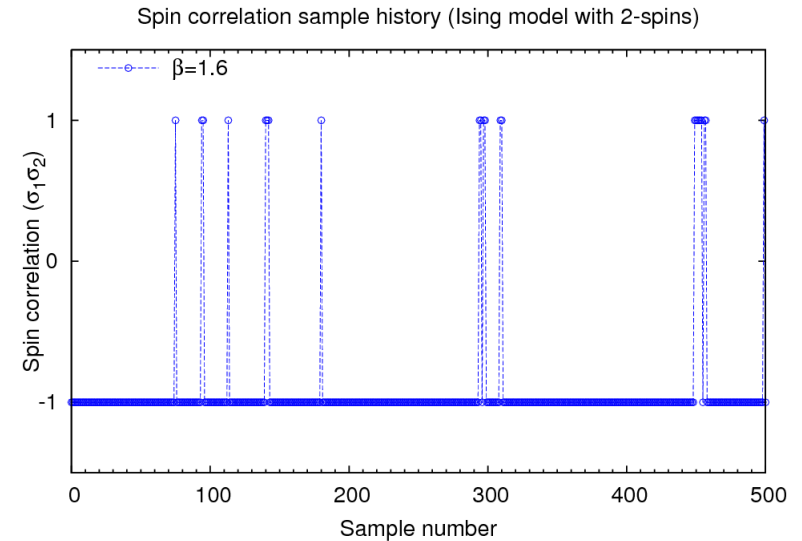
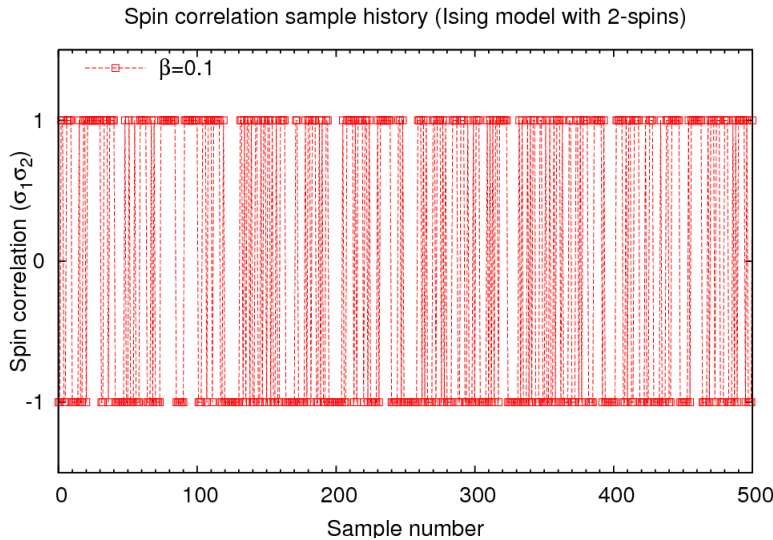


- First 500 samples are plotted.
- Random walking in the state space (4states)
- Spin average can take one of the values (-1,0,1)
- (spin average)=0 can occur for state #2 and #4.
- (spin average)=+1 occurs for state #1.
- (spin average)=-1 occurs for state #3.
- As increasing beta, the state stays at state #2 or #4. spin average = 0 states.

Results

– Spin correlation ensemble history

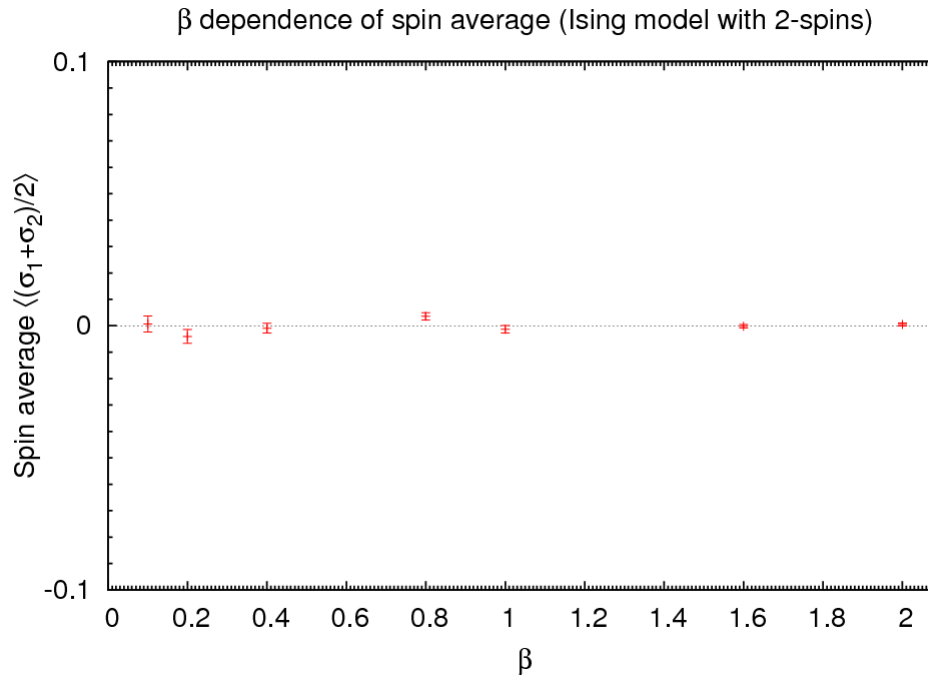
$$\sigma_1^{(j)} \sigma_2^{(j)}$$



- First 500 samples are plotted.
- Random walking in the state space (4states)
- Spin corr. can take +1 or -1.
- (spin corr.)=+1 can occur for state #1 and #3.
- (spin corr.)= -1 occurs for state #2 and #4.
- At small beta population of +1 and -1 is almost same.
- As increasing beta, state with (spin corr.)=-1 dominates. (state #2 and #4)

• Results

– Spin average expectation value

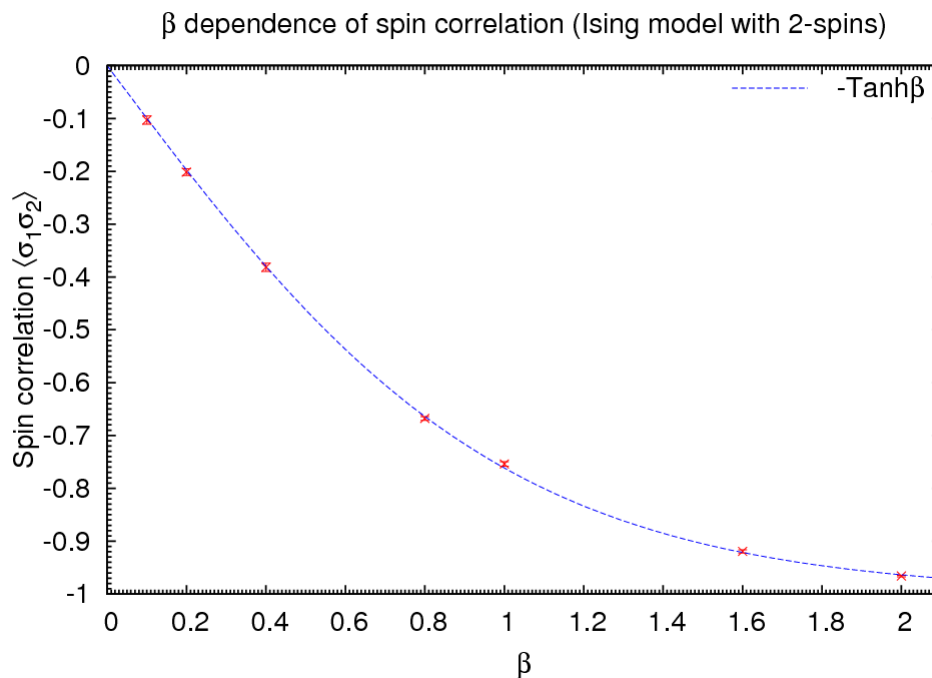


Averaging the history data we obtain zero. This is consistent with the theoretical one.

$$\langle \bar{\sigma} \rangle \approx \frac{1}{N} \sum_{j=1}^N \frac{\sigma_1^{(j)} + \sigma_2^{(j)}}{2} \approx 0$$

• Results

– Spin correlation expectation value



Averaging the history data we obtain $-\text{Tanh}(\text{Beta})$. This is consistent with the theoretical one.

$$\langle \sigma_1 \sigma_2 \rangle = \frac{+e^\beta - e^{-\beta} + e^\beta - e^{-\beta}}{4\text{Cosh}\beta} = -\text{Tanh}\beta \approx \frac{1}{N} \sum_{j=1}^N \sigma_1^{(j)} \sigma_2^{(j)}$$

• Difficulties in (Naive) Metropolis Algorithm

- As seen before the new candidate state(configuration) is really added when the Metropolis test accept.
- In Statistical Mechanics (Canonical ensemble), the exponent of the weight is the energy of the target system.
- The acceptance ratio is governed by the Energy difference

$$\Delta S = S([\text{Candidate State}]) - S([\text{Previous State}])$$

$$\begin{aligned}\rho &= \min(1, \exp[-S([\text{Candidate State}]) + S([\text{Previous State}])]) \\ &= \min(1, \exp[-\Delta S])\end{aligned}$$

- When ΔS is negative, Metropolis test always accept the candidate ($\rho = 1$).
- When ΔS is positive, the acceptance probability decreases as $\rho = \exp(-\Delta S) < 1$.
- When the target system has a huge number of d.o.f., the random sampling method to generate the candidate state almost always large positive number for ΔS . This is typical in statistical mechanics and huge multiple dimension integration.
- Candidate generation method with small energy difference is important.
- See also 2D-Ising model. (Heat-bath (Gibbs sampler) algorithm)

- Most of MCMC algorithms make use of the Metropolis algorithm and its extension.
 - For LQCD, the system has continuous variables (states).
 - Naïve Metropolis algorithm may fail due to the large energy difference.
- (2) Hybrid Monte Carlo (HMC) algorithm
(Scalatar, Scalapino, Sugar, PRB34(1986); Duane, Kennedy Pendleton, Roweth, PL195B(1987))
 - This algorithm is useful when the variables are continuous.
 - This is an extension of the Metropolis algorithm with better candidate generation.
 - The HMC algorithm is a de fact standard algorithm for LQCD with dynamical quarks.
 - In the next lecture I will describe the details of the HMC algorithm.

Problems

- (1) Check that the detailed balance condition is a sufficient condition of the eigenvector (stationary distribution) of the transition matrix. [page 22]
- (2) Check that the transition matrix for the Metropolis algorithm satisfies the detailed balance condition. [page 24].
- (3) Complete the transition matrix for the Ising model with 2-spins in a 4x4 matrix form and Check the eigenvector. [page 24-33]

$$P = \begin{pmatrix} P_{11} & P_{12} & P_{13} & P_{14} \\ P_{21} & P_{22} & P_{23} & P_{24} \\ P_{31} & P_{32} & P_{33} & P_{34} \\ P_{41} & P_{42} & P_{34} & P_{44} \end{pmatrix}$$

- (4) Get and compile the Ising model with 2-spins program. Check the result numerically. [page 24-33] (this needs gfortran and gnuplot on Linux)
- (5) Evaluate the averaged acceptance rate of the Metropolis test when the energy difference is a random variable from the Gaussian distribution with mean= μ and variance= $\sigma^2 = 2\mu$. [Hint: Complementary error function]

$$p(\Delta S) = \frac{1}{\sqrt{4\pi\mu}} \exp\left(-\frac{(\Delta S - \mu)^2}{4\mu}\right)$$

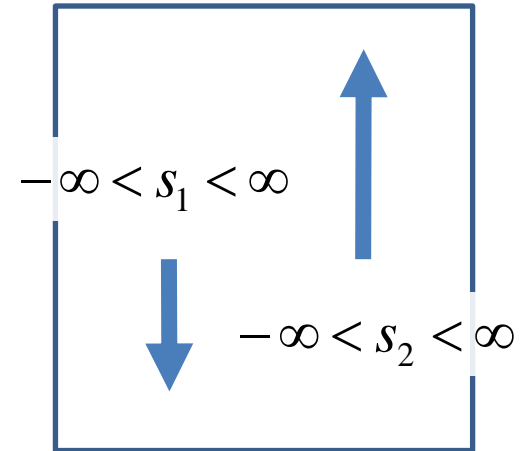
- (6) [Advanced] Consider a N-sites 1D Ising model with periodic boundary condition.

Backup (2-site Scalar model)

- For a continuous state model. I show the 2-site scalar model. (a toy model for lattice scalar field theories)

$$\beta < 1$$

$$Z(\vec{\eta}) = \int_{-\infty}^{\infty} d\vec{s} \exp \left[- \left(\beta s_1 s_2 + \frac{s_1^2 + s_2^2}{2} \right) + \vec{\eta} \cdot \vec{s} \right]$$



$$\left\langle \frac{s_1 + s_2}{2} \right\rangle = \frac{1}{Z(\vec{0})} \int_{-\infty}^{\infty} d\vec{s} \frac{s_1 + s_2}{2} \exp \left[- \left(\beta s_1 s_2 + \frac{s_1^2 + s_2^2}{2} \right) \right] = 0$$

$$\langle s_1 s_2 \rangle = \frac{1}{Z(\vec{0})} \int_{-\infty}^{\infty} d\vec{s} (s_1 s_2) \exp \left[- \left(\beta s_1 s_2 + \frac{s_1^2 + s_2^2}{2} \right) \right] = -\frac{\beta}{1 - \beta^2}$$

• Metropolis algorithm

(step 0) initial state $\vec{s}^{(t)}, t = 0$ from Gaussian Distribution $N[0, \text{var}]$

(step 1) Generate a candidate state \vec{s} from Gaussian Distribution $N[\vec{s}^{(t)}, \text{var}]$

$$\text{This corresponds to } q(\vec{s} | \vec{s}^{(t)}) = \frac{1}{2\pi \text{var}} \exp\left[-\frac{(\vec{s} - \vec{s}^{(t)})^2}{2 \text{var}}\right].$$

(step 2) Compute the weight $\rho = \min(1, \exp[-S(\vec{s}) + S(\vec{s}^{(t)})])$

(Step 3) Generate a random real number U from $[0,1)$.

(step 4) Take next state $\vec{s}^{(t+1)}$ as

$$\vec{s}^{(t+1)} = \begin{cases} \vec{s} & \text{when } U \leq \rho \text{ (Accept)} \\ \vec{s}^{(t)} & \text{otherwise (Reject)} \end{cases}$$

(step 5) $t \leftarrow t + 1$, goto step 1 for desired sample numbers.

- We do not have a finite distribution at $\beta=1$ with this model.
- We can not use uniform sampling for candidate generation because $-\infty < \vec{s} < \infty$.

- Fortran program:

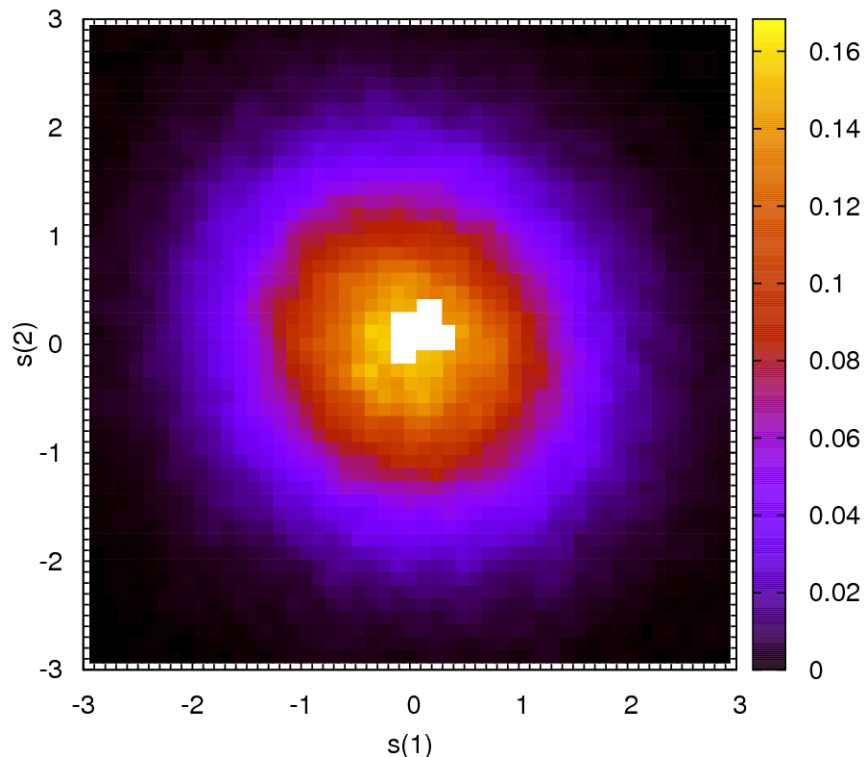
[<http://theo.phys.sci.hiroshima-u.ac.jp/~ishikawa/ASLFT2010/2SiteScalarMetropolis.tar.gz>]

- 10,000,000 samples are generated. But we save 10,000 samples with interval 100. We use $\text{var}=1$ for candidate generation.

- State weight/histogram generated via Metropolis algorithm

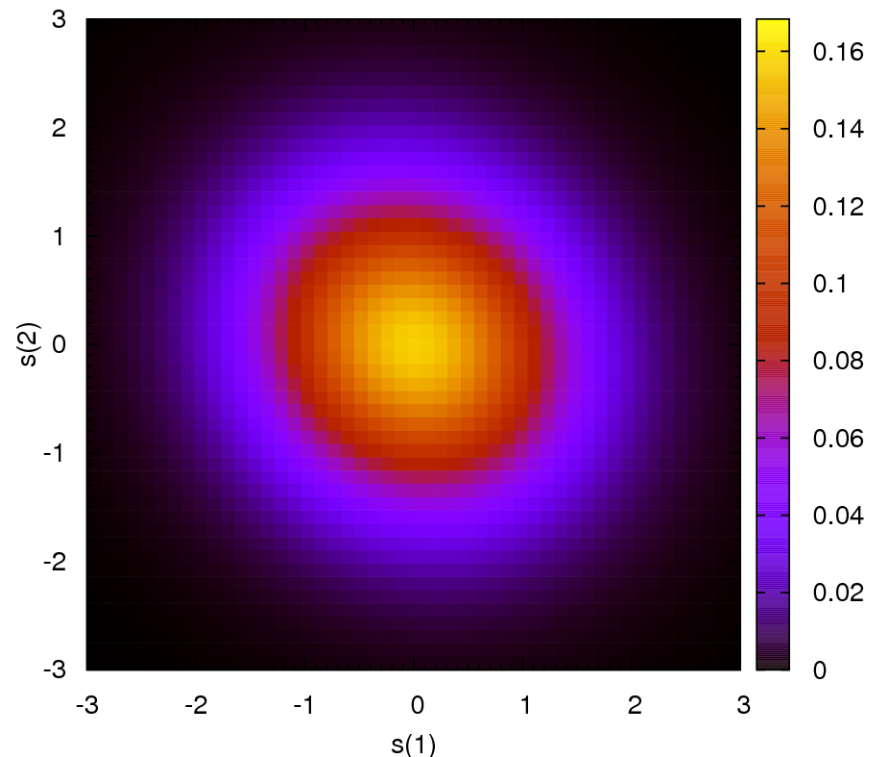
Measured

State Histogram 2-site scalar model ($\beta=0.1$)

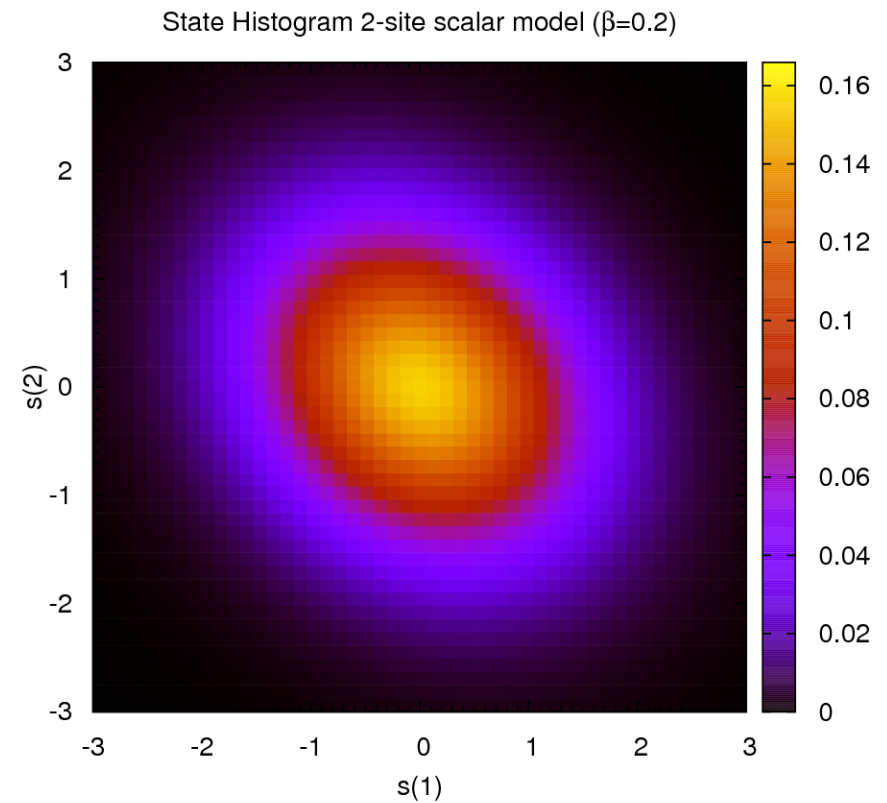
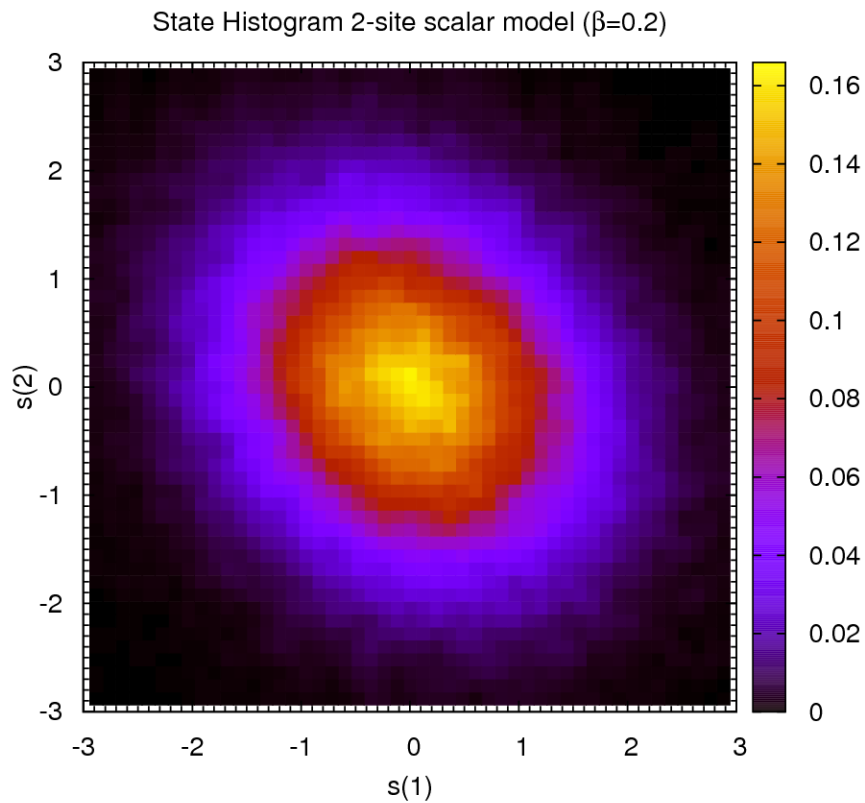


Theoretical

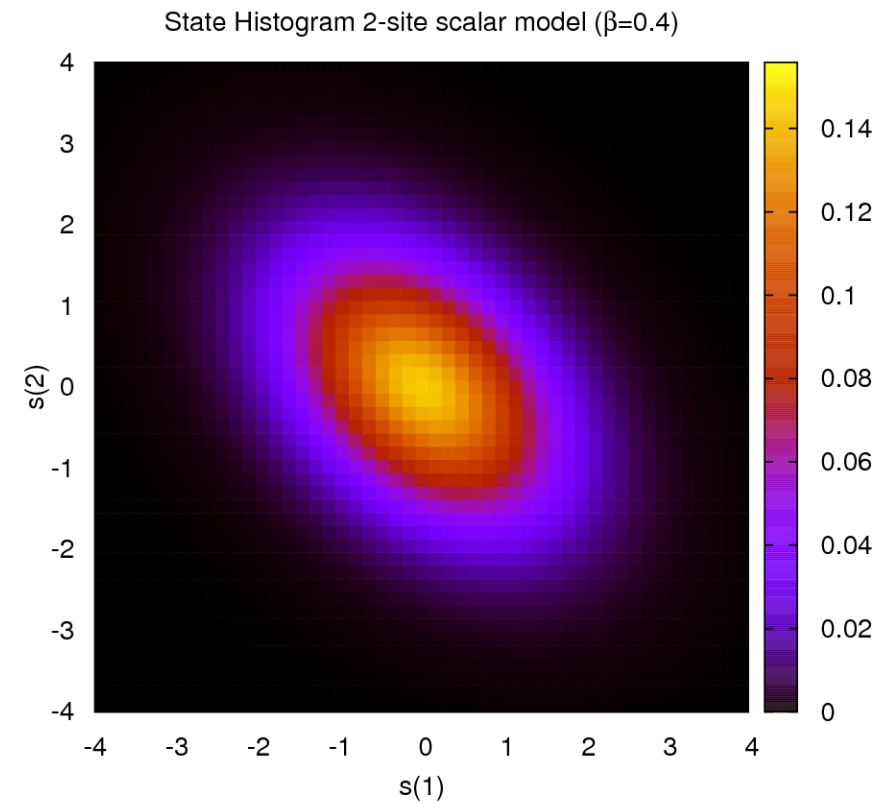
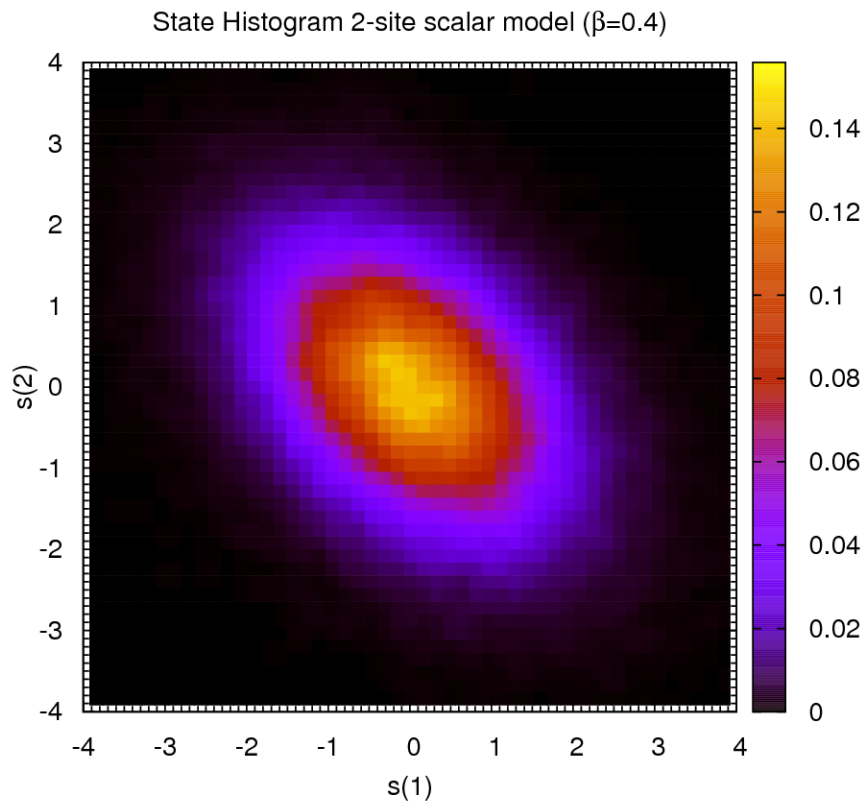
State Histogram 2-site scalar model ($\beta=0.1$)



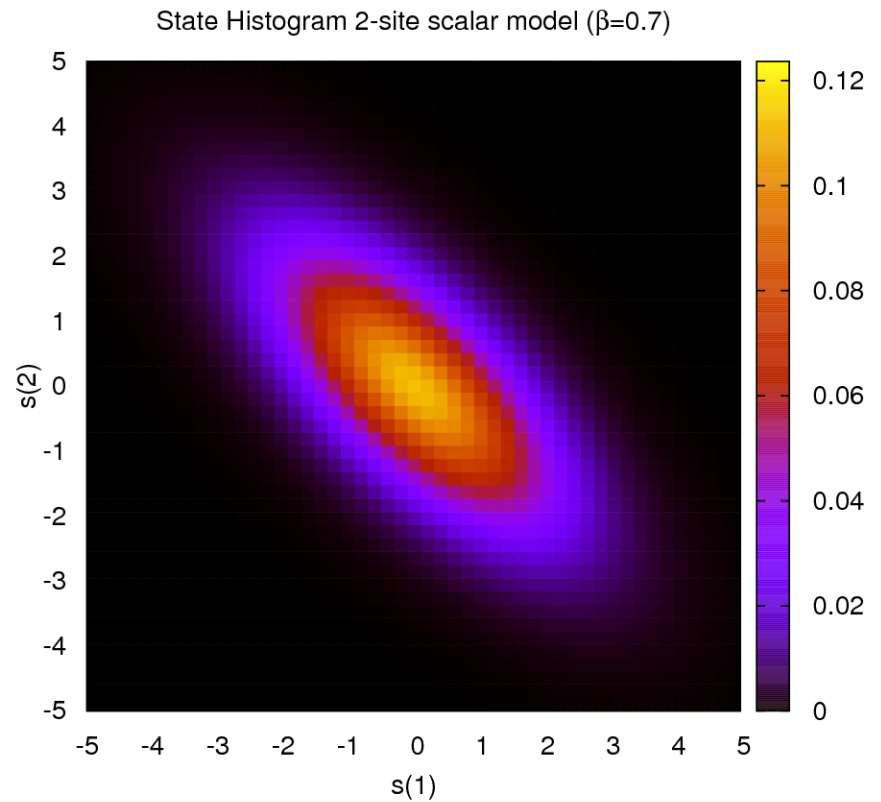
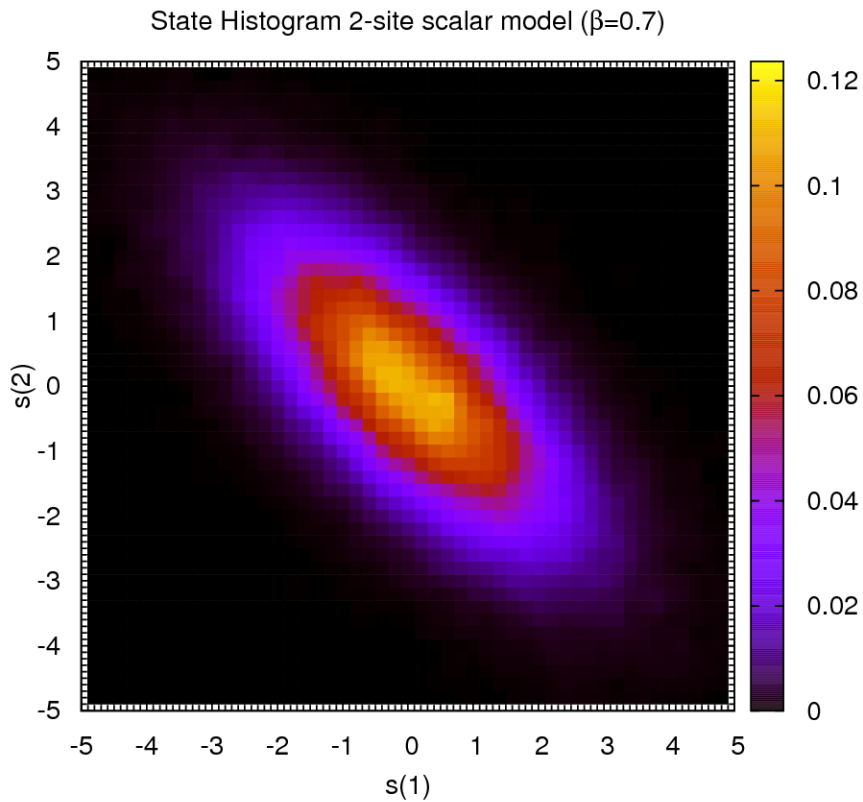
- State weight/histogram generated via Metropolis algorithm



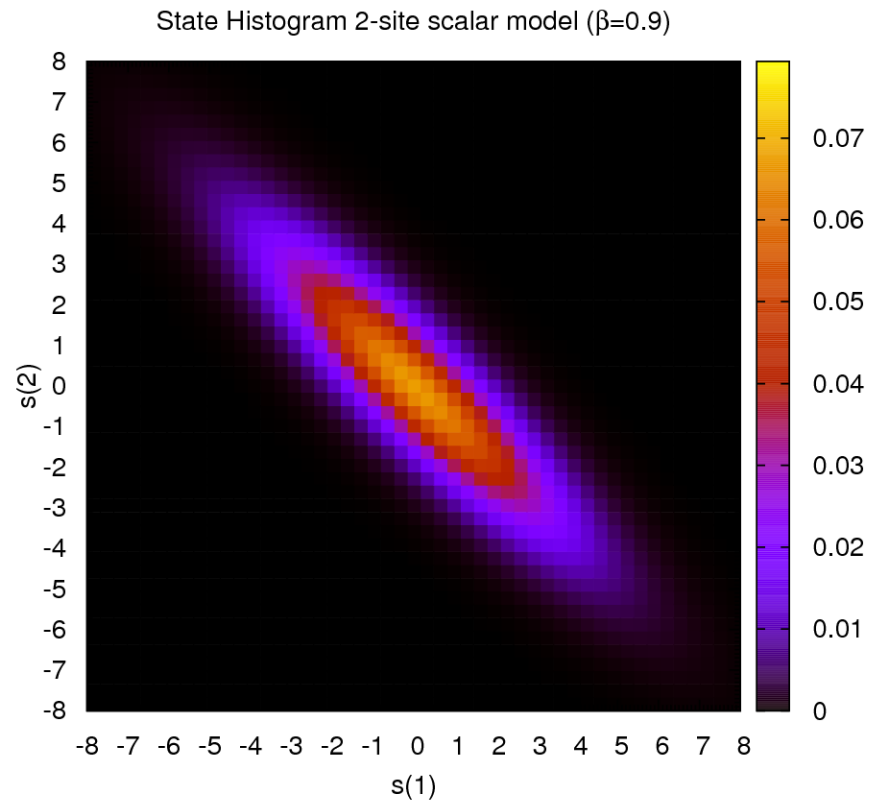
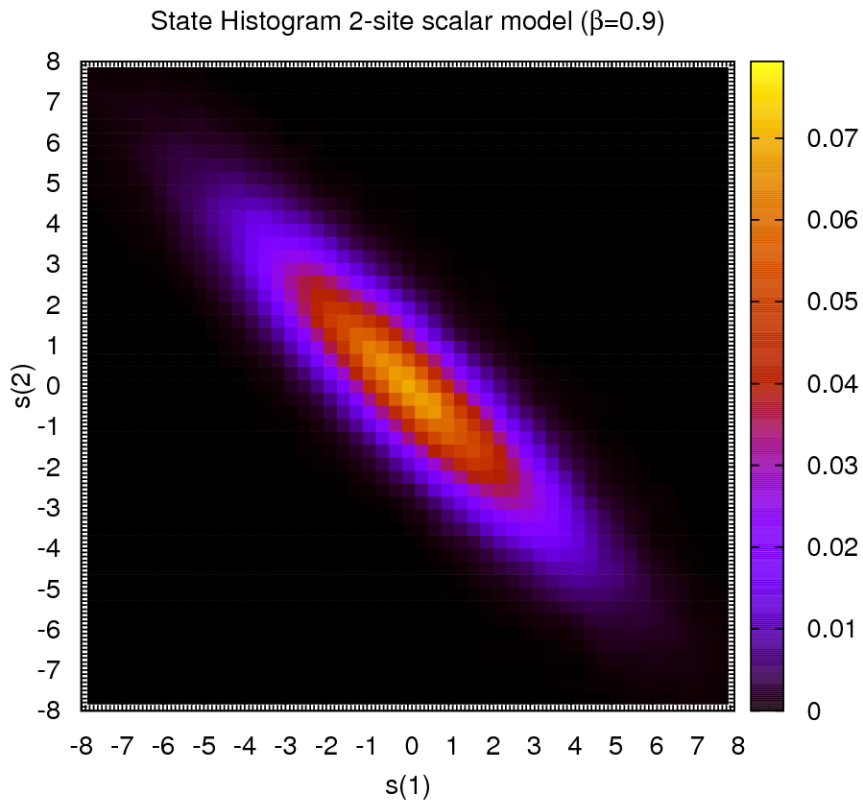
- State weight/histogram generated via Metropolis algorithm



- State weight/histogram generated via Metropolis algorithm



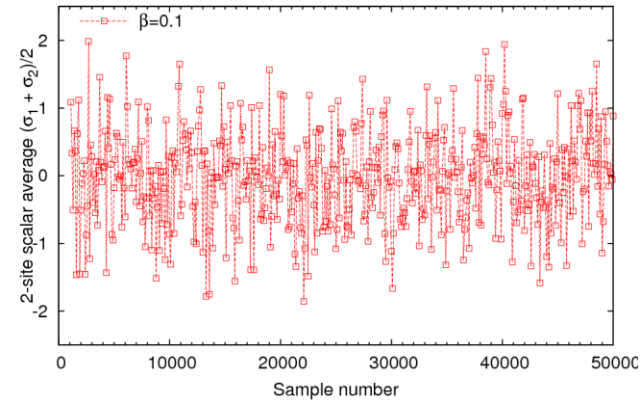
- State weight/histogram generated via Metropolis algorithm



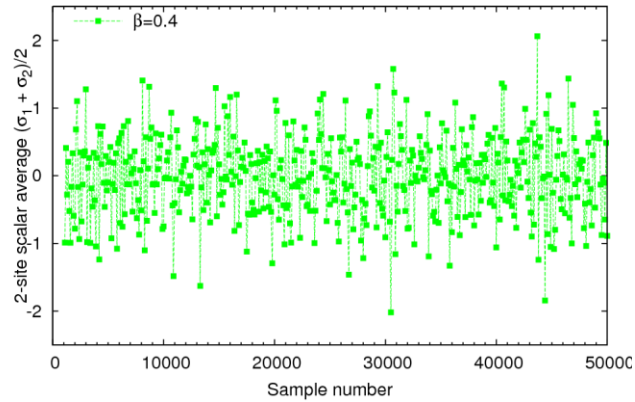
- Spin average and Spin correlation history generated via Metropolis algorithm

Spin average

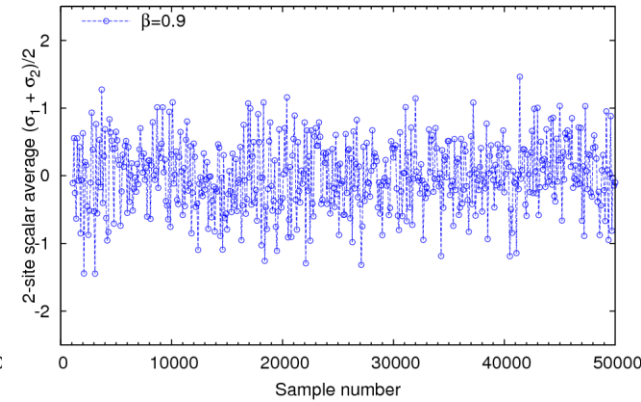
2-site scalar average sample history (2-site scalar model)



2-site scalar average sample history (2-site scalar model)

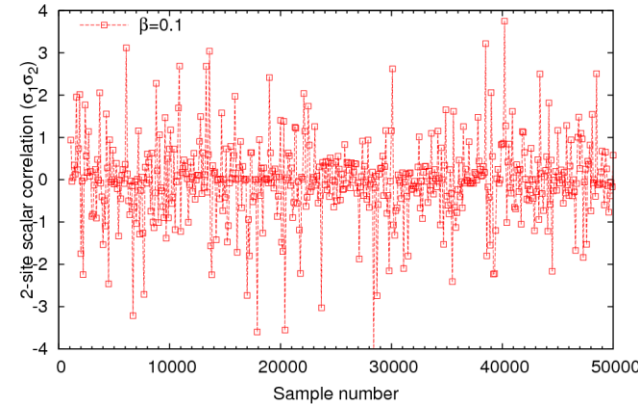


2-site scalar average sample history (2-site scalar model)

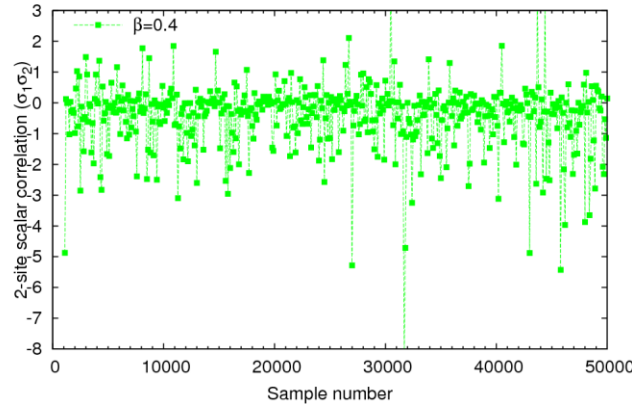


Spin correlation

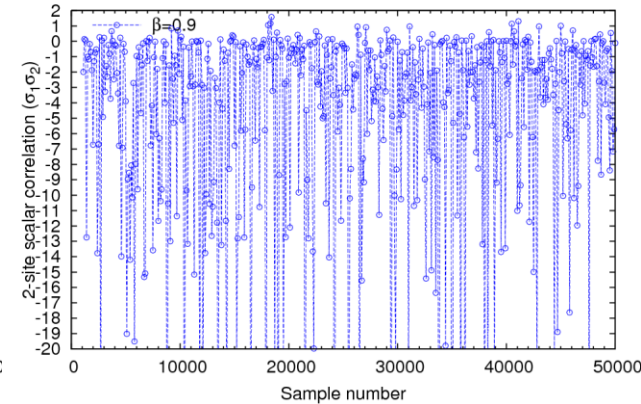
2-site scalar correlation sample history (2-site scalar model)



2-site scalar correlation sample history (2-site scalar model)

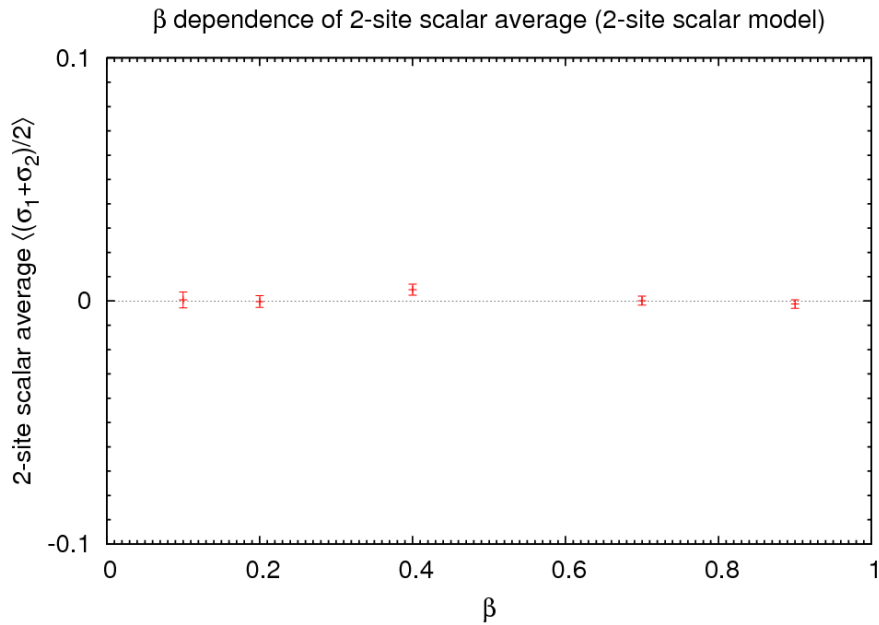


2-site scalar correlation sample history (2-site scalar model)

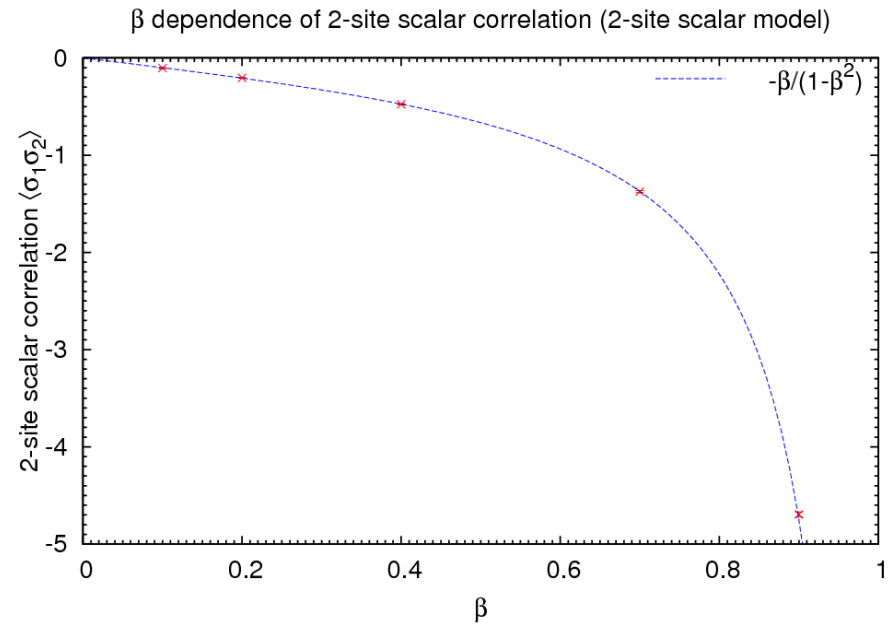


- Beta dependence of Spin average and Spin corr.

Spin average



Spin correlation



All programs are NO WARRANTY.

- Metropolis algorithm transition probability for $\vec{s}' \rightarrow \vec{s}$

$$P(\vec{s} | \vec{s}') = \rho(\vec{s}, \vec{s}')q(\vec{s} | \vec{s}') + (1 - r(\vec{s}'))\delta(\vec{s} - \vec{s}')$$

$$\rho(\vec{s}, \vec{s}') = \min(1, \exp[-S(\vec{s}) + S(\vec{s}')]), q(\vec{s} | \vec{s}') = \frac{1}{2\pi \text{var}} \exp\left[-\frac{(\vec{s} - \vec{s}')^2}{2 \text{var}}\right]$$

$$r(\vec{s}') = \int_{-\infty}^{\infty} d\vec{s} \rho(\vec{s}, \vec{s}')q(\vec{s} | \vec{s}')$$

$\delta(\vec{s}) =$ Delta function

Problem answers

- (1)
$$\sum_j P_{ij} w_j = \sum_j P_{ji} w_i \rightarrow \sum_j P_{ij} w_j = w_i \sum_j P_{ji}$$

$$\rightarrow \sum_j P_{ij} w_j = w_i \quad \text{because} \quad \sum_j P_{ji} = 1$$

- (2)

$$\rho_{ij} = \min\left(1, \frac{w_i}{w_j}\right)$$

and $q_{ij} = q_{ji}$

$$f_{ij} \equiv \log\left(\frac{w_i}{w_j}\right) \rightarrow \rho_{ij} = \min\left(1, \frac{w_i}{w_j}\right) = \Theta(f_{ij}) + \Theta(-f_{ij}) \frac{w_i}{w_j}$$

$$\rightarrow f_{ij} = -f_{ji}$$

$$\begin{aligned} \rho_{ij} w_j &= \left(\Theta(f_{ij}) + \Theta(-f_{ij}) \frac{w_i}{w_j} \right) w_j = w_j \Theta(f_{ij}) + \Theta(-f_{ij}) w_i \\ &= \left(\frac{w_j}{w_i} \Theta(f_{ij}) + \Theta(-f_{ij}) \right) w_i = \left(\frac{w_j}{w_i} \Theta(-f_{ji}) + \Theta(f_{ji}) \right) w_i \\ &= \rho_{ji} w_i \end{aligned}$$

- Similarly $P_{ij} w_j = P_{ji} w_i$

- (3) I show $\beta > 0$ case only.

$$P = \frac{1}{4} \begin{pmatrix} 1 & y & 1 & y \\ 1 & 3-2y & 1 & 1 \\ 1 & y & 1 & y \\ 1 & 1 & 1 & 3-2y \end{pmatrix} \quad \text{with } y = e^{-2\beta} \quad (\text{for } \beta > 0)$$

- Eigenpairs

$$w_{\lambda=1} = \begin{pmatrix} y \\ 1 \\ y \\ 1 \end{pmatrix} \frac{1}{2(2+y)}, \quad \text{with } \lambda = 1.$$

Desired distribution

$$w_{\lambda_2} = \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \quad \text{with } \lambda_2 = \frac{1-y}{2} < 1.$$

$$w_{\lambda_3} = \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix}, \quad \text{with } \lambda_3 = 0$$

- Thus MCMC converges to the desired distribution.

$$\lim_{N \rightarrow \infty} P^N \nu = w_{\lambda=1}$$

The convergence rate is governed by the difference between 1 and next largest eigenvalue.

- (5)
- (complementary) error functions:

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt \quad \text{error function.}$$

$$\operatorname{erfc}(x) = 1 - \operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_x^\infty e^{-t^2} dt \quad \text{complementary error function.}$$

- Averaging acceptance probability:

$$\langle P_{acc} \rangle = \int_{-\infty}^{\infty} \min(1, e^{-\Delta S}) \frac{1}{\sqrt{4\pi\mu}} e^{-\frac{(\Delta S - \mu)^2}{4\mu}} = \operatorname{erfc}\left(\frac{\sqrt{\Delta S}}{2}\right)$$

History

- 2013/01/31: Metropolis test probability is corrected.

$$\rho_{ij} = \min\left(1, \frac{w_j}{w_i}\right)$$

and $q_{ij} = q_{ji}$

Wrong

$$\rho_{ij} = \min\left(1, \frac{w_i}{w_j}\right)$$

and $q_{ij} = q_{ji}$

Right